# Local Correction of Juntas

Noga  $Alon^1$ 

Sackler School of Mathematics and Blavatnik School of Computer Science, Tel Aviv University, Tel Aviv 69978, Israel and Institute for Advanced Study, Princeton, New Jersey 08540, USA.

Amit Weinstein<sup>2</sup>

Blavatnik School of Computer Science, Tel Aviv University, Tel Aviv 69978, Israel.

### Abstract

A Boolean function f over n variables is said to be q-locally correctable if, given a black-box access to a function g which is "close" to an isomorphism  $f_{\sigma}$  of f, we can compute  $f_{\sigma}(x)$  for any  $x \in \mathbb{Z}_2^n$  with good probability using q queries to g.

We observe that any k-junta, that is, any function which depends only on k of its input variables, is  $O(2^k)$ -locally correctable. Moreover, we show that there are examples where this is essentially best possible, and locally correcting some k-juntas requires a number of queries which is exponential in k. These examples, however, are far from being typical, and indeed we prove that for almost every k-junta,  $O(k \log k)$  queries suffice.

Keywords:

local correction, locally correctable codes

## 1. Introduction

The field of property testing of Boolean functions received a considerable amount of attention in the last two decades. Many properties of functions have been examined in order to estimate what is the needed query complexity for testing them, that is, the number of inputs of the function one has to read in order to distinguish between a function that satisfies the property and one that is "far" from satisfying it. In particular, one is usually interested in properties for which the number of queries is independent of the input size. Some of these

Preprint submitted to Information Processing Letters

Email addresses: nogaa@tau.ac.il (Noga Alon), amitw@tau.ac.il (Amit Weinstein)

 $<sup>^1\</sup>mathrm{Research}$  supported in part by an ERC Advanced grant, by a USA-Israeli BSF grant and by NSF grant No. DMS-0835373.

<sup>&</sup>lt;sup>2</sup>Research supported in part by an ERC Advanced grant.

properties are linearity [7], being a dictator function [4, 11], a junta [9, 10], or a low-degree polynomial [2].

Another property that one might consider testing is functions isomorphism, i.e. testing if two functions are identical up to relabeling of the input variables. A common scenario is where one function is given in advance and the goal of the tester is to determine if the second input function is isomorphic to it or far from any isomorphism of it. Several recent results indicate that testing this property is hard for most functions (requires  $\Omega(n)$  queries), and specifically for k-juntas there are lower bounds which depend on k (see e.g. [6, 1, 8]).

The focus of our work is not testing such properties, but rather locally correcting functions, that is, determining the value of a function in a given point by reading its values in several other points. This is closely related to random self reducibility, as pointed out already in [7]. More precisely, we care about locally correcting specific functions which are known up to isomorphism.

**Question.** Given a specific Boolean function f, what is the needed query complexity in order to correct an input function which is close to some isomorphism  $f_{\sigma}$  of f?

This question can be seen as a special case of locally correctable codes (see, e.g., [12]). Namely, each codeword would be the  $2^n$  evaluations of an isomorphism of the input function (at most n! distinct codewords) and we would like to correct any specific value of the given noisy codeword using as few queries as possible.

Here we study the above question mostly for juntas. We provide both lower and upper exponential bounds for the query complexity of locally correcting juntas with respect to their size. However, the given lower bound is applicable only to a small portion of the juntas and in fact we show that most k-juntas are locally correctable using a nearly linear (in k) number of queries.

### 1.1. Preliminaries

In order to correct functions, we need to first define when two functions are "close", as otherwise correction is hopeless. We use the common definition, saying two Boolean functions are  $\varepsilon$ -close if they agree on all but at most an  $\varepsilon$  fraction of the inputs. The following definition best describes the focus of our work, indicating when a function is locally correctable.

**Definition.** A Boolean function  $f : \mathbb{Z}_2^n \mapsto \mathbb{Z}_2$  is said to be q-locally correctable for  $\varepsilon > 0$  if the following holds. There exists an algorithm that given an input function g which is  $\varepsilon$ -close to an isomorphism  $f_{\sigma}$  of f, can determine the value  $f_{\sigma}(x)$  for any specific  $x \in \mathbb{Z}_2^n$  with probability at least 2/3, using q queries to g.

More generally, we also define a family of functions to be locally correctable when we do not require to know which specific function from the family we are trying to correct.

**Definition.** A family  $\mathcal{F}$  of Boolean functions is said to be q-locally correctable for  $\varepsilon > 0$  if the following holds. There exists an algorithm that given an input

function g which is  $\varepsilon$ -close to an isomorphism  $f_{\sigma}$  of f, for some  $f \in \mathcal{F}$  from the family, can determine the value  $f_{\sigma}(x)$  for any specific  $x \in \mathbb{Z}_2^n$  with probability at least 2/3, using q queries to g.

A crucial observation when looking at the above definitions is the fact that the mentioned algorithm must hold for *every* input  $x \in \mathbb{Z}_2^n$ . Replacing this requirement by the ability to determine the value at a uniform random x, any function would be trivially 1-locally correctable for  $\varepsilon \leq 1/3$  as at least 2/3 of the inputs remain unmodified. In addition, it is useful to think of  $\varepsilon$  as a constant independent of n, which however can depend on some property of the function f. This dependence is often required to ensure that g is close to a unique isomorphism of f (up to equivalent isomorphisms).

A simple result regarding juntas is an exponential upper bound for the number of queries, in terms of the junta's size. For this upper bound, we use the analysis of testing low-degree polynomials and therefore get the following more general bound.

**Proposition 1.** Every polynomial of degree k is  $O(2^k)$ -locally correctable for  $\varepsilon < 2^{-k-3}$ .

*Proof sketch.* The techniques used in testing low-degree polynomials rely on their values on the points of random affine subcubes inside  $\mathbb{Z}_2^n$  which are defined by random bases of k + 1 vectors and an offset in  $\mathbb{Z}_2^n$  (see [2]). Taking such a subcube and evaluating the sum of a degree k polynomial on all  $2^{k+1}$  elements of it, always results in zero. The test itself selects several such random subcubes and verifies that this is indeed the case. Since in our case, we are given some specific input  $x \in \mathbb{Z}_2^n$  for which we want to correct the function, we can use a similar argument.

Given the input x, we randomly select k + 1 vectors  $x_1, x_2, \ldots, x_{k+1}$  and consider the affine subcube whose basis is the set of these k + 1 vectors and whose offset is x. Since the sum of evaluations inside this affine subcube (which includes x) is zero, we can deduce the value at x by querying the other  $2^{k+1} - 1$ locations of the cube, assuming none of them was modified. Since we select the k+1 vectors in the basis randomly, relying on the (easy case in the) analysis of [2] which is based on the fact that each input queried is uniformly random, we can bound this probability by  $(2^{k+1} - 1)\varepsilon < 1/4$  and therefore this algorithm indicates that f is indeed  $O(2^k)$ -locally correctable for  $\varepsilon < 2^{-k-3}$ .

**Corollary 2.** The family of k-juntas is  $O(2^k)$ -locally correctable for  $\varepsilon < 2^{-k-3}$ .

*Proof.* A k-junta is in particular a polynomial of degree k and therefore is also  $O(2^k)$ -locally correctable using the above proposition. In addition, the algorithm suggested by the proposition does not require any knowledge about the input function except for it being a polynomial of degree k, thus the family of k-juntas is  $O(2^k)$ -locally correctable.

## 1.2. Our results

A natural question is whether the exponential upper bound for low-degree polynomials, which is applicable also for juntas, is indeed tight in the case of juntas. We show that the answer is indeed positive, but only for a small fraction of the juntas. In other words, for some juntas the exponential upper bound is also best possible but this is far from being the typical case.

**Theorem 3.** There exist some k-juntas which require  $2^{\Omega(k)}$  (adaptive or nonadaptive) queries in order to be locally corrected, even for  $\varepsilon$  which is exponentially small in n.

In the typical case, however, i.e., for almost every junta, the lower bound above is far from being tight and in fact one can correct a typical k-junta using a nearly linear number of queries (in k). Formally, we prove the following.

**Theorem 4.** A k-junta in which every influencing variable has influence of at least 1/50 is  $O(k \log k)$ -locally correctable for  $\varepsilon < 2^{-k-3}$ . Therefore this is the case for almost every k-junta.

**Corollary 5.** The family of k-juntas in which every influencing variable has influence of at least 1/50 is  $O(k \log k)$ -locally correctable for  $\varepsilon < 2^{-k-3}$ .

#### 2. Local correction of k-juntas

We start this section with the proof of the lower bound for some juntas. The juntas used in the proof are very sparse, having an exponentially small fraction of inputs for which the value of the function is 1.

Proof of Theorem 3. Given  $k < n \in \mathbb{N}$  where n is even, define f to be the AND function of the first k literals  $x_1, \ldots, x_k$ . In order to prove a lower bound for the number of queries, we use Yao's principle. To this end, we define two distributions on functions which are all o(1)-close to being isomorphic to f, one for which the algorithm should return zero and another for which the algorithm should return one (denoted by  $\mathcal{D}_0$  and  $\mathcal{D}_1$  respectively). We further show that any algorithm that performs only  $2^{o(k)}$  queries would not be able to distinguish between the two distributions with non-negligible probability.

We first describe the distribution  $\mathcal{D}_0$  as follows. We randomly choose a permutation  $\sigma \in S_n$  so that  $\sigma(i) \in [n/2]$  for every  $i \in [k]$ , meaning the k relevant variables are all in the first half.<sup>3</sup> The function g given to the algorithm is defined by  $g(y) = f_{\sigma}(y)$  whenever the Hamming weight of y is at most 0.3n in each half (i.e.  $\sum_{i=1}^{n/2} y_i \leq 0.3n$  and  $\sum_{i=n/2+1}^n y_i \leq 0.3n$ ) and otherwise g(y) = 0. Notice that indeed g is o(1)-close to being isomorphic to f as we modified only an o(1)-fraction of the inputs. The input x is set to be the balanced input of

<sup>&</sup>lt;sup>3</sup>Throughout this work we use the notation  $[\ell] := \{1, 2, \dots, \ell\}.$ 

n/2 zeros followed by n/2 ones. Clearly  $f_{\sigma}(x) = 0$  for every instance in  $\mathcal{D}_0$  as required.

The distribution  $\mathcal{D}_1$  is similar to  $\mathcal{D}_0$  with one modification. The permutation  $\sigma$  is chosen so that  $\sigma(i) \notin [n/2]$  for every  $i \in [k]$ . The choice of x and the locations where we fix g(y) = 0 are defined as before and indeed  $f_{\sigma}(x) = 1$  for every instance in  $\mathcal{D}_1$ .

We first show that an arbitrary query to g in either distribution would output one with probability at most  $2^{-\Omega(k)}$ . Let y be some query the algorithm performs. Clearly, if the Hamming weight of y in either half is more than 0.3n, the result would be zero according to the definition of g in both distributions. Otherwise, the probability that g(y) = 1 is given by

$$\binom{m}{k} / \binom{n/2}{k} = \frac{(m-k+1)(m-k+2)\cdots m}{(n/2-k+1)(n/2-k+2)\cdots (n/2)} \le \left(\frac{3n/10}{n/2}\right)^k = 0.6^k$$

where m is the Hamming weight of y in the relevant half (either the first half for  $\mathcal{D}_0$  or the second half for  $\mathcal{D}_1$ ), which is known to be at most 0.3n. Therefore, any algorithm that performs at most  $2^{o(k)}$  queries would find a y for which g(y) = 1 only with negligible probability, and it would not be able to distinguish between  $\mathcal{D}_0$  and  $\mathcal{D}_1$  with noticeable probability. Notice that the proof implies that using an adaptive algorithm would not yield any improvement as we can predict all results to be zero in advance (and therefore this is equivalent to a non-adaptive algorithm).

The fact that the AND junta is very sparse was crucial for the above proof. In order to prove a better upper bound for most juntas, we need some restriction that would ensure the function is far from being sparse. In Theorem 4 we required something even stronger, that the influence of every influencing variable, that is, any of the k special variables of the junta, is at least 1/50.

**Definition 1** (Influence). Given a Boolean function  $f : \mathbb{Z}_2^n \to \mathbb{Z}_2$ , the influence of *i* with respect to *f* is defined by

$$\operatorname{Inf}_{i}(f) = \Pr_{T} \left[ f(x) \neq f(x + e_{i}) \right]$$

where  $e_i$  is the vector having 1 only at location i.

Thus, the influence is the probability that changing the value of the *i*th variable will also change the value of the function. This probability is taken over all values of x, and is therefore the expected influence of i in a restricted function (when the variable i itself is not restricted). Moreover, if the influence of some variable i is greater than 1/50, then the function is 1/100-far from being a constant.

Given a random k-junta for which the influencing variables are the first k variables, the influence of some variable  $1 \le i \le k$  is determined by the bias of the  $2^{k-1}$  pairs of inputs of length k which differ only in the *i*th variable, where

the values of all other variables in [k] range over all possibilities. The expected bias is hence 1/2, and moreover

$$\Pr[\mathrm{Inf}_i(f) < 1/50] = \Pr[B(2^{k-1}, 1/2) < 2^{k-1}/50] < 2^{-c2^k}$$

for some absolute constant c > 0, where here B is the binomial distribution and we applied one of the standard estimates for binomial distributions (c.f., e.g. [3], Appendix A). Therefore, by the union bound, the k influencing variables would all have influence greater than 1/50 with probability  $1 - 2^{-\Omega(2^k)}$ .

Now that we defined the influence of a variable and verified that indeed almost every junta satisfies the condition in the theorem, we describe the proof of Theorem 4.

Proof of Theorem 4. Let f be a k-junta as in Theorem 4, and let g be the given input function which is  $\varepsilon$ -close to  $f_{\sigma}$  (we assume  $\varepsilon < 2^{-k-3}$  in order to guarantee that g is close to a unique isomorphism  $f_{\sigma}$ ). Following the basic approach in the known junta testing algorithms (see e.g. [10, 5]), we intend to randomly divide the variables into parts and identify which sets have influencing variables. Here however, mistakenly identifying a set to have influencing variables (due to fault evaluations of the input function) or having more than one such variable in a part is not an essential issue (as estimating the number of influencing variables is not our goal).

Fix s = 3k and partition the set [n] into s parts uniformly at random, by assigning to each variable one of the s sets independently. For each set we perform  $r = 100 \log k + 500$  pairs of queries, where each pair (x, x') is chosen independently and uniformly at random such that x and x' agree on all elements outside of the current set. When a set has at least one influencing variable (with influence at least 1/50), each such pair would yield different outcomes with probability at least 1/100 (as the randomly restricted function over the variables outside of the current set is expected to be at least 1/100-far from being a constant). Therefore, the probability we would dismiss such a set is at most  $0.99^r < 0.5^{\log k} \cdot 0.99^{500} < 1/100k$  (assuming we did not hit a faulty evaluation - a probability that we later consider). Since there are at most k sets with influencing variables, by the union bound we would identify them all with probability at least 99/100.

In order to estimate how many sets we would consider as influencing, we compute the probability that a non-influencing set would mistakenly be considered otherwise. This can only occur if we query the function at a faulty input, which happens with probability  $\varepsilon$ . During this process, we perform only  $sr = O(k \log k)$  pairs of independent non-adaptive queries and therefore we would hit a faulty evaluation only with probability  $O(k \log k/2^k) = 2^{-\Omega(k)}$ .

So far with good probability we have identified at most k sets which are influencing. Let  $S_1, \ldots, S_k$  denote these k sets (where we add some arbitrary randomly chosen sets if less than k were found) and define  $S = \bigcup_{i=1}^k S_i$  to be their union (notice that the size of S is expected to be  $\mathbf{E}[|S|] = n/3$ ). Given the input x for which we were asked to determine  $f_{\sigma}(x)$ , we would like to choose an input y which agrees with x on all indices from S, and yet is uniformly distributed (except for the restriction to match x on the k influencing variables). Achieving this would guarantee that the probability of y hitting a faulty evaluation is at most  $2^{k+1}/2^{k+3} = 1/4$  (even if all faulty evaluations fall into inputs which agree with x on these k variables).

Let p = 3/4 and define y so that  $y_i = x_i$  for every  $i \in S$ , and otherwise  $\Pr[y_i \neq x_i] = p$ . Whenever i is not one of the special k variables,  $\Pr[y_i \neq x_i] = \Pr[i \notin S] \cdot p = \frac{2}{3} \cdot \frac{3}{4} = \frac{1}{2}$  and these probabilities are all independent. The independence between the different variables and the fact that  $\Pr[i \notin S]$  is exactly 2/3 are crucial points which require a moment of reflection to verify. This implies that indeed y is uniformly distributed over all inputs which agree with x on the special k variables, as required.

Combining the two parts together, the algorithm would return the correct answer  $g(y) = f_{\sigma}(x)$  with probability at least  $3/4 - 1/100 - 2^{-\Omega(k)} > 2/3$  (for large enough k).

Proof of Corollary 5. The algorithm provided here did not use any specific knowledge of the function f except for the guarantee of its structure, being a k-junta in which each influencing variable has influence at least 1/50. Therefore, this family is  $O(k \log k)$ -locally correctable for  $\varepsilon < 2^{-k-3}$ . Hence, for every fixed kthis family forms a locally correctable code which has polynomial size in n and constant number of queries  $O(k \log k)$ .

#### 3. Conclusions and open problems

In this work we have shown that k-juntas and degree k polynomials are q-locally correctable, where q depends on the structure parameter k of the function, and not on the number of variables n. We have also seen that q is always at most  $O(2^k)$  and that sometimes an exponential behavior is tight. The main general open question in this subject is that of computing the query complexity of local correction for any given function. In particular, it would be very interesting to find a characterization of all functions that are "easily" correctable, that is, have constant query complexity (independent of n).

Although we have seen both upper and lower bounds for juntas and polynomials, the lower bound is only applicable for specific functions. Symmetric functions, for example, are always 0-locally correctable as one does not need to query the function at all in order to correct an input. However, such functions can have arbitrary large degree as polynomials. Taking the majority function as an example, it is trivial to correct and yet it has high degree, but even a slight modification of it,  $Maj_{n-1}$  - the majority of n-1 of the variables, makes it hard for correcting. Given  $Maj_{n-1}$ , one can modify o(1) fraction of the inputs, namely the balanced layer, and make this function impossible for correcting in any number of queries.

 N. Alon and E. Blais, *Testing boolean function isomorphism*. In Proc. RANDOM-APPROX, pages 394-405, 2010.

- [2] N. Alon, T. Kaufman, M. Krivelevich, S. Litsyn and D. Ron, *Testing low-degree polynomials over GF(2)*. Proceedings of RANDOM-APPROX 2003, 188-199. Also: Testing Reed-Muller codes, IEEE Transactions on Information Theory 51 (2005), 4032-4039.
- [3] N. Alon and J. Spencer, The Probabilistic Method, Third Edition, Wiley 2008.
- [4] M. Bellare, O. Goldreich, and M. Sudan, Free bits, PCPs and nonapproximability - towards tight results. SIAM J. Comput., 27(3):804-915, 1998.
- [5] E. Blais, *Testing juntas nearly optimally*. Proceedings of the 41st annual ACM STOC, 2009, pp. 151-158.
- [6] E. Blais and R. O'Donnell, Lower bounds for testing function isomorphism. In IEEE Conference on Computational Complexity, pages 235-246, 2010.
- [7] M. Blum, M. Luby, and R. Rubinfeld, Self-testing/correcting with applications to numerical problems. Journal of Computer and System Sciences, 47(3):549-595, 1993.
- [8] S. Chakraborty, D. García-Soriano, and A. Matsliah, Nearly tight bounds for testing function isomorphism. In Proc. SODA, pages 1683-1702, 2011.
- [9] H. Chockler and D. Gutfreund, A lower bound for testing juntas. Information Processing Letters, 90(6):301-305, 2004.
- [10] E. Fischer, G. Kindler, D. Ron, S. Safra, and A. Samorodnitsky, *Testing juntas.* J. Comput. Syst. Sci., 68(4):753-787, 2004.
- [11] M. Parnas, D. Ron, and A. Samorodnitsky, *Testing basic boolean formulae*. SIAM J. Discrete Math., 16(1):20-46, 2002.
- [12] S. Yekhanin, *Locally decodable codes*, NOW Publishers, 2010.