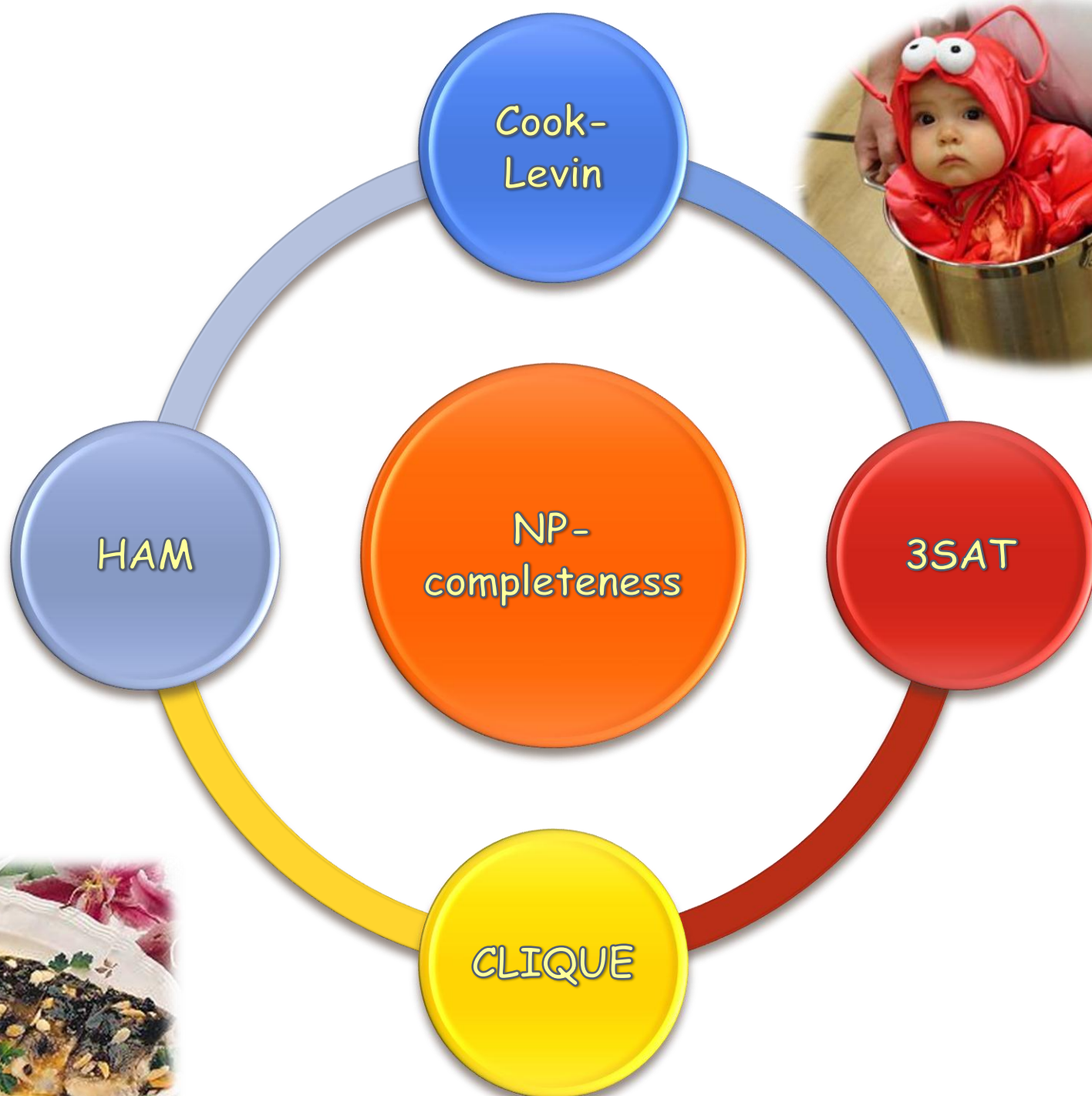




## Reductions

Or

- How to link between problems' complexity, while not knowing what they are



**להתראות  
בקרוב**

# Goal:

- Formalize the notion of "reductions"

# Plan:

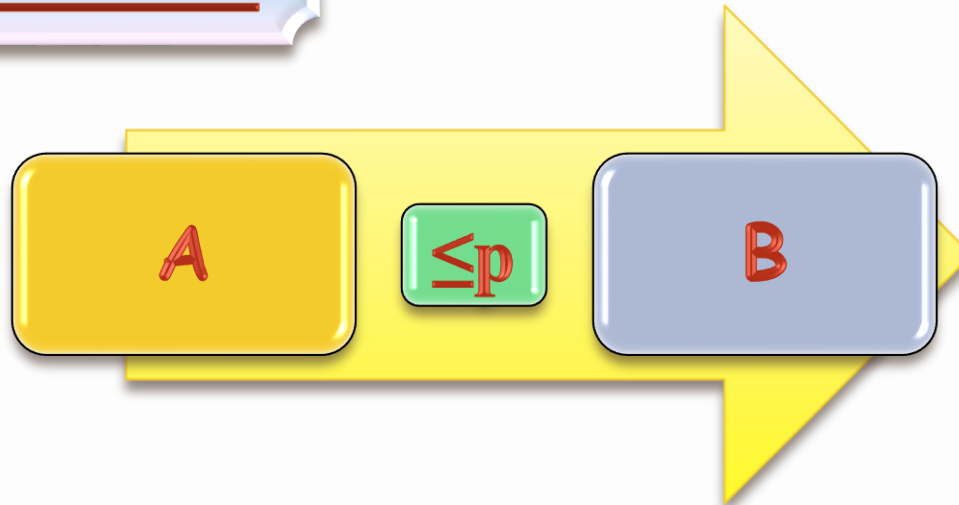
- Define **Karp** reductions
- Example: show HAMPATH  $\leq_p$  HAMCYCLE
- Closeness under reductions
- Define **Cook** reductions
- Discuss Completeness

# Reductions

an efficient procedure for  $A$   
using

an efficient procedure for  
 $B$

## Notation



$A$  cannot be  
radically harder  
than  $B$

- In other words:

$B$  is at least as  
hard as  $A$

# Karp reductions - Definition

$A$  is polynomial-time reducible to  $B$   
(denote  $A \leq_p B$ )

If  
there  
exists a

poly-time-computable  
function  $f: \Sigma^* \rightarrow \Sigma^*$

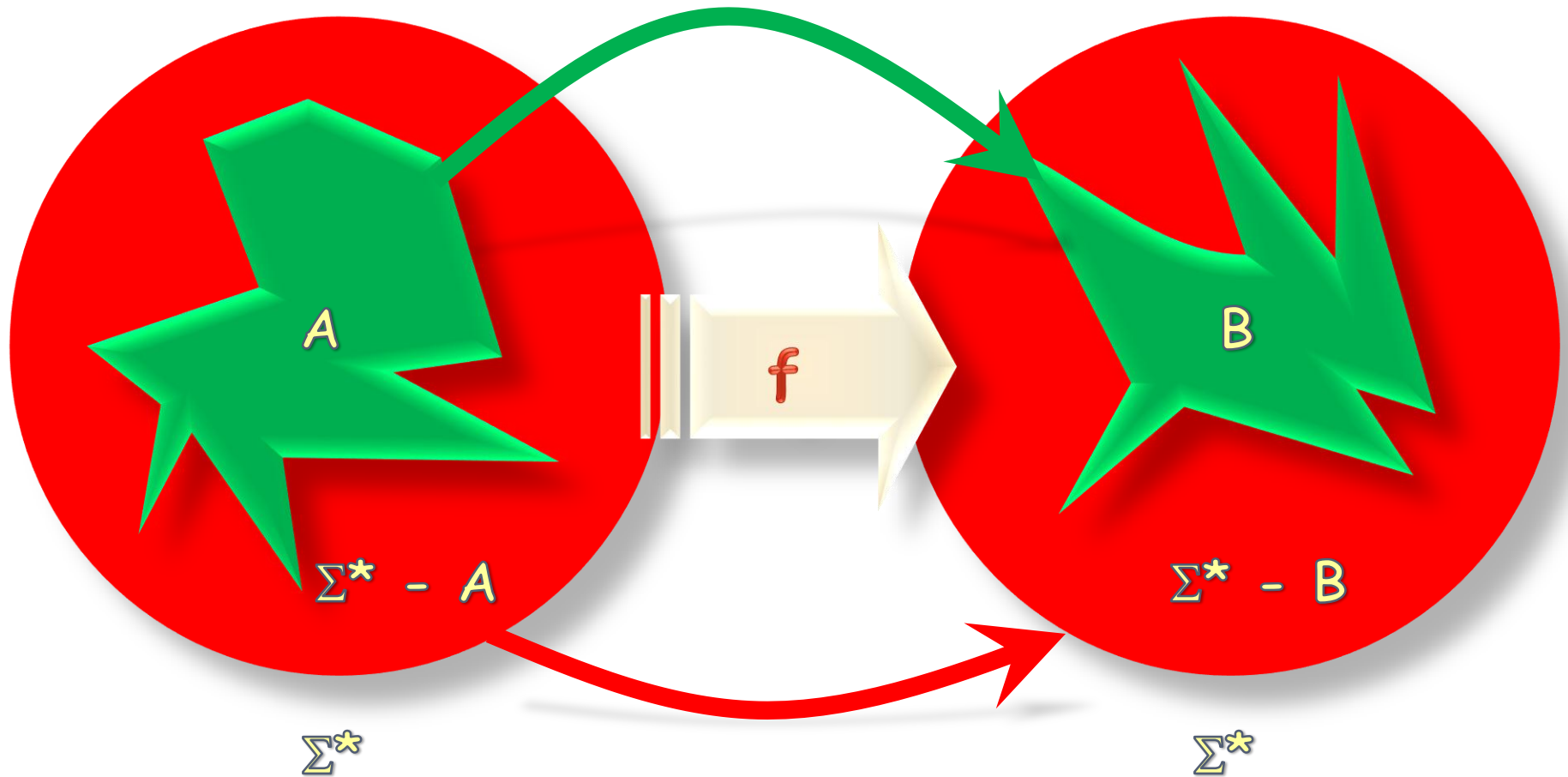
i.e.,  $\exists$  poly-time  
TM that outputs  
 $f(w)$  on input  $w$

s.t. for  
every  $w$

$w \in A \Leftrightarrow f(w) \in B$

$f$  is a poly-time  
reduction of  $A$  to  $B$

# Karp Reductions - Illustrated





To DO:

# Reducing

Come up with a reduction-function  $f$

Show  $f$  is polynomial time computable

Prove  $f$  is a reduction, i.e., show:

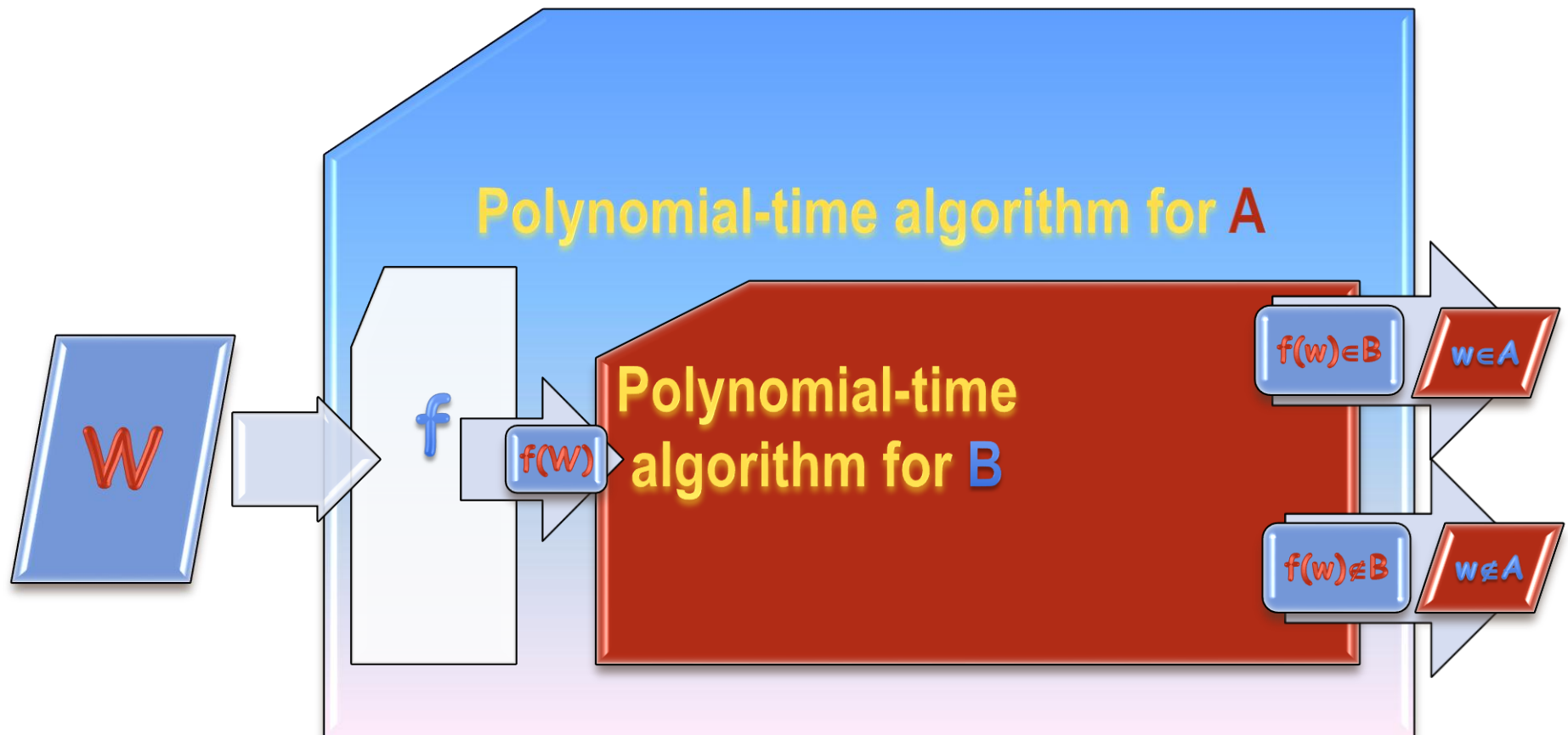
- $w \in A \implies f(w) \in B$
- $w \in A \implies f(w) \in B$



- We'll use reductions that, by default, would be of this type, which is called:
  - *Polynomial-time mapping reduction*
  - *Polynomial-time many-one reduction*
  - *Polynomial-time Karp reduction*

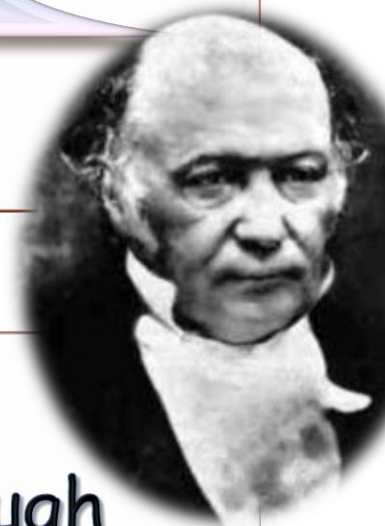


# Reductions and Efficiency



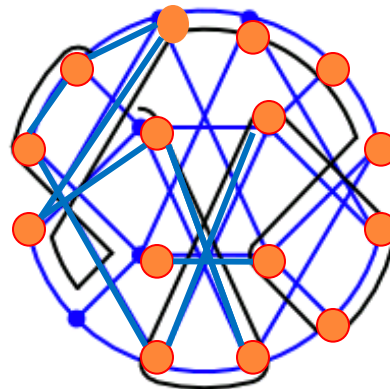
## Hamiltonian Path Instance:

- A directed graph  $G=(V,E)$



## Decision Problem:

- Is there a path in  $G$ , which goes through every vertex exactly once?

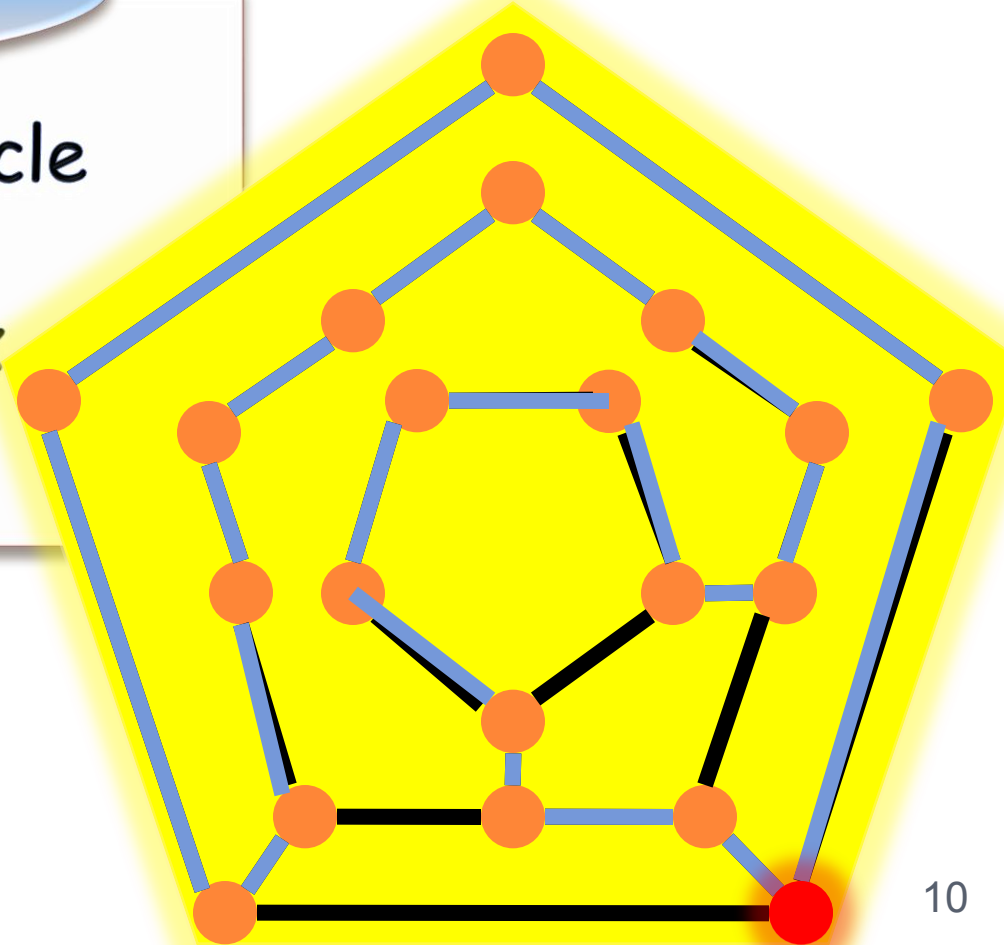


## Hamiltonian Cycle Instance:

- a directed graph  $G=(V,E)$ .

### Decision Problem:

- Is there a simple cycle in  $G$  that paths through each vertex exactly once?





# HAMPATH $\leq_p$ HAMCYCLE

$$f(\langle V, E \rangle) = \langle V \cup \{u\}, E \cup V \times \{u\} \rangle$$



## Completeness:

- Given a Hamiltonian path  $(v_0, \dots, v_n)$  in  $G$ ,  $(v_0, \dots, v_n, u)$  is a Hamiltonian cycle in  $G'$

## Soundness:

- Given a Hamiltonian cycle  $(v_0, \dots, v_n, u)$  in  $G'$ , removing  $u$  yields a Hamiltonian path.

# Check list

To DO:

✓ Come up with a reduction-function **f**

? ✓ Show **f** is polynomial time computable

Prove **f** is a reduction, i.e., show:

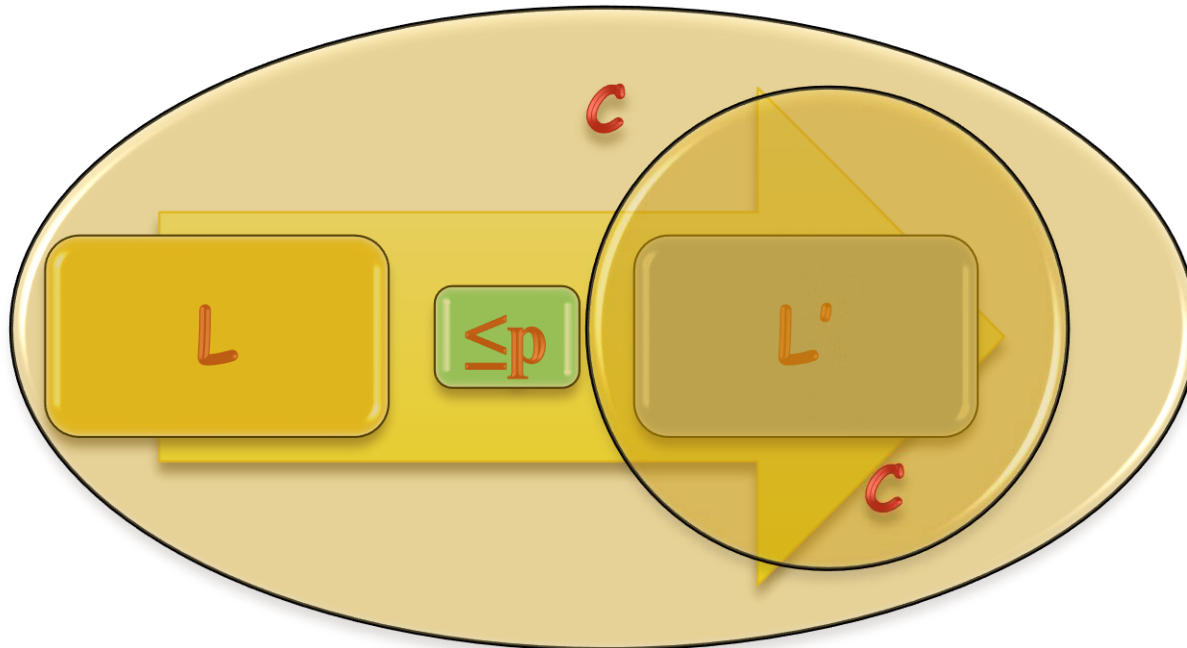
- ✓  $w \in \text{HAMPATH} \xrightarrow{\text{blue}} f(w) \in \text{HAMCYCLE}$
- ✓  $w \in \text{HAMPATH} \xleftarrow{\text{red}} f(w) \in \text{HAMCYCLE}$



# Closeness Under Reductions: Definition

A complexity class  $\mathcal{C}$  is closed under poly-time reductions if:

- $L$  is reducible to  $L'$  and  $L' \in \mathcal{C} \Rightarrow$   
 $L$  is also in  $\mathcal{C}$ .



# Observation

## Theorem:

- P, NP, PSPACE and EXPTIME are closed under polynomial-time Karp reductions

## Proof:

- Do it yourself !!





# Log-space Reductions

$A$  is log-space reducible to  $B$   
(denote  $A \leq_L B$ )

If  
there  
exists a

log-space-computable  
function  $f: \Sigma^* \rightarrow \Sigma^*$

s.t. for  
every  $w$

$w \in A \Leftrightarrow f(w) \in B$

i.e.,  $\exists$  log-space  
TM that outputs  
 $f(w)$  on input  $w$

$f$  is a log-space  
reduction of  $A$  to  $B$

Theorem:

- $\underline{L}$ ,  $\underline{NL}$ ,  $\underline{P}$ ,  $\underline{NP}$ ,  $\underline{PSPACE}$  and  $\underline{EXPTIME}$  are closed under log-space reductions.



# Reductions: General

## Cook Reduction:

- Assuming an efficient procedure that decides **B**, construct one for **A**.

an efficient procedure for **A**  
using

an efficient procedure for  
**B**

**Karp** is a special case  
of **Cook reduction**:

It allows only **1**  
**call** to **B**, whose  
outcome must be  
outputted as is

# Cook red. : HAMCYCLE $\rightarrow$ HAMPATH.

- 1 Let  $E' = E$
- 2 If  $E' = \emptyset$  reject
- 3 choose (any)  $\langle u, v \rangle$  in  $E'$
- 4 If  $\text{HAMPATH} ( \langle V + \{w, z\}, E' + \{\langle w, u \rangle, \langle v, z \rangle \} \rangle )$  accept
- 5  $E' = E' - \{\langle u, v \rangle\}$
- 6 Go to step 2

## Definition: $\mathcal{C}$ -complete

# Completeness



- For a class  $\mathcal{C}$  of decision problems and a language  $L \in \mathcal{C}$ ,  $L$  is  $\mathcal{C}$ -complete if:  
 $L' \in \mathcal{C} \Rightarrow L'$  is reducible to  $L$ .

## Theorem:

- $L$  is complete for classes  $\mathcal{C}, \mathcal{C}' \Rightarrow \mathcal{C} = \mathcal{C}'$

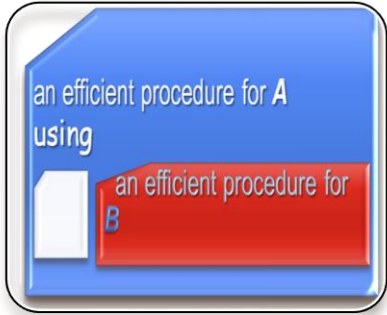
## Proof:

- All languages in  $\mathcal{C}$  and in  $\mathcal{C}'$  are reducible to  $L$ , which is in both. Since both are closed under reductions, they're the same ■

## Theorem:

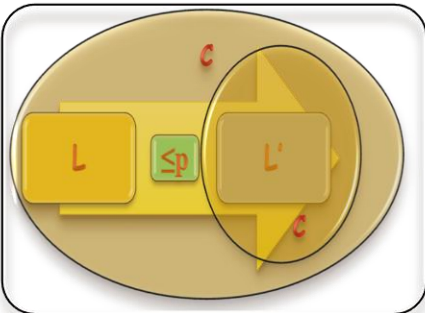
- Any  $L \in \text{NPC}, L \in \text{P} \Rightarrow \text{P} = \text{NP}$

# Summary



Discussed types of **reductions**:

- **Cook** vs. **Karp** reductions
- **Poly-time** vs. **log-space**



Defined:

- **"completeness"**

Find

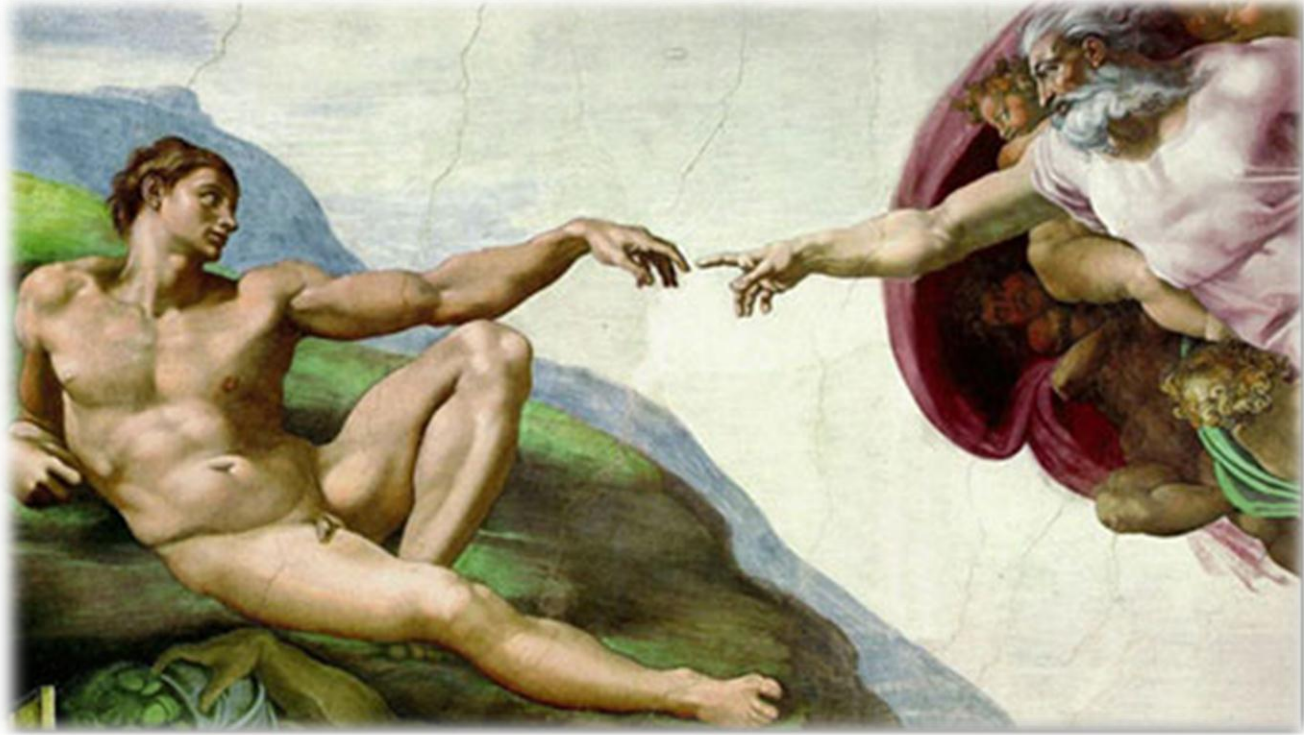
**L** and **C** s.t. **L**  
is **C-complete**



Discussed a way to show:

**equality** between **complexity classes**

The Cook/  
Levin  
theorem:



SAT is NP-Complete:



## Goal:

- In the beginning...  
of NP-Completeness

## Plan:

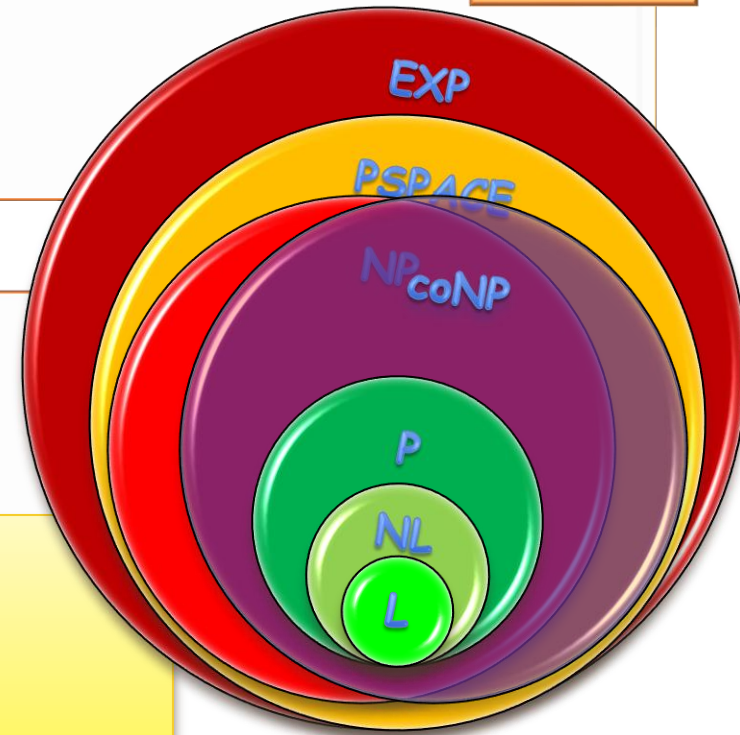
- SAT - definition and examples
- The Cook-Levin Theorem
- Look ahead

## SAT Instance:

- A Boolean formula.

## Decision Problem:

- Is the formula satisfiable?



SAT or  
unsAT?

$$x_1 \wedge \neg x_1$$

$$((x_1 \vee x_2 \vee \neg x_3) \wedge \neg x_1) \vee \neg(x_3 \wedge x_2)$$

## Theorem:

- SAT is in NP

## Proof:

- Can verify an ass. efficiently

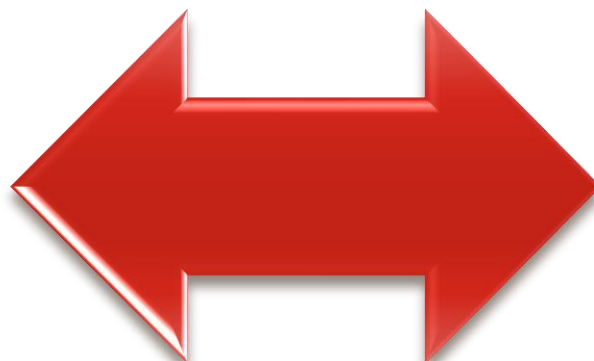


## Theorem:

- SAT is NP-Complete

## Proof Outline:

- Given an NP machine  $M$  and an input  $w$ , construct a *Boolean* formula  $\varphi_{M,w}$   
 $\varphi_{M,w}$  satisfiable  $\Leftrightarrow M$  accepts  $w$ .



$\varphi_{M,w}$   
 $\in SAT$

## Represent a computation as a configurations' table

machine's state

# Input

Tape ends



# Example

$$Q = \{q_0, q_1, q_{\text{accept}}, q_{\text{reject}}\}$$

$$\Sigma = \{0, 1\}$$

$$\Gamma = \{0, 1, \_ \}$$

$$\delta$$

$$\begin{aligned} \delta(q_0, 1) &= \{(q_1, \_, R)\} \\ \delta(q_1, 1) &= \{(q_0, \_, R)\} \\ \delta(q_0, 0) &= \{(q_0, \_, R)\} \\ \delta(q_1, 0) &= \{(q_1, \_, R)\} \\ \delta(q_0, \_) &= \{(q_{\text{acc}}, \_, L)\} \\ \delta(q_1, \_) &= \{(q_{\text{rej}}, \_, L)\} \end{aligned}$$

|   |                |                |                |                  |                |   |
|---|----------------|----------------|----------------|------------------|----------------|---|
| # | q <sub>0</sub> | 0              | 1              | 1                | 1              | # |
| # | _              | q <sub>0</sub> | 1              | 1                | 1              | # |
| # | _              | _              | q <sub>1</sub> | 1                | 1              | # |
| # | _              | _              | _              | q <sub>0</sub>   | 1              | # |
| # | _              | _              | _              | _                | q <sub>1</sub> | # |
| # | _              | _              | _              | q <sub>rej</sub> | _              | # |

$$Q = \{q_0, q_1, q_{\text{accept}}, q_{\text{reject}}\}$$

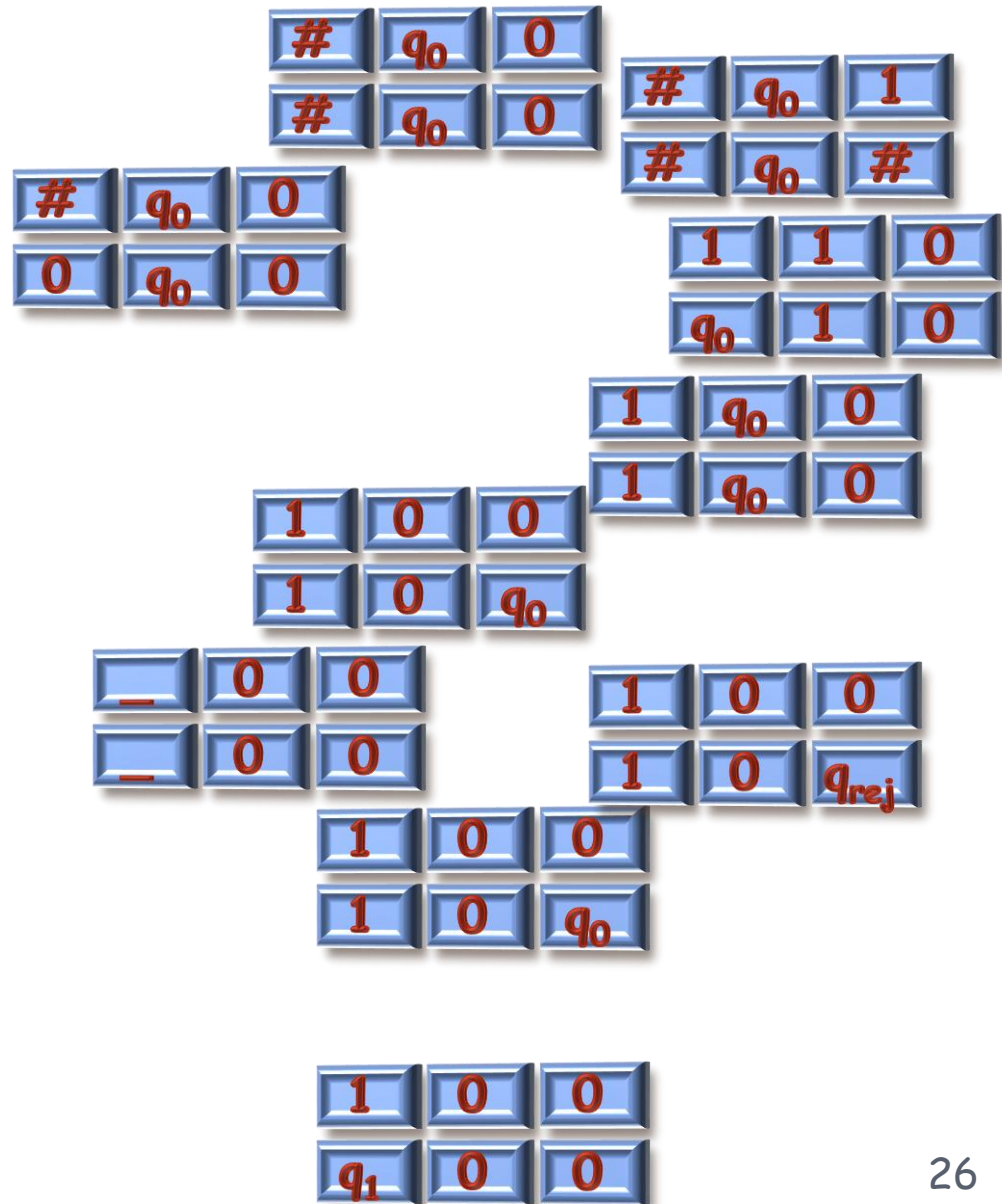
$$\Sigma = \{0, 1\}$$

$$\Gamma = \{0, 1, \_ \}$$

$$\delta$$

$$\begin{aligned} \delta(q_0, 1) &= \{(q_1, \_, R)\} \\ \delta(q_1, 1) &= \{(q_0, \_, R)\} \\ \delta(q_0, 0) &= \{(q_0, \_, R)\} \\ \delta(q_1, 0) &= \{(q_1, \_, R)\} \\ \delta(q_0, \_) &= \{(q_{\text{acc}}, \_, L)\} \\ \delta(q_1, \_) &= \{(q_{\text{rej}}, \_, L)\} \end{aligned}$$

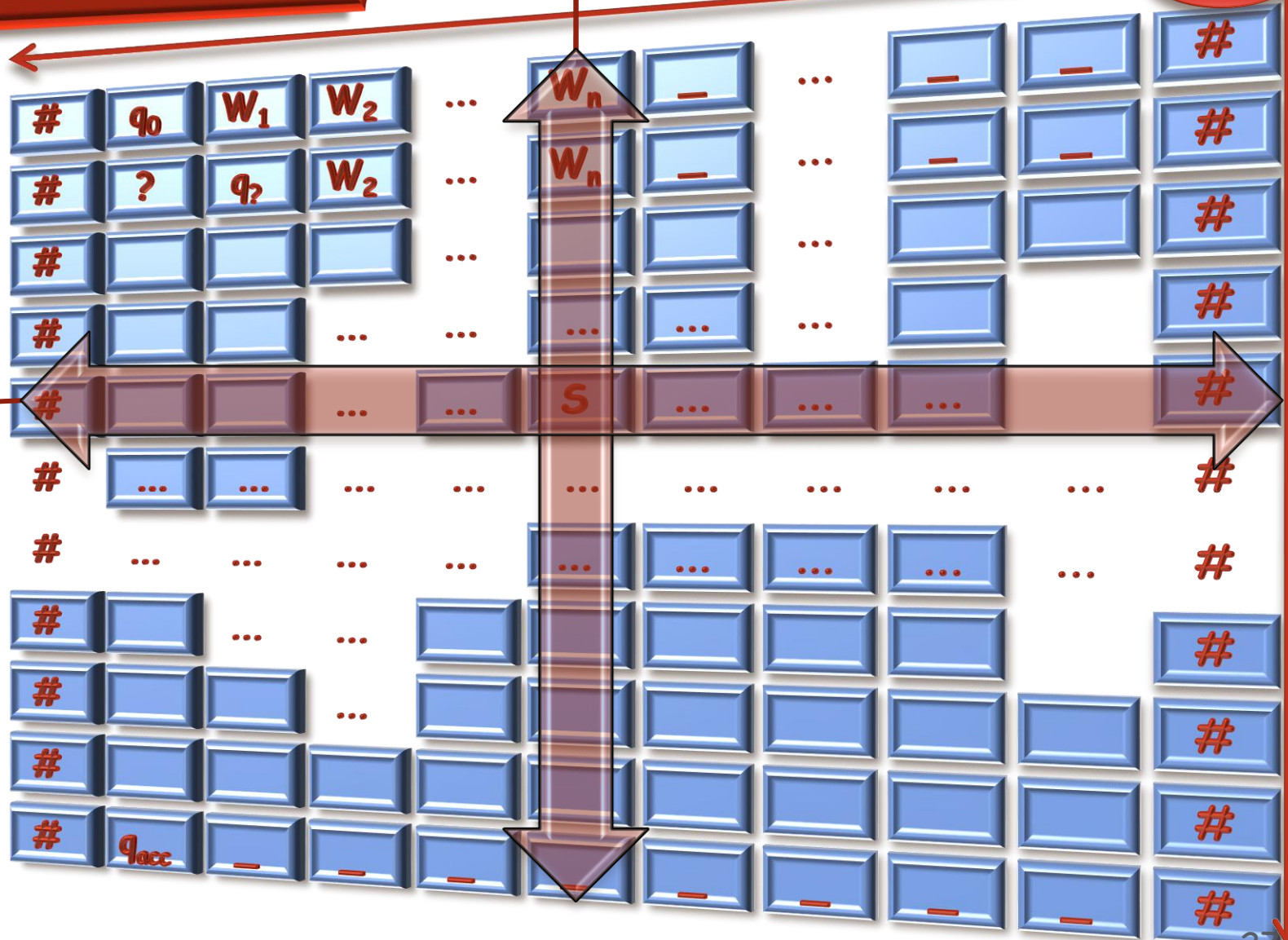
$$\Delta_M \subset (\Gamma \cup Q \cup \{\#\})^6$$



Boolean  $X_{i,j,s}$  standing for:  
does cell  $i,j$  has value  $s$ ?

$\varphi_{M,w}$  variables

$cn^e$



$$\varphi_{M,w} =$$

$$\varphi_{M,w}$$

$\geq 1$  value

$< 2$  values

1 value to each entry

$$\bigwedge_{1 \leq i, j \leq cn^e} \left[ \left( \bigvee_{s \in (\Gamma \cup Q \cup \{\#\})} X_{i,j,s} \right) \wedge \left( \bigwedge_{s \neq t \in (\Gamma \cup Q \cup \{\#\})} (\overline{X_{i,j,s}} \vee \overline{X_{i,j,t}}) \right) \right]$$

input consistent

start

input

blanks

$$\bigwedge X_{0,0,\#} \bigwedge X_{0,1,q_0} \bigwedge X_{0,2,w_1} \bigwedge \dots \bigwedge X_{0,n+1,w_n} \bigwedge X_{0,n+2,-} \bigwedge \dots \bigwedge X_{0,cn^e,-} \bigwedge X_{0,cn^e+1,\#}$$

locally legal transition

transitions legal

$$\bigwedge_{0 \leq i, j \leq cn^e} \left[ \left( \bigvee \langle s_{0,0}, s_{0,1}, s_{1,0}, s_{1,1}, s_{2,0}, s_{2,1} \rangle \in \Delta_M \left[ \bigwedge_{i'=0,1,2, j'=0,1} X_{i+i', j+j', s_{i',j'}} \right] \right) \right]$$

machine accepts

$\exists$  accepting configuration

$$\bigwedge_{0 \leq i, j \leq cn^e} \bigvee X_{i,j,q_{acc}}$$

$\varphi_{M,w} =$ 

$$\bigwedge_{1 \leq i, j \leq cn^e} \left[ \left( \bigvee_{s \in (\Gamma \cup Q \cup \{\#\})} x_{i,j,s} \right) \wedge \left( \bigwedge_{s \neq t \in (\Gamma \cup Q \cup \{\#\})} (\overline{x_{i,j,s}} \vee \overline{x_{i,j,t}}) \right) \right]$$

$$\wedge X_{0,0,\#} \wedge X_{0,1,q_0} \wedge X_{0,2,w_1} \wedge \dots \wedge X_{0,n+1,w_n} \wedge X_{0,n+2,-} \wedge \dots \wedge X_{0,cn^e,-} \wedge X_{0,cn^e+1,\#}$$

$$\bigwedge_{0 \leq i, j \leq cn^e} \left[ \left\langle s_{0,0}, s_{0,1}, s_{1,0}, s_{1,1}, s_{2,0}, s_{2,1} \right\rangle \in \Delta_M \left[ \bigwedge_{i'=0,1,2, j'=0,1} \left[ X_{i+i', j+j', s_{i',j'}} \right] \right] \right]$$

$$\bigwedge_{0 \leq i, j \leq cn^e} \bigvee X_{i,j,q_{acc}}$$

Q.E.D.

**Claim:**

- $\forall i, j$  transition is locally legal  $\Leftrightarrow$  tableau legal

**Corollary:**

- $\varphi_{M,w}$  Satisfiable  $\Leftrightarrow W \in L_M$

**Claim:**

- Size of  $\varphi_{M,w}$  polynomial in  $|W|$

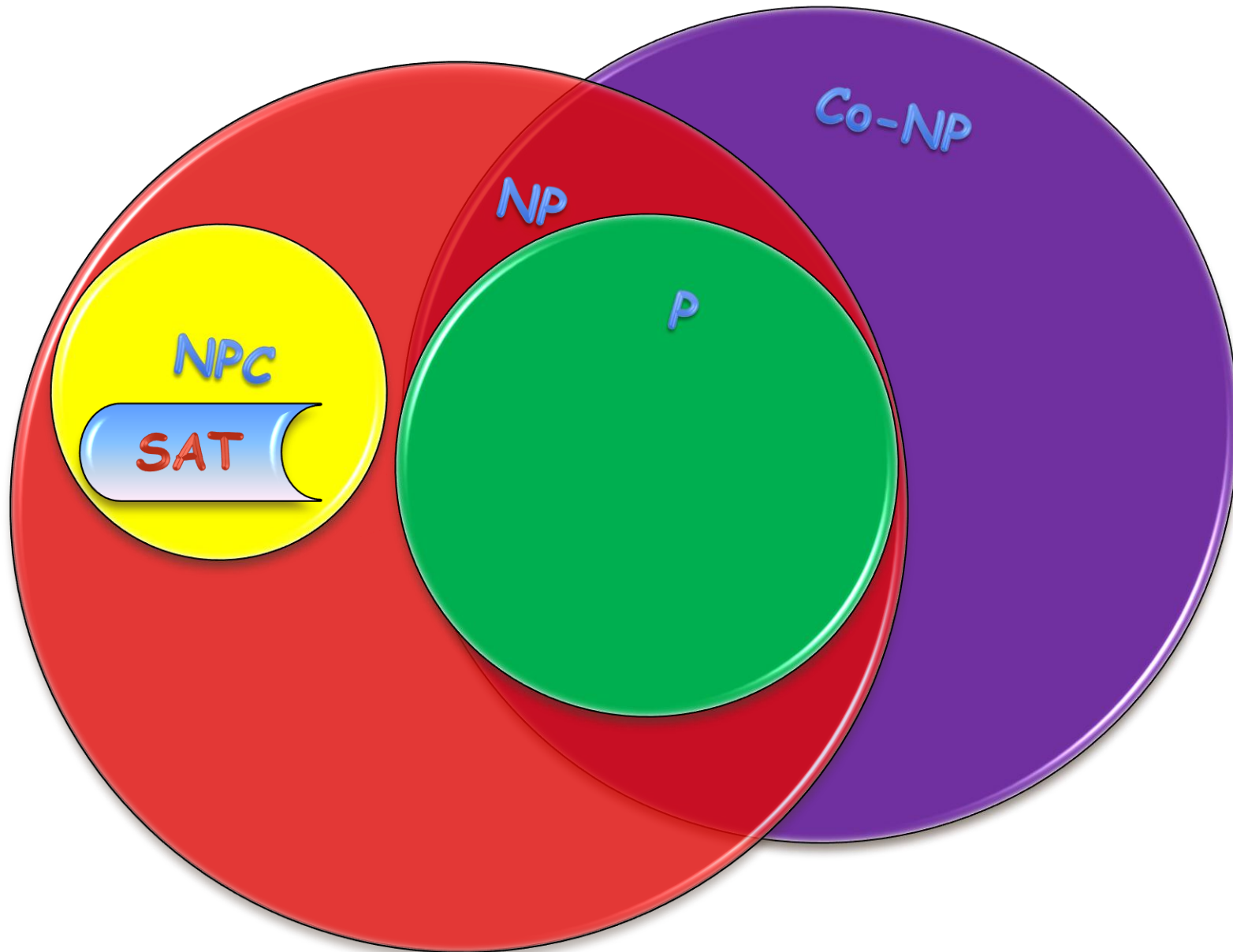


We have just shown  
**SAT** is **NP-hard**, as  
any **NP** language can  
be reduced to **SAT**

**SAT is NPC**



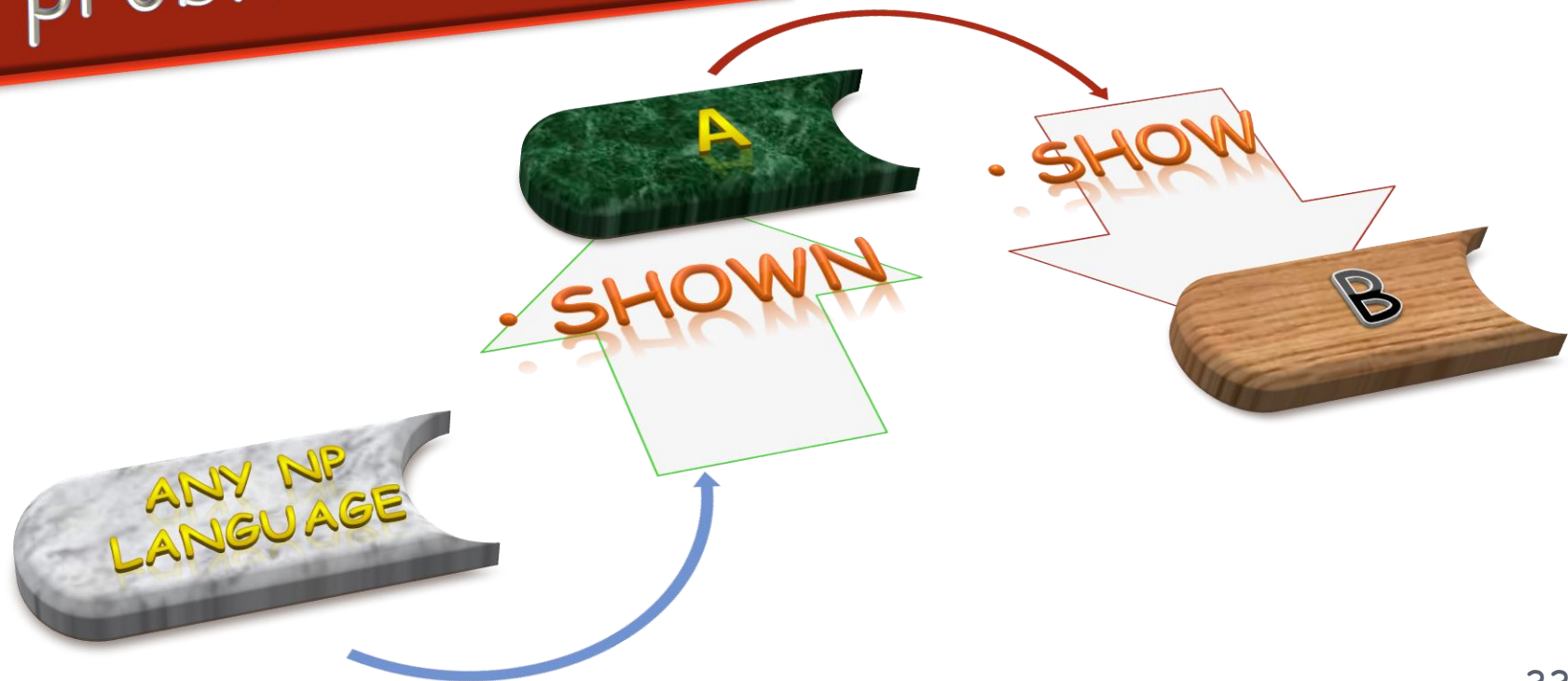
# P, NP, co-NP and NPC



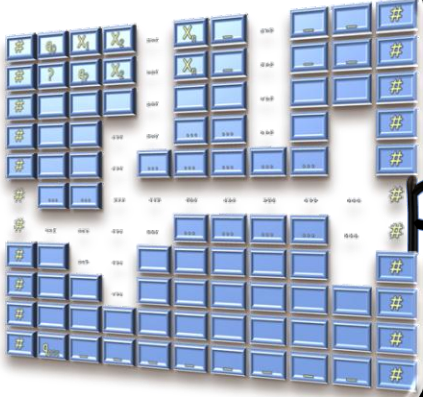
Henceforth, to show  
a problem **A** is **NP-**  
**hard**, it suffices to  
reduce **SAT** to **A**



Furthermore, once we've shown **A** is **NP-hard**, we can reduce from it to show other problems **NP-hard**



# Summary



proved **SAT** is **NP-Complete**



Consider **SAT** the Genesis problem, and explored how to proceed and show other problems are **NP-hard**

## Goal:

- introduce some additional NP-Complete problems.

## Plan:

- 3SAT
- CLIQUE & INDEPENDENT-SET

Recall:  $L$  is NPC if

- $L$  In NP
- $L$  NP-hard - via Karp-reduction

# SAT and NPC

So far we only showed one such problem: SAT

- which, however, is not up for the tasks ahead

Next we show a special case of SAT is NPC:

- 3SAT

3SAT Instance:

- 3CNF formula

Conjunctive Normal Form -  
3 literals in each clause

Decision Problem:

- Is it satisfiable?

3CNF:

$$(x \vee y \vee \neg z) \wedge (x \vee \neg y \vee z) \\ (x \vee x \vee x) \wedge (\neg x \vee \neg x \vee \neg x)$$

**Claim:**

- 3SAT  $\in$  NP ♦

3SAT is a special case of SAT.

**Claim:**

- 3SAT  $\in$  NP-hard

**Proof:**

- amend our SAT formula, so it becomes 3CNF
- First make it a CNF: use DNF  $\rightarrow$  CNF on 3rd line

Does this suffice?

Are all others OK?

What is the size of new formula?

$$\varphi_{M,w} = \bigwedge_{1 \leq i, j \leq cn^e} \left[ \left( \bigvee_{s \in (\Gamma \cup Q \cup \{\#\})} x_{i,j,s} \right) \wedge \left( \bigwedge_{s \neq t \in (\Gamma \cup Q \cup \{\#\})} (\overline{x_{i,j,s}} \vee \overline{x_{i,j,t}}) \right) \right]$$

$$\wedge x_{0,0,\#} \wedge x_{0,1,q_0} \wedge x_{0,2,w_1} \wedge \dots \wedge x_{0,n+2,w_n} \wedge x_{0,n+3,-} \wedge \dots \wedge x_{0,cn^e,-} \wedge x_{0,cn^e+1,\#}$$

$$\bigwedge_{0 \leq i, j \leq cn^e} \left[ \left( \bigvee_{\langle s_{0,0}, s_{0,1}, s_{1,0}, s_{1,1}, s_{2,0}, s_{2,1} \rangle \in \Delta_M} \left[ x_{i+i', j+j', s_{i',j'}} \right] \right) \right]$$

$$\wedge \bigvee_{0 \leq i, j \leq cn^e} x_{i,j,q_{acc}}$$

# CNF $\rightarrow$ 3CNF

$$(x \vee y) \wedge (x_1 \vee x_2 \vee \dots \vee x_t) \wedge \dots$$

clauses with 1 or  
2 literals

replication

$$(x \vee y \vee x)$$

clauses with more than 3  
literals

split

$$(x_1 \vee x_2 \vee c_{11}) \wedge (\neg c_{11} \vee x_3 \vee c_{12}) \wedge \dots \wedge (\neg c_{1t-3} \vee x_{t-1} \vee x_t)$$

QED

3SAT is NP-Complete

# CLIQUE is NPC

## CLIQUE instance:

- A graph  $G=(V,E)$  and a threshold  $k$

## Decision problem:

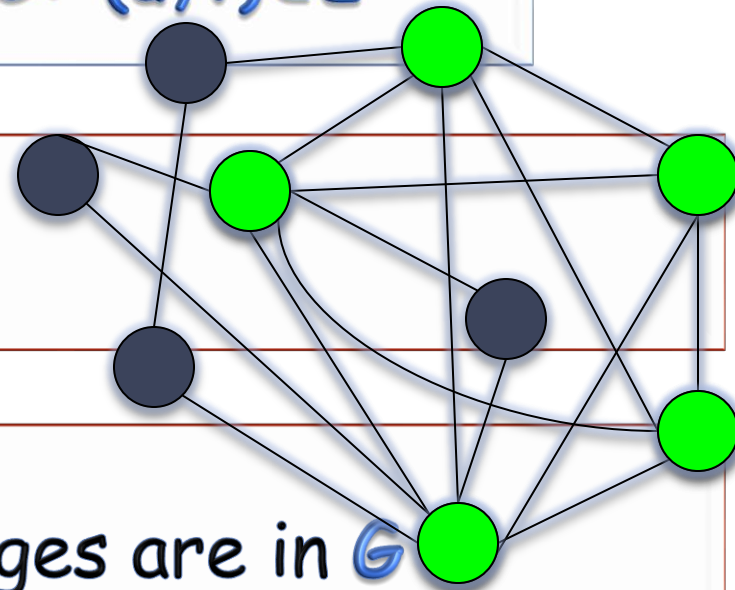
- Is there a set of nodes  $C=\{v_1, \dots, v_k\} \subseteq V$ , s.t.  $\forall u, v \in C: (u, v) \in E$

## Observation:

- $CLIQUE \in NP$

## Proof:

- Given  $C$ , verify all inner edges are in  $G$



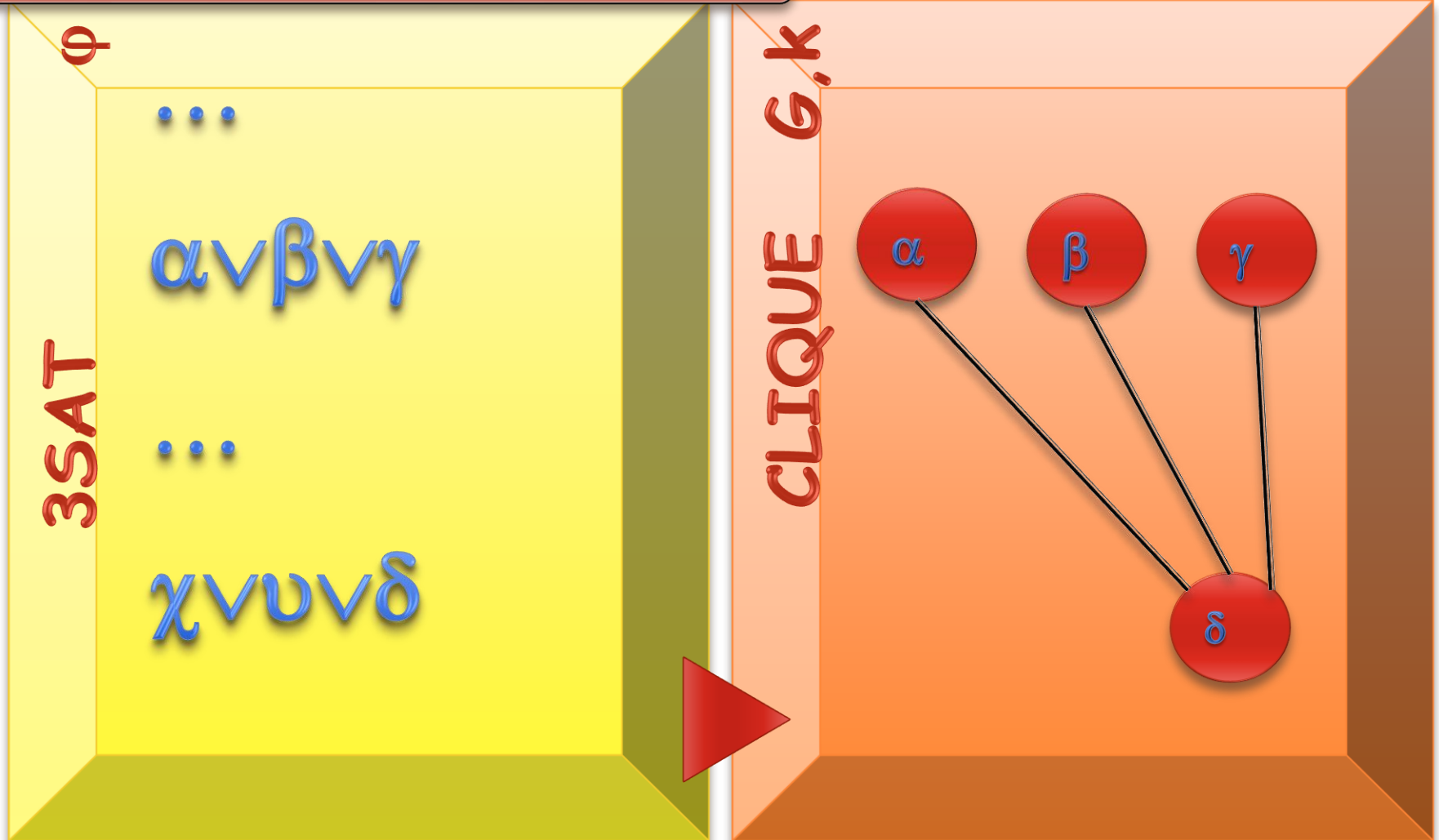
1 vertex for 1 occurrence

inconsistency  $\Leftrightarrow$  non-edge

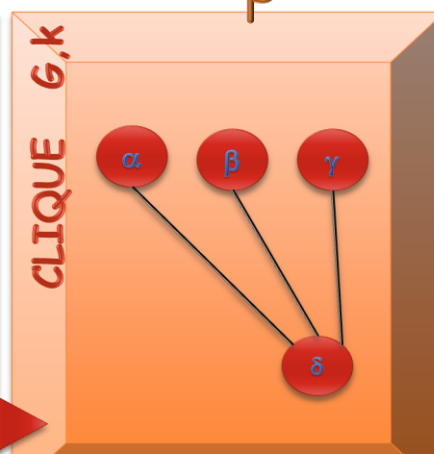
• within triplets  $\alpha = -\delta$

K = number of clauses

$$\underline{SAT} \leq_p \underline{CLIQUE}$$



# SAT $\leq_p$ CLIQUE: proof



each triplet disconnected  
 $k$ -clique has 1 vertex in each

## Completeness:

- Let  $A$  be a satisfying assignment to  $\varphi$ ,  $C(A)$  contains 1  $v_\alpha$  s.t.  $A(v_\alpha)$  for every clause

## Soundness:

- In a clique  $C$  in  $G$  of size  $k$ , each variable has  $\leq 1$  of its literals-vertex in  $C$
- extend to a satisfying assignment to  $\varphi$

# INDEPENDENT-SET is NPC

## IS instance:

- A graph  $G=(V,E)$  and a threshold  $k$

## Decision problem:

- Is there a set of nodes  $I=\{v_1, \dots, v_k\} \subseteq V$ , s.t.  $\forall u, v \in I: (u,v) \notin E$

## Observation:

- $IS \in NP$

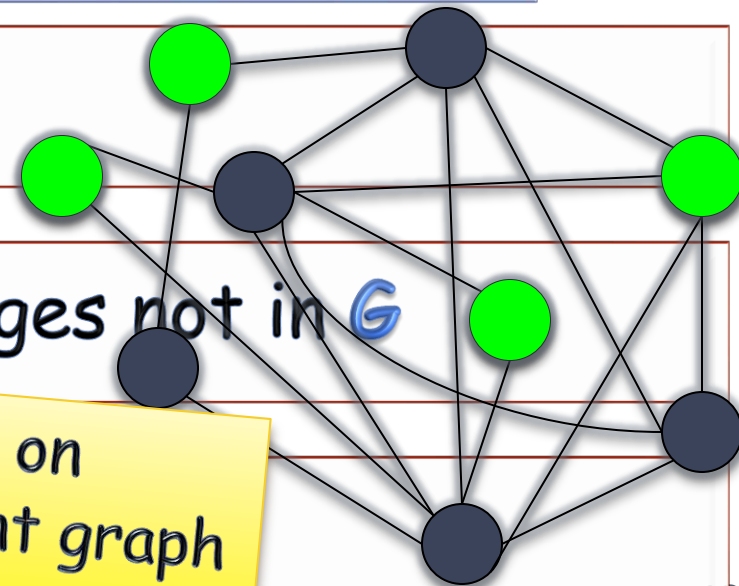
## Proof:

- Given  $I$ , verify all inner edges not in  $G$

## Observation:

- $IS$  is NP-hard

$Clique=IS$  on  
complement graph



Reductions

Polynomial  
Time  
Reductions

Completeness



Hamiltonian  
Path

Log Space  
Reductions

Completeness



Complexity  
Classes

NP

co-NP

P

L

NL

EXPTIME

PSPACE

WWindex



Hamilton, William  
Rowan



Karp, Richard



Cook, Stephen  
Arthur



Levin, Leonid

SAT

Cook-Levin  
Theorem



3SAT

Cook-Levin  
Theorem



Clique

Independent  
Set

Subset Sum

CNF

NPC

NP Hard

# WWindex