Country Portfolio Dynamics

Devereux and Sutherland

Presented by Judit Temesvary

April 2 2008







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② General overview of methodology

- General overview of methodology
 - Solution method for the steady state portfolio



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 - Solution method for the steady state portfolio
 - Solution method for time variation in equilibrium portfolio



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- Useful in studying the response of portfolio allocations to business cycles

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- Solution to first problem: use second-order approximations
- Solution to second problem: portfolio equilibrium endogenously determined so as to satisfy second order approximations of EOCs

General Overview of Methodology

Portfolio holdings

$$\alpha(Z_t) \simeq \alpha(\overline{Z}) + \frac{\partial \alpha}{\partial Z} \Big(Z_t - \overline{Z} \Big)$$
$$\simeq \overline{\alpha} + \underbrace{\hat{\alpha}_t}_{=\gamma \hat{Z}_t}$$

- Samuelson (1970): to solve for portfolio holdings up to order *N* approximate the portfolio problem up to order *N*+2
- Expected excess returns

$$E_t[r_{xt+1}] = E_t[r_{1t+1} - r_{2t+1}] \simeq \underbrace{\overline{r_x}^e}_{=0} + \underbrace{\hat{r_x}^{e(1)}}_{=0} + \underbrace{\hat{r_x}^{e(2)}}_{constant} + \underbrace{\hat{r_x}^{e(3)}}_{=\delta'\hat{Z}},$$

 Once portfolio problem is solved the first-order behaviour of all other variables can be solved in the usual way - including the first-order behaviour of realised asset prices and returns

Separate variables into portfolio and non-portfolio variables



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- Solve (5) for eqm. portfolio



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- Solve (5) for vector of coefficients for time variation in eqm. portfolio

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- Two countries and two (internationally traded) assets
- Home country produces good Y_H with price P_H
- Foreign country produces good Y_F with price P_F^*
- Home country agent preferences:

$$U_t = E_t \sum_{\tau=t}^{\infty} \beta^{\tau-t} \left[u(C_\tau) + v(.) \right]$$

- C is a composite of home and foreign goods
- $v\left(\cdot
 ight)$ captures parts not relevant to the portfolio problem
- *P* : consumer price index for home agents

Image: A matrix

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•
$$r'_t = \begin{bmatrix} r_{1,t} & r_{2,t} \end{bmatrix}$$



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• Then we have:

•
$$\alpha_{1,t-1} + \alpha_{2,t-1} = W_{t-1}$$



•
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Excess returns:

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Excess returns:

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$$r_{x,t} = r_{1,t} - r_{2,t}$$

 At end of each period, agents select portfolio holding to carry into next period

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For domestic agents:

$$E_t \left[u'(C_{t+1})r_{1,t+1} \right] = E_t \left[u'(C_{t+1})r_{2,t+1} \right]$$

For foreign agents:

$$E_t \left[u'(C_{t+1}^*)r_{1,t+1} \right] = E_t \left[u'(C_{t+1}^*)r_{2,t+1} \right]$$

From now, let: $\alpha_t = \alpha_{1,t}$ and $\alpha_{2,t} = W_t - \alpha_t$ Ignore non-portfolio equations for home and foreign agents • Approximate around \bar{X} (non-portfolio variables \bar{C} , \bar{r}_x , \bar{Y} , \bar{W}) and $\bar{\alpha}$ (portfolio holdings)



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$$\bar{W} = 0, \ \bar{Y} = \bar{C} \qquad \bar{r}_x = 0$$
$$\bar{r}_1 = \bar{r}_2 = 1/\beta \qquad \bar{\alpha}_2 = -\bar{\alpha}_1 = \bar{\alpha}$$



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α determined endogenously - point such that second-order approximations of the FOCs are satisfied around *X* and *α α*

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• Second-order approximation of the home-country FOC: $E_t \left[\hat{r}_{x,t+1} + \frac{1}{2} \left(\hat{r}_{1,t+1}^2 - \hat{r}_{2,t+1}^2 \right) - \rho \hat{C}_{t+1} \hat{r}_{x,t+1} \right] = O \left(\epsilon_{APPR}^3 \right)$ • Second-order approximation of the foreign-country FOC: $E_t \left[\hat{r}_{x,t+1} + \frac{1}{2} \left(\hat{r}_{1,t+1}^2 - \hat{r}_{2,t+1}^2 \right) - \rho \hat{C}_{t+1}^* \hat{r}_{x,t+1} \right] = O \left(\epsilon_{APPR}^3 \right)$



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 (1)



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- $E_t \left[\left(\hat{C}_{t+1} \hat{C}^*_{t+1} \right) \hat{r}_{x,t+1} \right] = 0 + O \left(\epsilon^3_{APPR} \right)$ (1)
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$$E[\hat{r}_{x}] = -\frac{1}{2}E[\hat{r}_{1,t+1}^{2} - \hat{r}_{2,t+1}^{2}] + \rho \frac{1}{2}E_{t}[(\hat{c}_{t+1} - \hat{c}_{t+1}^{*})\hat{r}_{x,t+1}] + O(\epsilon_{APPR}^{3})$$
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• Need to find $\bar{\alpha}$ such that (1) holds

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 - α enters the non-portfolio solutions only through the budget constraint
 - Only $\bar{\alpha}$ enters the first-order approximation of the budget constraints
 - The portfolio excess return $\bar{\alpha}\hat{r}_{x,t+1}$ is a zero mean iid. random variable, and $E(\hat{r}_x) = 0$.



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$$\hat{W}_t = rac{1}{eta} \hat{W}_{t-1} + \hat{Y}_t - \hat{C}_t + \xi_t + O\left(\epsilon_{APPR}^2\right)$$



•
$$A_1 \begin{bmatrix} s_{t+1} \\ E_t [c_{t+1}] \end{bmatrix} = A_2 \begin{bmatrix} s_t \\ c_t \end{bmatrix} + A_3 x_t + B\xi_t + O(\epsilon_{APPR}^2)$$

 $x_t = N x_{t-1} + \varepsilon_t$



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- ε: vector of iid. shocks



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• We can use these equations to express the LHS terms of (1) in terms of ξ and exogenous terms



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- $\hat{r}_{x,t+1} = [R_1] \xi_{t+1} + [R_2]_i [\varepsilon_{t+1}]^i + O(\varepsilon_{APPR}^2)$



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- $\hat{r}_{x,t+1} = [R_1] \xi_{t+1} + [R_2]_i [\varepsilon_{t+1}]^i + O(\varepsilon_{APPR}^2)$

$$\left(\hat{C}_{t+1} - \hat{C}_{t+1}^*\right) = \left[D_1\right]\xi_{t+1} + \left[D_2\right]_i \left[\varepsilon_{t+1}\right]^i + \left[D_3\right]_k \left[z_{t+1}\right]^k + O\left(\varepsilon_{APPR}^2\right)^{i}$$



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$$\hat{r}_{x,t+1} = [R_1] \xi_{t+1} + [R_2]_i [\varepsilon_{t+1}]^i + O(\varepsilon_{APPR}^2)$$

$$(\hat{C}_{t+1} - \hat{C}_{t+1}^*) = [D_1] \xi_{t+1} + [D_2]_i [\varepsilon_{t+1}]^i + [D_3]_k [z_{t+1}]^k + O(\varepsilon_{APPR}^2)^{i}$$

where the vector of state variables:

$$z_{t+1}' = \left[\begin{array}{cc} x_t & s_{t+1} \end{array} \right]$$



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• Using the fact that

$$\xi_{t+1} = \tilde{\alpha} \hat{r}_{x,t+1}$$

we get the reduced form equations:

$$\begin{split} \hat{r}_{x,t+1} &= \left[\tilde{R}_{2}\right]_{i} \left[\varepsilon_{t+1}\right]^{i} + O\left(\varepsilon_{APPR}^{2}\right) \\ \left(\hat{C}_{t+1} - \hat{C}_{t+1}^{*}\right) &= \left[\tilde{D}_{2}\right]_{i} \left[\varepsilon_{t+1}\right]^{i} + \left[D_{3}\right]_{k} \left[z_{t+1}\right]^{k} + O\left(\varepsilon_{APPR}^{2}\right) \end{split}$$

...where the matrices are:

$$\begin{split} [\tilde{R}_{2}]_{i} &= \frac{1}{1 - [R_{1}]\tilde{\alpha}} [R_{2}]_{i} \\ [\tilde{D}_{2}]_{i} &= \left(\frac{[D_{1}]\tilde{\alpha}}{1 - [R_{1}]\tilde{\alpha}} [R_{2}]_{i} + [D_{2}]_{i}\right) \end{split}$$

• Now we can evaluate the LHS of (1)!!!

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Solving for the portfolio approximation point

 $\bullet\,$ Combining the above terms, we can rewrite and simplify (1) as:

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• Solving for the corresponding equilibrium portfolio:

$$\tilde{\alpha} = \frac{[D_2]_i [R_2]_j [\Sigma]^{i,j}}{([R_1][D_2]_i [R_2]_j - [D_1][R_2]_i [R_2]_j) [\Sigma]^{i,j}}$$

Time variation in equilibrium portfolios

• The above solution is non time-varying: now want to analyze portfolio behavior around equilibrium



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- State variables change over time: portfolio choice problem is different in every period



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- We need a third-order approximation of portfolio problem



Third-order Approximation

• Combining third-order approximations of home and foreign protfolio choice FOCs yields:

$$E_{t} \begin{bmatrix} -\rho \left(\hat{C}_{t+1} - \hat{C}_{t+1}^{*} \right) \hat{r}_{x,t+1} \\ + \frac{\rho^{2}}{2} \left(\hat{C}_{t+1}^{2} - \hat{C}_{t+1}^{2*} \right) \hat{r}_{x,t+1} \\ - \frac{\rho}{2} \left(\hat{C}_{t+1} - \hat{C}_{t+1}^{*} \right) \left(\hat{r}_{1,t+1}^{2} - \hat{r}_{2,t+1}^{2} \right) \end{bmatrix} = O \left(\epsilon_{APPR}^{4} \right) (3)$$

$$E_{t} \left[\hat{r}_{x,t+1} \right] = E_{t} \begin{bmatrix} -\frac{1}{2} \left(\hat{r}_{1,t+1}^{2} - \hat{r}_{2,t+1}^{2} \right) \\ -\frac{1}{6} \left(\hat{r}_{1,t+1}^{3} - \hat{r}_{2,t+1}^{3} \right) \\ + \rho \left(\hat{C}_{t+1} + \hat{C}_{t+1}^{*} \right) \hat{r}_{x,t+1} \\ -\frac{\rho^{2}}{2} \left(\hat{C}_{t+1}^{2} + \hat{C}_{t+1}^{2*} \right) \hat{r}_{x,t+1} \\ + \frac{\rho}{2} \left(\hat{C}_{t+1} + \hat{C}_{t+1}^{*} \right) \left(\hat{r}_{1,t+1}^{2} - \hat{r}_{2,t+1}^{2} \right) \end{bmatrix} + O \left(\epsilon_{APPR}^{4} \right) (4)$$



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• These are the third-order equivalents of (1) and (2)

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The Portfolio Solution

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$$\hat{W}_{t+1} = \frac{1}{\beta}\hat{W}_t + \hat{Y}_{t+1} - \hat{C}_{t+1} + \tilde{\alpha}\hat{r}_{x,t+1} + \frac{1}{2}\hat{Y}_{t+1}^2 - \frac{1}{2}\hat{C}_{t+1}^2 + \frac{1}{2}\tilde{\alpha}\left(\hat{r}_{1,t+1}^2 - \hat{r}_{2,t+1}^2\right) + \hat{\alpha}_t\hat{r}_{x,t+1} + \frac{1}{\beta}\hat{W}_t\hat{r}_{2,t} + O\left(\epsilon_{APPR}^3\right)$$

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$$\hat{W}_{t+1} = \frac{1}{\beta}\hat{W}_t + \hat{Y}_{t+1} - \hat{C}_{t+1} + \tilde{\alpha}\hat{r}_{x,t+1} + \frac{1}{2}\hat{Y}_{t+1}^2$$

$$-\frac{1}{2}\hat{C}_{t+1}^2 + \frac{1}{2}\tilde{\alpha}\left(\hat{r}_{1,t+1}^2 - \hat{r}_{2,t+1}^2\right) + \hat{\alpha}_t\hat{r}_{x,t+1} + \frac{1}{\beta}\hat{W}_t\hat{r}_{2,t} + O\left(\epsilon_{APPR}^3\right)$$
• where

$$\hat{\alpha}_t = \frac{1}{\beta \bar{Y}} (\alpha_t - \bar{\alpha}) = \frac{\alpha_t}{\beta \bar{Y}} - \tilde{\alpha}$$

 Postulate that \$\hat{\alpha}_t\$ is a linear function of the state variables of the model:

$$\hat{\alpha}_t = \gamma' \begin{bmatrix} x_t \\ s_{t+1} \end{bmatrix} = \gamma' z_{t+1} = [\gamma]_k [z_{t+1}]^k$$



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• Let
$$\xi_t = \hat{\alpha}_t \hat{r}_{x,t+1}$$

$$A_{1} \begin{bmatrix} s_{t+1} \\ E_{t}(c_{t+1}) \end{bmatrix} = \tilde{A}_{2} \begin{bmatrix} s_{t} \\ c_{t} \end{bmatrix} + \tilde{A}_{3}x_{t} + \tilde{A}_{4}\Lambda_{t} + B\xi_{t} + O(\epsilon_{APPR}^{3})$$
$$x_{t} = Nx_{t-1} + \varepsilon_{t}$$
$$\Lambda_{t} = vech \begin{bmatrix} x_{t} \\ s_{t} \\ c_{t} \end{bmatrix} \begin{bmatrix} x_{t} & s_{t} & c_{t} \end{bmatrix}$$

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$$\begin{aligned} (\hat{C} - \hat{C}^*) &= [\tilde{D}_0] + [\tilde{D}_2]_j [\varepsilon]^i + [\tilde{D}_3]_k [z]^k \\ \bullet &+ [\tilde{D}_4]_{i,j} [\varepsilon]^i [\varepsilon]^j + \begin{pmatrix} [\tilde{D}_5]_{k,i} \\ + [\tilde{D}_1] [\tilde{R}_2]_i [\gamma]_k \end{pmatrix} [\varepsilon]^i [z]^k (5) \\ &+ [\tilde{D}_6]_{i,j} [z]^i [z]^j + O (\epsilon^3_{APPR}) \end{aligned}$$



 Now extract equations from state-space solution and use result that excess return on portfolio time-variation ξ_t = â_t î_{x,t+1}:

$$\begin{aligned} & (\hat{C} - \hat{C}^{*}) = [\tilde{D}_{0}] + [\tilde{D}_{2}]_{j} [\varepsilon]^{i} + [\tilde{D}_{3}]_{k} [z]^{k} \\ \bullet & + [\tilde{D}_{4}]_{i,j} [\varepsilon]^{i} [\varepsilon]^{j} + \begin{pmatrix} [\tilde{D}_{5}]_{k,i} \\ + [\tilde{D}_{1}] [\tilde{R}_{2}]_{i} [\gamma]_{k} \end{pmatrix} [\varepsilon]^{i} [z]^{k} (5) \\ & + [\tilde{D}_{6}]_{i,j} [z]^{i} [z]^{j} + O(\varepsilon_{APPR}^{3}) \end{aligned}$$

$$\bullet & \hat{r}_{x} = E [\hat{r}_{x}] - [\tilde{R}_{4}]_{i,j} [\Sigma]^{i,j} + [\tilde{R}_{2}]_{i} [\varepsilon]^{i} + [\tilde{R}_{4}]_{i,j} [\varepsilon]^{i} [\varepsilon]^{j} \\ & + ([\tilde{R}_{5}]_{k,i} + [\tilde{R}_{1}] [R_{\tilde{2}}]_{i} [\gamma]_{k}) [\varepsilon]^{i} [z]^{k} + O(\varepsilon_{APPR}^{3}) \end{aligned}$$
(6)



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$$\hat{C} = [\tilde{C}_{2}^{H}]_{i} [\varepsilon]^{i} + [\tilde{C}_{3}^{H}]_{k} [z]^{k} + O(\varepsilon_{APPR}^{2}) \\
\hat{C}^{*} = [\tilde{C}_{2}^{F}]_{i} [\varepsilon]^{i} + [\tilde{C}_{3}^{F}]_{k} [z]^{k} + O(\varepsilon_{APPR}^{2}) \\
\hat{r}_{1} = [\tilde{R}_{2}^{1}]_{i} [\varepsilon]^{i} + [\tilde{R}_{3}^{1}]_{k} [z]^{k} + O(\varepsilon_{APPR}^{2}) \\
\hat{r}_{2} = [\tilde{R}_{2}^{2}]_{i} [\varepsilon]^{i} + [\tilde{R}_{3}^{2}]_{k} [z]^{k} + O(\varepsilon_{APPR}^{2})$$
(7)

• Combining (5), (6) and (7) and simplifying, we can rewrite and simplify (3) as:



Evaluating the LHS

- Combining (5), (6) and (7) and simplifying, we can rewrite and simplify (3) as: $\begin{bmatrix} \tilde{R}_2 \end{bmatrix}_i \left(\begin{bmatrix} \tilde{D}_5 \end{bmatrix}_{k,j} + \begin{bmatrix} \tilde{D}_1 \end{bmatrix} \begin{bmatrix} \tilde{R}_2 \end{bmatrix}_j \begin{bmatrix} \gamma \end{bmatrix}_k \right) \begin{bmatrix} \Sigma \end{bmatrix}^{i,j} \\ + \begin{bmatrix} \tilde{D}_2 \end{bmatrix}_i \begin{bmatrix} \tilde{R}_5 \end{bmatrix}_{k,i} \begin{bmatrix} \Sigma \end{bmatrix}^{i,j} = O\left(\epsilon_{APPR}^3\right)$



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- Solving for the equilibrium coefficient vector γ :



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 \bullet Solving for the equilibrium coefficient vector γ :

$$\gamma_{k} = -\frac{\left(\left[\tilde{R}_{2}\right]_{i}\left[\tilde{D}_{5}\right]_{k,j}\left[\Sigma\right]^{i,j} + \left[\tilde{D}_{2}\right]_{i}\left[\tilde{R}_{5}\right]_{k,j}\left[\Sigma\right]^{i,j}\right)}{\left[\tilde{D}_{1}\right]\left[\tilde{R}_{2}\right]_{i}\left[\tilde{R}_{2}\right]_{j}\left[\Sigma\right]^{i,j}} + O\left(\epsilon_{APPR}\right) (8)$$

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$$\begin{bmatrix} \tilde{R}_2 \end{bmatrix}_i \left(\begin{bmatrix} \tilde{D}_5 \end{bmatrix}_{k,j} + \begin{bmatrix} \tilde{D}_1 \end{bmatrix} \begin{bmatrix} \tilde{R}_2 \end{bmatrix}_j \begin{bmatrix} \gamma \end{bmatrix}_k \right) \begin{bmatrix} \Sigma \end{bmatrix}^{i,j} \\ + \begin{bmatrix} \tilde{D}_2 \end{bmatrix}_i \begin{bmatrix} \tilde{R}_5 \end{bmatrix}_{k,j} \begin{bmatrix} \Sigma \end{bmatrix}^{i,j} = O\left(\epsilon_{APPR}^3\right)$$

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(8)

 This gives us the first-order effect of state variables on portfolio time variation

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- Next: consider simple and specific example for illustration



• One-good, two-country endowment economy



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- Agents have CRRA preferences:

$$U_t = E_t \sum_{\tau=t}^{\infty} \beta^{\tau-t} \frac{C_t^{1-\rho}}{1-\rho}$$

• Endowments of single good and the money supply follow AR1 processes with iid. and symmetric shocks:

$$\log Y_{t} = \zeta_{Y} \log Y_{t-1} + \varepsilon_{Y,t}$$
$$\log Y_{t}^{*} = \zeta_{Y} \log Y_{t-1}^{*} + \varepsilon_{Y^{*},t}$$
$$\log M_{t} = \zeta_{M} \log M_{t-1} + \varepsilon_{M,t}$$
$$\log M_{t}^{*} = \zeta_{M} \log M_{t-1}^{*} + \varepsilon_{M^{*},t}$$

Time invariant Covariance matrix of Innovations





• Home and foreign nominal bonds are traded: $\alpha_{B,t}$ and $\alpha_{B^*,t}$



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• We also have

$$W_t = \alpha_{B,t} + \alpha_{B^*,t}$$



• FOCs for consumption and bond holdings:



Equilibrium conditions

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$$C_{t}^{-\rho} = \beta E_{t} \left[C_{t+1}^{\rho} r_{B^{*},t+1} \right]$$

$$C_{t}^{*-\rho} = \beta E_{t} \left[C_{t+1}^{*\rho} r_{B^{*},t+1} \right]$$

$$E_{t} \left[C_{t+1}^{-\rho} r_{B,t+1} \right] = E_{t} \left[C_{t+1}^{-\rho} r_{B^{*},t+1} \right]$$

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$$E_{t} \left[C_{t+1}^{*-\rho} r_{B,t+1} \right] = E_{t} \left[C_{t+1}^{*-\rho} r_{B^{*},t+1} \right]$$

• Resource constraint:

$$C_t + C_t^* = Y_t + Y_t^*$$

• Equilibrium bond holdings:

$$\tilde{\alpha}_B = -\tilde{\alpha}_{B^*} = -\frac{\sigma_Y^2}{2(\sigma_M^2 + \sigma_Y^2)(1 - \beta\zeta_Y)}$$

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• Now solve for time variation around eqm. bond holdings



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$$\gamma_{k} = -\frac{\left(\left[\tilde{R}_{2}\right]_{i}\left[\tilde{D}_{5}\right]_{k,j}\left[\Sigma\right]^{i,j} + \left[\tilde{D}_{2}\right]_{i}\left[\tilde{R}_{5}\right]_{k,j}\left[\Sigma\right]^{i,j}\right)}{\left[\tilde{D}_{1}\right]\left[\tilde{R}_{2}\right]_{i}\left[\tilde{R}_{2}\right]_{j}\left[\Sigma\right]^{i,j}} + O\left(\epsilon_{APPR}\right)$$



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 $\hat{\alpha}_{t} = \gamma' \begin{bmatrix} x_{t} \\ s_{t+1} \end{bmatrix} = \gamma' z_{t+1} = [\gamma]_{k}[z_{t+1}]^{k}$

Forming the appropriate matrices

$$\tilde{R}_{2} = \begin{bmatrix} 1 & -1 & -1 & 1 \end{bmatrix}$$

$$\tilde{D}_{1} = \begin{bmatrix} 2(1-\beta) \end{bmatrix}$$

$$\tilde{R}_{5} = \mathbf{0}$$

$$\tilde{D}_{5} = \begin{bmatrix} \Delta_{2} & -\Delta_{1} & -\Delta_{1} & \Delta_{1} \\ \Delta_{1} & -\Delta_{2} & -\Delta_{1} & \Delta_{1} \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ \Delta_{3} & \Delta_{3} + 2(1-\beta) & 0 & -2(1-\beta) \end{bmatrix}$$

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$$\begin{split} \Delta_{1} &= -\frac{1-\beta}{1-\beta\zeta_{Y}}\tilde{\alpha}_{B}\left\{\left(1-\zeta_{Y}\right)\rho\left[1-\zeta_{Y}\left(1-\beta\right)\beta\right]+\zeta_{Y}\left(1-\beta\right)\right\}\\ \Delta_{2} &= -\frac{1-\beta}{1-\beta\zeta_{Y}}\frac{\beta\left(1-\zeta_{Y}\right)^{2}\zeta_{Y}\left(1-\beta\rho\right)}{\left(1-\beta\zeta_{Y}\right)\left(1-\beta\zeta_{Y}^{2}\right)}+\Delta_{1}\\ \Delta_{3} &= -\frac{1-\beta}{1-\beta\zeta_{Y}}\frac{1-\beta\left[1-\left(1-\zeta_{Y}\right)\beta\rho\right]}{\beta} \end{split}$$

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Solutions for time variations in bond holdings

$$\hat{\alpha}_{B,t} = \gamma_1 Y_t + \gamma_2 Y_t^* + \gamma_3 M_t + \gamma_4 M_t^* + \gamma_5 \hat{W}_t \hat{\alpha}_{B^*,t} = -\gamma_1 Y_t - \gamma_2 Y_t^* - \gamma_3 M_t - \gamma_4 M_t^* + (1 - \gamma_5) \hat{W}_t$$



Solutions for time variations in bond holdings

$$\hat{\alpha}_{B,t} = \gamma_1 Y_t + \gamma_2 Y_t^* + \gamma_3 M_t + \gamma_4 M_t^* + \gamma_5 \hat{W}_t$$
$$\hat{\alpha}_{B^*,t} = -\gamma_1 Y_t - \gamma_2 Y_t^* - \gamma_3 M_t - \gamma_4 M_t^* + (1 - \gamma_5) \hat{W}_t$$

where the vector of coefficients:



Solutions for time variations in bond holdings

$$\begin{split} \hat{\alpha}_{B,t} &= \gamma_{1}Y_{t} + \gamma_{2}Y_{t}^{*} + \gamma_{3}M_{t} + \gamma_{4}M_{t}^{*} + \gamma_{5}\hat{W}_{t} \\ \hat{\alpha}_{B^{*},t} &= -\gamma_{1}Y_{t} - \gamma_{2}Y_{t}^{*} - \gamma_{3}M_{t} - \gamma_{4}M_{t}^{*} + (1 - \gamma_{5})\,\hat{W}_{t} \\ \bullet \text{ where the vector of coefficients:} \\ \gamma_{1} &= \gamma_{2} = \frac{1}{2}\left(1 - \frac{(1 - \zeta_{Y})\left[1 - \rho + (1 - \beta)\,\beta\rho\zeta_{Y}^{2}\right]}{1 - \beta\zeta_{Y}}\right)\tilde{\alpha}_{B} \\ \zeta_{3} &= \gamma_{4} = 0 \\ \gamma_{5} &= \frac{1}{2} \end{split}$$

Image: Image:



• Paper extends Devereux and Sutherland (2006) solution method for equilibrium portfolios to higher order approximations



- Paper extends Devereux and Sutherland (2006) solution method for equilibrium portfolios to higher order approximations
- Finds analytical expressions for dynamic behavior of portfolios in open economy GE models



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- Provides simple and clear insights into factors determining the dynamic evolution of portfolios

