Randomly charged polymers, random walks, and their extremal properties

Deniz Ertaş¹,* and Yacov Kantor²
¹Department of Physics, Massachusetts Institute of Technology, Cambridge, Massachusetts 02139
²School of Physics and Astronomy, Tel Aviv University, Tel Aviv 69978, Israel
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Motivated by an investigation of ground state properties of randomly charged polymers, we discuss the size distribution of the largest Q-segments (segments with total charge Q) in such polymers with N monomers (N-mers). Upon mapping the charge sequence to one-dimensional random walks (RWs), this corresponds to finding the probability for the largest segment with total displacement Q in an N-step RW to have length L. Using analytical, exact enumeration, and Monte Carlo methods, we reveal the complex structure of the probability distribution in the large N limit. In particular, the size of the longest neutral segment has a distribution with a square-root singularity at β = L/N = 1, an essential singularity at β = 0, and a discontinuous derivative at β = 1/2. The behavior near β = 1 is related to another interesting RW problem, which we call the "staircase problem." We also discuss the generalized problem for d-dimensional RWs.

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I. INTRODUCTION

The importance of understanding proteins [1] has attracted much attention to the statistical mechanics of heterogeneous polymers. A particular type of heteropolymers built with a random mixture of positively and negatively charged groups along their backbone are called polyanions (PA's). The presence of long-range electrostatic interactions causes a rather unique behavior in such polymers: the behavior of a single PA with unscreened electrostatic interactions at a low temperature T is extremely sensitive to its total (excess) charge Q₀.

Geometrical properties of polymers can be conveniently described by their radius of gyration (root-mean-squared size) R_g [2]. At high T, the effect of electrostatic interactions is small and R_g is approximately equal to that of an uncharged polymer. However, upon lowering of T the PA attempts to take advantage of the presence of two types of charges along its backbone by assuming spatial conformations in which every charge is predominantly surrounded by charges of an opposite sign. This behavior can be approximately described using a Debye–Hückel-type theory [3], which leads to the conclusion that at low T the polymer should collapse into a dense state with condensation energy E_{cond} = -Nq₀²/a, where N is the number of monomers, q₀ is the typical charge of a monomer, and a is a microscopic distance such as diameter of the monomer. In such a collapsed state, R_g \sim N^{1/3}. On the other hand, renormalization group inspired scaling arguments showed [4] that at low T one should expect a strongly stretched state with R_g \sim N. This apparent contradiction was resolved by noting [5] that the low-T behavior is extremely sensitive to the overall charge Q₀:

It has been observed [5] that randomly charged PA's with vanishing Q₀ indeed collapse at low T, while R_g, which is averaged over unrestricted quenches, grows with decreasing T. Such sensitivity is consistent with experimental observations of PA's [6].

From a detailed study of the Q₀ dependence of R_g, the following picture began emerging [7,8]: Consider a dense (globular, approximately spherical) low-T state of the PA. Its energy can be roughly separated into three terms, such as

\[ E = -Nq₀²/a + \gamma S + Q₀²/R_g. \]  

(In this description we omit the dimensionless prefactors of order unity.) The first term in this equation represents the Debye–Hückel-type condensation energy, the second term is the surface energy (where the surface tension \( \gamma \approx q₀²/a³ \)), and the surface area \( S \approx a²N²/3 \), while the last term is the electrostatic energy of the globule of radius \( R_g \approx aN^{1/3} \). For vanishing Q₀, the globule remains approximately spherical. However, when \( Q₀ > Q_R \approx q₀N^{1/2} \), the electrostatic term exceeds the surface tension term, the spherical shape becomes unstable and the polymer starts to stretch in order to minimize the electrostatic energy. Since the threshold charge \( Q_R \) increases with N exactly as the standard deviation of the total charge Q₀ in a random sequence of charges, for any N there will be a finite portion of chains with Q₀ exceeding \( Q_R \). (Note that this property is specific to three-dimensional electrostatic interactions. For the N dependence of \( Q_R \) in general space dimensions, see Ref. [8].)

While the above arguments suggest that a typical PA should stretch out at low T, such stretching may lead to a loss of the condensation energy. A reasonable compromise between stretching (which minimizes the electrostatic energy) and remaining compact (which gains in
condensation energy) is for the PA to form a necklace
of weakly charged blobs connected with highly charged
"necks," by taking advantage of the charge fluctuations
along the chain. The results of the Monte Carlo [7] and
exact enumeration [8] studies qualitatively support such
a picture. An example of such a low-energy configuration
is shown in Fig. 1.

While the exact treatment of electrostatic interactions
is not possible, we can pose a simplified problem which,
we hope, captures some essential features of this necklace
model. For example, we may ask what the typical size
of the largest neutral (or weakly charged) segment in a
random sequence of \( N \) charges will be. In order to an-
swer this question, we investigated the size distribution
of the largest \( Q \)-segments (segments with a total charge
\( Q \)) in such \( N \) monomers (\( N \)-mers). This problem can be
mapped to a one-dimensional random walk (RW): the se-
quence of charges \( \{q_i\} (i = 1, \ldots, N; q_i = \pm 1) \) is mapped
into a sequence of unit steps in the positive or negative
directions along an axis. The sequence of charges with
vanishing total charge \( Q_0 \) now corresponds to a RW that
returns to the origin after \( N \) steps, while a neutral seg-
ment inside the sequence of charges corresponds to a loop
inside the RW. Similarly, a segment with charge \( Q \) cor-
responds to a segment (in the corresponding RW) whose
end is displaced by \( Q \) units from its beginning. The pri-
mary objective of this work is to investigate the proba-
bility \( P_N(L, Q) \) that the largest \( Q \)-segment in an \( N \)-step
RW has length \( L \).

There is an apparent simplicity of the formulation of
the problem; i.e., it is similar (and related) to the classi-
cal RW problems [9], such as the problem of first passage
times or the problem of last return to the starting point,
for which probability distributions can be computed ex-
actly by using the method of reflections [10]. However,
the search for the longest segment of the RW, among all
possible starting points, creates a more complicated
problem. In its essence, the problem is more closely related
to the statistics of self-avoiding, rather than regular, ran-
dom walks. This will be clearly seen in Sec. V where a
particularly simple limit of the problem is reduced to a
problem of two interacting walkers (one of which is the
"staircase walker"). The "self-interacting nature" of the
problem can be seen even more clearly in its generaliza-
tions to arbitrary space dimension \( d \), where many analo-
gies between this problem and the self-avoiding walks
exist.

Some of the results presented in this paper have been
briefly reported before [11]. In this work we present a
complete exposition of those results, as well as many
new results related to this problem and its generalized
version. In Sec. II we define the problem accurately and
argue that in the large-\( N \) limit it can be described in
terms of a probability density \( p(\ell, q) \), where \( \ell \equiv L/N \)
and \( q \equiv Q/\sqrt{N} \) are the reduced length and charge,
respectively. This probability density is investigated using
Monte Carlo (MC) and exact enumeration methods, as
well as by analytical arguments. In particular, we show
that the function \( p(\ell, 0) \) has an essential singularity in the
\( \ell \to 0 \) limit, and diverges as \( 1/\sqrt{(1 - \ell)} \) in the limit
\( \ell \to 1 \). These properties can be easily understood from
qualitative arguments presented in Sec. III. In Sec. IV
we construct an exact integral expression that enables an
analytic investigation of certain properties of \( p(\ell, q) \). In
Sec. V we show that our problem is related to a different
problem of two random walkers (which we call the "stair-
case problem"). This relation enables us to use the latter
problem to investigate the behavior of \( p(\ell, 0) \) in the limit
\( \ell \to 1 \). While some of the properties of \( p(\ell, q) \) can be
deduced analytically, we had to complement our results
by MC and exact enumeration studies, which appear in
almost every section of the paper along with analytical
arguments on the subject.

FIG. 1. Low-\( T \) configuration of a polyampholyte, which
resembles a necklace made up of weakly charged beads and
a highly charged string. Dark and light spheres denote
monomers of opposite charge.

FIG. 2. Example of a RS \( \omega \), and the corresponding RW
depicted by \( S_\ell(\omega) \). In this case, the longest 0-segments have
lengths \( L = 18 \) (dotted lines), while the longest 4-segments
(dot-dashed lines) have lengths \( L = 22 \). There are no 8-seg-
ments.
An additional insight into the problem can be gained by considering its generalization to \(d\)-dimensional RW's. (This generalization is not related to the original problem of PAs or to their embedding dimension.) In this generalization, which is described in Sec. VI, \(Q\) is treated as a \(d\)-dimensional vector rather than a scalar. As in the one-dimensional case, \(Q = 0\) corresponds to a loop in the RW. Since the generalized problem investigates the presence of large loops, it is somewhat related to the problem of self-avoiding walks [2], whose behavior is also controlled by self-intersections (i.e., loops). In particular, the probability distribution of the \(Q\)-segments becomes trivial for \(d > 4\), when large loops are virtually absent.

II. EXTREMAL SEGMENTS: DEFINITIONS AND MAIN PROPERTIES

In this section, we present an exact definition of the problem of extremal segments of a one-dimensional sequence and review the qualitative features of the resulting probability distributions.

Consider the set \(\Omega_N\), which contains all \(N\)-element sequences \(\{q_i\} (i = 1, \ldots, N; q_i = \pm 1)\). Here, \(q_i\) physically corresponds to the charge (positive or negative) on the \(i\)th monomer of the \(N\)-mer. Alternatively, it can be thought of as the direction of the \(i\)th step of an \(N\)-step one-dimensional RW. A randomly charged polymer (or, alternatively, RW) can then be represented as a random sequence (RS) \(\omega \in \Omega_N\) picked with equal probability \(2^{-N}\). Figure 2 depicts an example of such a sequence and the corresponding path, where the position \(S_1(\omega) = \sum_{j=1}^{i} q_j\) of the path at index \(i\) gives the accumulated charge from the beginning of the polymer till the \(i\)th monomer. \([S_0(\omega) = 0.]\) In the language of the RW's, \(S_i\) is simply the displacement of the walk from the origin after \(i\) steps. Every segment of the sequence between, say, steps \(i\) and \(j\), has a certain charge \(Q_{ij}(\omega) = S_j(\omega) - S_i(\omega)\). A segment for which \(Q_{ij}(\omega) = Q\) will be called a Q-segment. Given a randomly chosen sequence \(\omega \in \Omega_N\) and a charge \(Q\), let \(P_N(L, Q)\) denote the probability that the largest Q-segment in \(\omega\) has length \(L\). It should be stressed that the definition refers to the largest Q-segment among all possible Q-segments with different starting points that may exist in \(\omega\). For example, the dotted lines in Fig. 2 indicate the longest 0-segments (\(L = 18\)) and the dot-dashed lines show the longest 4-segments (\(L = 22\)) in a sequence with \(N = 24\) [12]. Clearly, the longest Q-segment does not have to be unique. If there is at least one Q-segment in the sequence then its length \(L\) satisfies \(0 \leq L \leq N\). From the definitions is clear that the 0-segment is always present and therefore \(\sum_{L=0}^{N} P_N(L, 0) = 1\). However, the set of Q-segments in a given sequence may be empty \(\Pr[|Q| = 0]\) (Fig. 2).

Most properties of RS's have simple continuum limits. We demonstrate this in Secs. III and V by discussing RW problems that are exactly solvable, and relating them to the behavior of \(P_N(L, Q)\) in certain limits. Thus, we also expect \(P_N(L, Q)\) to approach a similar scaling form when \(N, L, Q \to \infty\), while the reduced length \(\ell \equiv L/N\) and the reduced charge \(q \equiv Q/\sqrt{N}\) are kept constant. In this continuum limit, it is more convenient to work with the probability density

\[
p(\ell, q) \equiv \frac{N}{2} [P_N(L, Q) + P_N(L + 1, Q)].
\]

Of course, for small \(N\), this definition of \(p(\ell, q)\) will still depend on \(N\). We expect it to become a function only of the reduced variables in the \(N, L, Q \to \infty\) limit. Note that at least one term in the square brackets of Eq. (2) vanishes since \(P_N(L, Q) = 0\) for odd \(L + Q\). To prevent even-odd oscillations, we included two terms in the definition of \(p\), as in the definitions that are used in continuum limits of discrete RW's.

We have initially examined the behavior of \(P_N(L, Q)\) using numerical (exact enumeration and Monte Carlo) methods, details of which are given in the Appendix. Monte Carlo results obtained for a variety of large \(N\)'s up to \(N = 10^4\) were virtually indistinguishable from each other when plotted in the properly scaled variables. The results for \(N = 1000\) are depicted as a solid curve in each one of the graphs in Fig. 3. For that particular value of \(N\) we evaluated the probability density from \(10^8\) randomly selected sequences. For short chains (up to \(N = 36\)) it was possible to perform a complete enumeration and get the exact results for \(P_N(L, Q)\). When these exact results are plotted in the scaled form, as presented in Fig. 3, we can see that even for such modest values of \(N\), there is an extremely fast convergence to the continuum distribution \(p(\ell, 0)\), depicted by the solid curve (especially for \(\ell > 0.5\)).

The probability density \(p(\ell, 0)\) shown in Fig. 3 has several remarkable properties.

(a) MC results show that \(p\) at \(\ell = 1/2\) is very close to unity (0.1004 ± 0.006). At that point the slope of the

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**FIG. 3.** Probability density of largest neutral segments as a function of reduced length \(\ell = L/N\). Symbols depict exact enumeration results for \(N\) up to 36. In each graph, the solid line shows the MC evaluation of \(p(\ell, 0)\) from \(10^8\) randomly selected sequences of length \(N = 1000\).
curve changes by an order of magnitude. While it is impossible to ascertain from the numerical results that there is actually a discontinuity in the first derivative of $p(\ell,0)$ with respect to $\ell$, both the MC results and analytical arguments indicate that $\ell = \frac{1}{2}$ is a very special point of the curve.

(b) For $\ell \to 0$, the function exhibits an essential singularity of the form

$$p(\ell) \sim \ell^{-x} \exp(-B/\ell), \quad \ell \ll 1,$$

where $B \approx 1.7$ and $x \approx 2$. The estimates of the coefficient $B$ and of the exponent $x$ have been obtained from the MC data. However, in the $\ell \to 0$ limit we are dealing with almost vanishing probabilities, and therefore the statistical accuracy is small. Thus the estimates depend on the precise range of $\ell$'s for which the fit is performed. Nevertheless, the existence of the singularity can be easily understood from the fact that for small $\ell$ the absence of large loops in the entire chain can be thought of as a requirement that such loops are absent in many separate and independent segments of the sequence. In Sec. III this argument will be discussed in detail.

(c) For $\ell \to 1$, $p(\ell,0)$ diverges as $A/\sqrt{\pi(1-\ell)}$, with $A = 1.208 \pm 0.005$. This estimate of the constant $A$ has been obtained from MC results for the $N = 1000$ sequence. In Sec. IV we prove the existence of the square-root singularity from an integral relation that is derived for $p(\ell, q)$. The proof, however, does not provide a value for the prefactor $A$, and we are limited to MC estimates, as well as results extracted from exact enumeration studies that will be presented in Sec. IV. (The accumulated evidence of MC and exact enumeration shows that $A$ is definitely larger than 1.) Some more intuitive, although less rigorous, results regarding the $\ell \to 0$ and $\ell \to 1$ limits are presented in Sec. III. The exact enumeration results depicted in Fig. 3 are not suitable for extraction of asymptotic behavior, since the $N$'s are too small in Sec. IV we show that it is possible to exactly calculate $P_N(L = N - M, Q)$ for small $M$ (i.e., $M = 0, 2, 4$) and arbitrary sequence length $N$. In principle, the correct behavior of $p(\ell,0)$ in the $\ell \to 1$ limit can be deduced from the exact values of $P_N(L = N - M, 0)$ only if the limit $N, M \to \infty$ (while keeping $M/N = 1 - \ell$ constant) is taken before the $\ell \to 1$ limit. Somewhat surprisingly, if we attempt to match the asymptotic form of $p(\ell,0)$ near $\ell = 1$ with $P_N(L,0)$ for $L = N - 2$, we find $A = 1$, i.e., we reproduce almost the exact value of the prefactor. Thus, the discrete distribution approaches its asymptotic (continuum) form within a few steps of the extreme $L = N$.

At this point we would like to remark on a possible relation between our problem and the problem of “randomly broken objects” [13,14]. It is particularly worthwhile noting the similarity between the plots in Fig. 3 and the results displayed in Fig. 1(a) in the work by Derrida and Flyvbjerg (DF) [14]. In the latter case, a segment of unit total length is divided into mutually exclusive parts by a self-similar random process. Figure 1(a) in [14] represents the probability distribution for the length of the largest segment. Obviously, in the DF model the second largest segment must be smaller than $\frac{1}{2}$. This leads to a singularity in the distribution of the largest segment at $\frac{1}{2}$.

(Similar arguments lead to additional singularities at $\frac{1}{3}, \frac{1}{4}$, etc.) Despite these similarities, several important differences exist. Most importantly, in our model neutral segments can overlap and there is no restriction on the sum of their lengths. Thus, the basic reasoning for the existence of the singularity at $\frac{1}{2}$ in the DF model does not apply to our problem. We do not know whether there is some deeper relation between these problems.

Consider next the full probability density $p(\ell, q)$, which is depicted in Fig. 4. Introduction of an additional variable $q$ significantly increases the CPU time needed to analyze a single RS. The MC data in this figure represent only $10^7$ sequences of length $N = 1024$; i.e., its accuracy is smaller than the MC results depicted by the solid line in Fig. 3. Figure 4 demonstrates further peculiarities of $p(\ell, q)$: For fixed $\ell$, the $q$ dependence of $p$ is qualitatively different for $\ell > \frac{1}{2}$ and $\ell < \frac{1}{2}$: When $\ell > \frac{1}{2}$, the distribution has a single peak at $q = 0$, which approaches a Gaussian shape as $\ell$ increases, while for $\ell < \frac{1}{2}$ we see a minimum at $q = 0$ and two peaks symmetrically located around the minimum. While qualitatively such behavior can be easily understood (e.g., for small $\ell$ the $0$-segments are very improbable, since they are typically large, and consequently the maximum must be reached for a nonzero value of $q$) the transition between the $\ell < \frac{1}{2}$ and $\ell > \frac{1}{2}$ regions is rather sharp: we analyzed the $q$ dependence of the graphs representing the fixed-$\ell$ sections of Fig. 4 and concluded that the transition from a single maximum to a minimum surrounded by two maxima cannot be obtained by a variation of parameters in a simple function (the way it is done in the mean-field description of a phase transition near the critical temperature). The numerical data create an impression of two different functions glued along $\ell = \frac{1}{2}$.

The areas $A_{\ell} \equiv \int_{-\infty}^{+\infty} dq p(\ell, q)$ under fixed-$\ell$ sections are shown in Fig. 5. For $\ell > \frac{1}{2}$ it will be proven in Sec. IV.
that $A_\ell \sim \text{const}/\sqrt{1-\ell}$; Figure 5(b) demonstrates the numerical validity of this relation --- $A_\ell \sqrt{1-\ell}$ remains approximately constant in the range of validity. The accuracy of the small-$\ell$ regime is rather low; we only note that $A_\ell$ is approximately linear in $\ell$ for $0.15 < \ell < 0.5$, as can be seen from Fig. 5(a).

### III. QUALITATIVE ARGUMENTS

In this section we present approximate derivations of several features of $p(\ell, q)$. Despite the approximate nature of the arguments, they are rather intuitive, and will be useful when we generalize the problem to $d$-dimensional RW's.

Most properties of RW's have simple continuum limits. As an example, let us consider the special case $L = N$ of our probability distribution: The probability $P_N(L = N, Q)$ that the largest $Q$-segment has length $N$ is simply equal to the probability that the overall charge $Q_0$ of the RS is equal to $Q$. This probability (for even $N + Q_0$) is given by

$$W_N(Q_0) \equiv \text{Prob}(S_N(\omega) = Q_0) = 2^{-N} \frac{N!}{[(N - Q_0)/2]!(N + Q_0)/2!] \sim \sqrt{\frac{2}{\pi N}} \exp(-Q_0^2/2N).$$

(4)

Consider a restricted subset of all RS's in $\Omega_N$, which consists only of sequences with total charge $Q_0$. The conditional probability for the largest $Q$-segment in a sequence selected from this subset to have length $L$ will be denoted as $P_N(L, Q|Q_0)$. This probability is related to $P_N(L, Q)$ by the relation

$$P_N(L, Q) = \sum_{Q_0} P_N(L, Q|Q_0)W_N(Q_0).$$

(5)

In the case of $Q = 0$, i.e., for 0-segments, we note that from the definition it follows that the conditional probability is normalized, i.e., $\sum_L P_N(L, 0|Q_0) = 1$. We further note that as a function of $L$, the conditional probability is expected to be peaked at value that depends on $Q_0$. Let us assume for simplicity that the peak is very narrow; i.e., the length of the largest 0-segment is uniquely determined by $Q_0$ and can be described by a function $Q_0(L)$. Indeed, when $Q_0 \sim 0$, the longest 0-segment typically has $L \sim N$, while for very large $Q_0$, the longest 0-segment must be short. Thus $Q_0(L)$ is a monotonically decreasing function. This approximation is especially reasonable for the extremes $\ell \rightarrow 0$ or 1. In that case, $P_N(L, 0) \approx W_N(Q_0(L))$, and thus

$$p(\ell, 0) \approx \frac{N}{2} W_N(Q_0(L)) \left(\frac{dQ_0}{dL}\right).$$

(6)

Standard scaling arguments suggest that for $Q_0 \ll \sqrt{N}$ we can relate $L \approx N - aQ_0^2$, where $a$ is of order unity. This gives $Q_0(L) \approx \sqrt{(N - L)/a}$, and finally leads to

$$p(\ell, 0) \approx \left(\frac{N}{2}\right) \sqrt{\frac{2}{\pi N}} \frac{1}{\sqrt{\alpha(N - L)}} = \frac{\text{const}}{\sqrt{\pi(1-\ell)}}.$$

(7)

On the other hand, for $Q_0 \gg \sqrt{N}$, the length of the longest 0-segment will be of order of a scale at which the random excursion of the RW becomes comparable to the drift produced by $Q_0$, i.e., when $L^{1/2} \approx (2B)^{-1/2}LQ_0/N$, where $B$ is a constant of order unity. Thus, $Q_0(L) \approx N(2B/L)$ and

$$p(\ell, 0) \approx \left(\frac{N}{2}\right) \left(\sqrt{\frac{2}{\pi N}} e^{-BN/L}\right) \left(\frac{\sqrt{B/2N}}{L^{3/2}}\right) = \frac{\text{const}}{L^{3/2}} e^{-B/\ell}.$$

(8)

Thus, this simple scaling argument correctly reproduces the square-root divergence for $\ell \rightarrow 1$, and the $\exp(\text{const}/\ell)$ singularity for $\ell \rightarrow 0$.

It is useful to consider an alternative derivation of the behavior in $\ell \rightarrow 0$ limit, since such derivation involves a somewhat different view of the same properties. A RS with an extremely short 0-segment must have a strong imbalance between the charges (large $Q_0$), i.e., resemble a biased random walk. Consider the probability $Z_N(L) = \sum_{L'} P_N(L', 0)$ that the largest 0-segment in an $N$-step sequence does not exceed length $L$. If $L \ll N$, this quantity can be used to estimate $Z_{2N}(L)$ for a sequence twice as long: Two halves of the sequence of length $2N$ must be biased walks with the same direction of bias to prevent creation of long loops, which start in one half of sequence and end in the other half. In addition, loops longer than $L$ must be absent from each half of the sequence. Thus, $Z_{2N}(L) \approx \frac{1}{2} Z_N(L)$. This
relation is only approximate since it disregards the correlation between the two halves of the sequence close to its middle. (Loops longer than \( L \) can begin in one half of the sequence and end at the other half; correction for this effect may introduce an \( L \)-dependent prefactor.) If the continuum limit is well defined, we can express this relation in the form

\[
\int_0^{t/2} p(\ell, 0) d\ell \approx \frac{1}{2} \left( \int_0^t p(\ell, 0) d\ell \right)^2. \tag{9}
\]

This approximation is satisfied by \( p(\ell, 0) = (2B/\ell^2) e^{-B/\ell} \). The approximation casts serious doubts on the exact value of the preexponential power \( x \), defined in Eq. (3). Note that different derivations of the behavior of \( p(\ell, 0) \) in the \( \ell \to 0 \) limit produced different values of \( x \). Our MC results are not accurate enough to distinguish between these predictions. However, it can be shown that the approximate equality (9) can be rephrased as an exact inequality \([\text{left-hand side}] < [\text{right-hand side}]\). This leads to the conclusion that \( x \geq 2 \), which rules out the value \( 3/2 \) suggested in Eq. (8).

The method of reflections is a standard tool in calculating the behavior of random walkers near reflecting or absorbing walls (see Ref. [9]). It can be used to calculate various seemingly nontrivial probabilities in terms of probabilities that are easily evaluated. One such result, which is important for the following discussion, is that the probability for an \( N \)-step RW to never return to its starting point is equal to the probability that it reaches its starting point exactly at the \( N \)th step [15], i.e.,

\[
\text{Prob}\{S_i(\omega) \neq 0, \ 1 \leq i \leq N\} = \text{Prob}\{S_N(\omega) = 0\} = W_N(0), \tag{10}
\]

where \( W_N \) was defined in Eq. (4). This relation permits, for instance, an exact solution to a simplified version of our problem. In the modified problem, the largest \( Q \)-segments are selected among those that start from the beginning of the RS, rather than all possible starting positions. This modified probability \( P'_H(L, Q) \) is given by the probability that the path \( \omega \) reaches position \( Q \) at the \( L \)th step, and that it never again passes through position \( Q \) until the \( N \)th step. Using Eqs. (4) and (10), we obtain the result (for \( N, L, Q \) all even or all odd)

\[
P'_H(L, Q) = W_L(Q)W_{N-L}(0) = 2^{-N} \frac{L!}{[(L-Q)/2][(L+Q)/2][(N-L)/2]!} \frac{(N-L)!}{[(N-L)/2]!}
\]

\[
\Rightarrow \frac{2}{\pi \sqrt{L(N-L)}} \exp(-Q^2/2L). \tag{11}
\]

Unfortunately, the search for the longest \( Q \)-segment in the RS among all possible starting points creates a more complicated problem. However, we similarly expect \( P'_H(L, Q) \) to approach a scaling form when \( N, L, Q \to \infty \), while the reduced length \( \ell \equiv L/N \) and the reduced charge \( q \equiv Q/\sqrt{N} \) are kept constant. In this continuum limit, it the probability density is defined analogously with \( p' : p'(\ell, q) = \frac{N}{2}(P'_H(L, Q) + P'_H(L+1, Q)) \). In this limit Eq. (11) reduces to

\[
p'(\ell, q) = \frac{1}{\pi \sqrt{\ell(1-\ell)}} \exp(-q^2/2\ell). \tag{12}
\]

We intuitively expect \( p \) and \( p' \) to behave similarly, at least in the \( \ell \to 1 \) limit, and indeed in that limit \( p' \) resembles \( p \) [see Eq. (17)].

### IV. EXACT RELATIONS

The probabilities \( P_N(L, Q) \) for different values of \( N \), \( L \), and \( Q \) satisfy an interesting relation, which in the continuum limit becomes an integral expression that relates \( p(\ell, q) \) at arbitrary values of \( \ell > \frac{1}{2} \) and \( q \) to the values of \( p(\ell = \frac{1}{2}, q) \). While such a relation is insufficient to completely determine the function \( p(\ell, q) \), it suffices to determine some of its important features. In this section, we derive this relation and explore its consequences.

We first consider the following sets of random sequences, for \( N/2 < L < N \) and arbitrary \( Q \):

\( A_Q = \{ \omega \in \Omega_{2L-N} : S_{2L-N}(\omega) = Q \} \),

\( B_Q = \{ \omega \in \Omega_{2(N-L)} : \text{Largest } Q \text{-segment in } \omega \text{ has size } N-L \} \),

\( C_Q = \{ \omega \in \Omega_N : \text{Largest } Q \text{-segment in } \omega \text{ has size } L \} \).

\( A_Q \) is the set of all \((2L-N)\)-step sequences with total displacement (charge) \( Q \). This set has \( 2^{2L-N}W_{2L-N}(Q) \) elements, where the function \( W \) has been defined in Eq. (4). The set \( B_Q \) contains all \((2N-2L)\)-step sequences whose largest \( Q \)-segments are exactly half as long as the whole sequence. By definition, there are \( 2^{(N-L)}P_{2(N-L)}(N-L, Q) \) such sequences. Finally, \( C_Q \) is our "target set," which consists of all \( N \)-step sequences whose largest \( Q \)-segment has length \( L \). This set contains \( 2^NP_N(L, Q) \) sequences. We shall use the sequences from the \( A \)- and \( B \)-type sets to construct the sequences of the "target set": It is possible to construct a one-to-one onto mapping

\[
f : \bigcup_{Q'} (B_{Q'} \times A_{Q'-Q'}) \mapsto C_Q, \tag{13}
\]
i.e., each sequence in $C_Q$ can be uniquely associated with a pair of sequences from $B_{Q'}$ and $A_{Q-Q'}$ for some value of $Q'$, and vice versa. The mapping $f$ is schematically shown in Fig. 6. Basically, the sequence from $A_{Q-Q'}$ is inserted into the sequence from $B_{Q'}$ at its midpoint to create a sequence in $C_Q$. After such an insertion we obtain a sequence of length $2(N - L) + 2L - N = N$, which contains a segment of charge $Q - Q' + Q' = Q$ of length $(N - L) + (2L - N) = L$. Thus we created an $N$-step sequence with a $Q$-segment of size $L$. From the process of construction it is clear, that this is the largest $Q$-segment in the sequence: if a larger $Q$-segment had existed in the resulting chain, we could have reversed the process by removing a segment of length $2L - N$ from the center of the chain. This would have yielded a $2(N - L)$ step chain whose largest $(Q - Q')$-segment was longer than half of its entire length, contradicting the initial assumption regarding the chain from the set $B_{Q-Q'}$. The "reversibility" of the process also proves the one-to-one correspondence between the sets. It should be stressed, however, that this process requires that the midpoint of the resulting $N$-step sequence is necessarily included in the largest $Q$-segment. Thus, the proof is valid only for $L > N/2$.

Since $A_{Q_1}$ and $A_{Q_2}$ are disjoint when $Q_1 \neq Q_2$, equating the number of elements in the domain and range of $f$ gives the identity

$$P_N(L, Q) = \sum_{Q'} W_{2L-N}(Q - Q') P_{2(N-L)}(N - L, Q').$$

Taking the continuum limit of the above equation, we replace the probabilities $P$ by the probability density $p$, and the discrete probability $W$ by its continuum (Gaussian) form, which follows from Eq. (4) and obtain

$$p(\ell, q) = \frac{1}{\sqrt{4\pi(2\ell - 1)(1 - \ell)}} \int_{-\infty}^{+\infty} dq' \times e^{-\frac{(q' - \sqrt{2\ell})^2}{2(2\ell - 1)}} p\left(\frac{1}{2}, q'\right),$$

where $q' = Q'/\sqrt{N}$. Since the equation is linear in the function $p$, it cannot be used to determine proportional-ity constants. (Since the equation is valid only for $\ell \geq \frac{1}{2}$, the normalization condition of $p$ cannot be used either.) Equation (15) expresses an unknown function in an interval of $\ell$'s via the values of the same unknown function at a particular point $\ell = \frac{1}{2}$. Despite these limitations, Eq. (15) can be utilized to explain some properties of $p(\ell, q)$ and to extract information using alternative methods, as will be explained below. Before proceeding, we note that in the $\ell \to \frac{1}{2}$ limit the Gaussian term in the integrand of Eq. (15) [the exponential term with the prefactor $1/\sqrt{2\pi(2\ell - 1)}$] becomes $\delta(q - q')$, and the integral relation reduces to identity.

By integrating both sides of Eq. (15) over $q$, we find a relation between the areas $A_\ell$, for $\ell > \frac{1}{2}$:

$$A_\ell \equiv \int_{-\infty}^{+\infty} dq p(\ell, q) = \frac{1}{\sqrt{2(1 - \ell)}} \int_{-\infty}^{+\infty} dq p\left(\frac{1}{2}, q\right),$$

which confirms the observation from the MC data that for $\ell > \frac{1}{2}$, $A_\ell$ is proportional to $1/\sqrt{1 - \ell}$. The relation (16) provides a method for measuring the otherwise unknown proportionality constant by detailed calculation of probability density at $\ell = \frac{1}{2}$, i.e., measurement of $A_{1/2}$.

In the $\ell \to 1$ limit, the variable $q'$ disappears from the exponent in Eq. (15), and the relation reduces to

$$p(\ell \to 1, q) = \frac{A_{1/2}}{\sqrt{4\pi(1 - \ell)}} e^{-q'/2}.\quad (17)$$

This relation both confirms our contention that $p(\ell, 0)$ has a square-root divergence $A/\sqrt{\pi(1 - \ell)}$ with $A = \frac{1}{2}A_{1/2}$, and demonstrates that the fixed-$\ell$ sections of the surface in Fig. 4 approach a pure Gaussian shape when $\ell \to 1$.

The proportionality coefficient of the square-root divergence $A$ is simply related sum over $Q$ of the probabilities for the largest $Q$-segment to be exactly half of the length of the RS. By complete enumeration we calculated the probabilities $P_M(M/2, Q)$ for all $Q$ and $M \leq 30$, and formed the sums $A(M) \equiv \frac{1}{2} \sqrt{M} \sum_Q P_M(M/2, Q)$.

(Only even sequence lengths $M$ were used.) The sums $A(M)$ converge to $A$ in the $M \to \infty$ limit. Figure 7 depicts the sequence of the estimates $A(M)$ plotted versus $1/M$. The extrapolation to $1/M = 0$ provides an estimate $A = \frac{1}{2}A_{1/2} = 1.011 \pm 0.001$. This result is consistent with the MC estimates of $A$, and has smaller error bars. It is interesting to note that despite the fact that $A$ is almost unity, it is definitely larger than 1.

Finally, we note that the discrete relation in Eq. (14) can be used to produce exact analytical forms for $P_N$. Consider cases when $L = N - M$ and $M$ is a small number. Equation (14) can be rewritten in the terms of $M$ as follows:

$$P_N(N - M, Q) = \sum_{Q'} W_{N-2M}(Q - Q') P_{2M}(M, Q').\quad (18)$$

![Fig. 6. Schematic illustration of the mapping f. A pair of sequences from $B_{Q'}$ and $A_{Q-Q'}$ are combined to form a sequence from $C_Q$.](image-url)
Placement of the i-th step from the origin of the walk. Let us define the following variables:

\[ M_i(\omega) \equiv \max \{S_0(\omega), S_1(\omega), \ldots, S_i(\omega)\} , \]  
\[ m_i(\omega) \equiv \min \{S_0(\omega), S_1(\omega), \ldots, S_i(\omega)\} . \]

The variables \( M_i \) and \( m_i \) represent the maximal and minimal coordinates achieved by the random walker up to (and including) the i-th step. In Fig. 8(a), the dot-dashed and dotted lines depict \( M_i \) and \( m_i \), respectively, corresponding to a RS \( \omega \) shown above the graph. (The corresponding \( S_i \) is depicted by the solid line.) The variable \( M_i \) (\( m_i \)) is a monotonic nondecreasing (nonincreasing) function of \( i \), which graphically looks like an ascending (descending) staircase. One can also view \( M_i \) and \( m_i \) as two walls that contain the entire RW. Initially the walls are located at \( M_0 = m_0 = 0 \), and they gradually separate from each other: whenever the random walker inside reaches a wall and performs an additional step in the direction of the wall, it pushes the wall to a new position thus increasing the distance between the walls.

Consider two RS's, \( \omega_1 \) and \( \omega_2 \), selected from \( \Omega_N \). We are interested in the probability

\[ \phi_L = \text{Prob}[S_i(\omega_2) > M_i(\omega_1), 1 \leq i \leq L] \]

that the path \( \omega_2 \) remains above the maximum point of \( \omega_1 \) that far, for the first \( L \) steps. The dotted line in Fig. 9 depicts the RS \( \omega_1 \), which generates the staircase (solid line) that the RS \( \omega_2 \) is supposed to remain entirely above of. We denote the determination of \( \phi_L \) as the "staircase problem." The dot-dashed line in Fig. 9(a) depicts a permitted \( \omega_2 \), while dot-dashed lines in Figs. 9(b) and 9(c) show examples of forbidden cases. (Analogously, one can define problem of RW staying below \( m_i \), and a problem of RW staying either above \( M_i \) or below \( m_i \), i.e., staying outside the walls pushed by the RS \( \omega_1 \).) Every step of the staircase begins when the RS \( \omega_2 \) arrives to that particular maximal value of \( S \) for the first time. The step ends when the sequence exceeds that value for the first time. The sizes of these steps are independent of each other, and their distribution is given by the first arrival time to index 1, i.e., \( \text{Prob(size of a step= } k) = k^{-1}\text{Prob}(S_k = 1) \sim k^{-3/2} \). (For a general

**V. EXTREMAL SEGMENTS AND THE "STAIRCASE PROBLEM"**

In this section, we define a new problem in the theory of random walks, related to two simultaneous walkers, and analyze it detail. We derive the relation between this problem, and the problem of extremal segments, and use this relation to investigate the properties of \( p(\ell, 0) \) in the \( \ell \to 1 \) limit.

Consider a random sequence (walk) \( \omega = \{q_1, q_2, \ldots, q_N\} \). It can be graphically represented by a plot of \( S_i \) versus \( i \), where \( S_i \) represents the total displacement of the i-th step from the origin of the walk. Let us define the following variables:

\[ M_i(\omega) \equiv \max \{S_0(\omega), S_1(\omega), \ldots, S_i(\omega)\} , \]
\[ m_i(\omega) \equiv \min \{S_0(\omega), S_1(\omega), \ldots, S_i(\omega)\} . \]

The variables \( M_i \) and \( m_i \) represent the maximal and minimal coordinates achieved by the random walker up to (and including) the i-th step. In Fig. 8(a), the dot-dashed and dotted lines depict \( M_i \) and \( m_i \), respectively, corresponding to a RS \( \omega \) shown above the graph. (The corresponding \( S_i \) is depicted by the solid line.) The variable \( M_i \) (\( m_i \)) is a monotonic nondecreasing (nonincreasing) function of \( i \), which graphically looks like an ascending (descending) staircase. One can also view \( M_i \) and \( m_i \) as two walls that contain the entire RW. Initially the walls are located at \( M_0 = m_0 = 0 \), and they gradually separate from each other: whenever the random walker inside reaches a wall and performs an additional step in the direction of the wall, it pushes the wall to a new position thus increasing the distance between the walls.

Consider two RS's, \( \omega_1 \) and \( \omega_2 \), selected from \( \Omega_N \). We are interested in the probability

\[ \phi_L = \text{Prob}[S_i(\omega_2) > M_i(\omega_1), 1 \leq i \leq L] \]

that the path \( \omega_2 \) remains above the maximum point of \( \omega_1 \) that far, for the first \( L \) steps. The dotted line in Fig. 9 depicts the RS \( \omega_1 \), which generates the staircase (solid line) that the RS \( \omega_2 \) is supposed to remain entirely above of. We denote the determination of \( \phi_L \) as the "staircase problem." The dot-dashed line in Fig. 9(a) depicts a permitted \( \omega_2 \), while dot-dashed lines in Figs. 9(b) and 9(c) show examples of forbidden cases. (Analogously, one can define problem of RW staying below \( m_i \), and a problem of RW staying either above \( M_i \) or below \( m_i \), i.e., staying outside the walls pushed by the RS \( \omega_1 \).) Every step of the staircase begins when the RS \( \omega_2 \) arrives to that particular maximal value of \( S \) for the first time. The step ends when the sequence exceeds that value for the first time. The sizes of these steps are independent of each other, and their distribution is given by the first arrival time to index 1, i.e., \( \text{Prob(size of a step= } k) = k^{-1}\text{Prob}(S_k = 1) \sim k^{-3/2} \). (For a general
vival events for each $L$), and confirmed this particular value of $\alpha$ to within 1%. Figure 10 shows $\phi_L \sim L^{-3/4}$ as a function of $1/\log(L)$. The fact that this combination remains independent of $L$ when $L \to \infty$ demonstrates the assumed power law. The points on the graph provide successive estimates of the prefactor $C_\phi$; the error bars indicate statistical uncertainties (one standard deviation) for each $L$. We estimate the asymptotic value of the coefficient as $C_\phi = 0.263 \pm 0.001$.

A very closely related probability distribution is

$$\tilde{\phi}_L = \text{Prob}[S_2(\omega_2) > M_{i-1}(\omega_1), 1 \leq i \leq L],$$

(i.e., this time the two paths are allowed to meet at positions where $\omega_1$ has reached a new maximum. Figures 9(a) and 9(c) both correspond to the permitted events in the definition of $\tilde{\phi}_L$. Now let

$$f_L = \text{Prob}[S_1(\omega_2) > M_i(\omega_1), 1 \leq i \leq L - 1; S_L(\omega_2) = S_2(\omega_1)]$$

denote the probability of such a meeting occurring for the first time at step $L$. Meeting at the $L$th step represents an extremely simple event, i.e., despite the fact that we are considering the behavior of two random walkers, it is easy to construct all possible cases for short $L$. In Fig. 11, the solid and dot-dashed lines represent $\omega_1$ and $\omega_2$, respectively, for $L = 1, 3, 4$, and 5. We can see that there is a single possibility for $L = 1, 3, 4$, and five possibilities for $L = 5$. (The diagram in the bottom right represents 4 different cases; the dashed lines indicate the alternative segments in both $\omega_1$ and $\omega_2$.) $f_L$ is simply equal to $2^{-L}$ (probability of a single diagram) multiplied by the number of distinct such diagrams. Since $\{f_i\}$ is a rapidly converging series, we can easily evaluate the infinite sum $\sum f_i$ to a high accuracy by summing the first few terms. (The convergence of the infinite series $\sum f_i$ can be easily seen from the fact that it is bounded from above by the probability that $\omega_1$ is at a maximum when the two RW’s meet for the first time.) We can use

![FIG. 10. Numerical demonstration of the power-law relation $\phi_L \sim L^{-3/4}$, and the determination of the constant $C_\phi$.](image)
the probabilities \( f_i \) to relate \( \bar{\phi}_L \) to \( \phi_L \) via the following relation:

\[
\bar{\phi}_L = \phi_L + \sum_{L_1=1}^{L} f_{L_1} \phi_{L-L_1} + \sum_{L_1=1}^{L} \sum_{L_2=1}^{L-L_1} f_{L_1} f_{L_2} \phi_{L-L_1-L_2} + \cdots \tag{25}
\]

Fast decay of \( f_L \) with increasing \( L \), allows the replacement of \( \phi_{L-L_1}, \phi_{L-L_1-L_2}, \ldots \) in Eq.(25) by \( \phi_L \) in the \( L \rightarrow \infty \) limit, leading to

\[
\bar{\phi}_L \overset{L \rightarrow \infty}{\longrightarrow} \frac{1}{1 - \sum_i f_i} \phi_L \equiv C_f \phi_L. \tag{26}
\]

The coefficient \( C_f \) can be calculated to high accuracy by summing up the series \( \{f_i\} \). We have obtained the value \( C_f = 1.413 \pm 0.005 \) by extrapolating from finite sums of \( f_i \), which we have obtained exactly for \( L \) up to 18, and up to \( L = 100 \) using a Monte Carlo method. The results are shown in Fig. 12.

Finally, we are in a position to discuss the connection of the staircase problem to the problem of our main interest. For simplicity, let us only consider \( P_N(L, 0) \) in the \( L/N \rightarrow 1 \) limit and examine all RS's with \( S_N(\omega) > 0 \) whose largest neutral segments are \( L \) steps long. To construct such a sequence, we can start with a neutral segment \( \omega_0 \) of size \( L \), depicted by a solid line in Fig. 13. This segment is completed into the \( N \)-step RS by adding pieces to its two ends (thick dashed and dotted lines in Fig. 13), in such a way that a larger neutral segment is not created. In order to avoid overcounting when there is more than one largest neutral segment, we can, for example, require that the initially selected segment is the leftmost of all largest segments. Let \( L' \) be the size of the piece \( \omega_R \) added to the right-hand side of \( \omega_0 \). (The left-hand side piece \( \omega_L \) will then have length \( N - L - L' \).

To avoid creating a larger neutral segment that begins somewhere inside \( \omega_0 \) and ends somewhere inside \( \omega_R \), the sequence \( \omega_R \) must remain above the staircase generated by the successive maxima of \( \omega_0 \), i.e., if the sequence \( \omega_R \) is translated to the beginning of the sequence \( \omega_0 \) (as depicted by the thin dashed line in Fig. 13) they must satisfy conditions defined in the staircase problem. Similar restrictions apply to the segment \( \omega_L \); however, this time both \( \omega_0 \) and \( \omega_L \) should be viewed “backwards” (thin dotted line in Fig. 13). [Formally, for any sequence \( \omega \) it is convenient to define a conjugate sequence \( \omega^* \), which consists of the elements \( q_i \) of \( \omega \) written in reverse order, as illustrated in the Fig. 8(b). The conjugate of a given path can be obtained by rotating the original path by 180° around the axis normal to the plane. Thus, the staircase conditions have to be satisfied between the

\[\omega_L \quad \omega_0 \quad \omega_R\]
sequences \( \omega_0^L \) and \( \omega_R^L \). Since \( \omega_0 \) is a neutral segment, its elements are not completely independent, while our original definition of the staircase problem required the presence of two completely random sequences. However, when \( N - L \ll N \), the two ends of \( \omega_0 \) can be treated approximately as independent RS's, and they become completely independent in the \( (N - L)/N \to 0 \) (i.e., \( \ell \to 1 \)) limit. Finally, we notice that the above requirements were somewhat over-restrictive: we are allowed to create neutral segments exactly of length \( L \) between \( \omega_0 \) and \( \omega_R \), and therefore the probability will be described by \( \phi_L \) rather than by \( \phi_0 \). The segment \( \omega_L \), however, must satisfy probabilities described by \( \phi_L \) because we initially required that the neutral segment created by \( \omega_0 \) is the leftmost segment in the RS. This yields

\[
P_N(L,0) = 2 \sum_{L' = 0}^{N - L} \phi_{N - L - L'} W_L(0) \phi_{L'},
\]

the factor 2 coming from RW's with \( S_N(\omega) < 0 \). Finally, taking the sum over \( \ell' \) in the large \( N \) limit, we obtain (for even \( L \))

\[
\lim_{L/N \to 1-} P_N(L,0) = \frac{2C_2^2 C_f}{(N - L)^{1/2 - 2\alpha}} \sqrt{\frac{2}{\pi L(N - L)}} \int_0^1 [\ell'(1 - \ell')]^{1 - \alpha} \frac{d\ell'}{(2\alpha)[N - L]^{1/2 - 2\alpha} \sqrt{\pi L(N - L)}}.
\]

In the above, \( \Gamma(x) \) is the factorial function. This result has several remarkable consequences: First of all, this result suggests that \( p(\ell, 0) \) has a well-behaved continuum limit only if \( \alpha = 1/4 \). This implies that \( \phi_L \sim L^{-3/4} \), a result we have not yet found in the literature. Knowledge of \( C_f \) and \( C_f \) now enables an independent calculation of the proportionality coefficient \( A \) through the relation \( A = \sqrt{2C_2^2 C_f [\Gamma(1/4)]^2 / \Gamma(1/2)} = 1.025 \pm 0.015 \). Although it is slightly larger and less accurate, this result is consistent with other estimates of \( A \).

VI. HIGHER DIMENSIONS

The fact that \( p(\ell, 0) \) has a singularity at \( \ell = 1 \) is a consequence of the fact that a RW in one dimension returns to its starting position very often. Thus, it is clear that the behavior of \( p(\ell, 0) \) depends strongly on the dimensionality of the RW. In order to investigate this, we have generalized the original problem to RW's on a \( d \)-dimensional hypercubic lattice. Now the "elementary charge" (scalar) of the one-dimensional problem is replaced by an elementary step (vector) between neighboring sites on that lattice along one of \( 2d \) possible directions, and there are \( (2d)^N \) possible \( N \)-step walks. (We cannot use the analogy with the sequence of charges, anymore.) The probability distribution \( P_N(L, Q) \) can be easily generalized:

\[
P_N(L, Q) \to P_N^{(d)}(L, Q),
p(\ell, q) \to p^{(d)}(\ell, q),
A_\ell \to A^{(d)}_\ell,
\]

where \( Q = (Q_1, \ldots, Q_d) \) is now the \( d \)-dimensional displacement of a segment in the RW, and \( q = (dN)^{-1/2} Q \).

Most of the arguments used to explore the features of one-dimensional RW's can be applied with minor changes to the \( d \)-dimensional walks. As an example, let us consider the qualitative derivation of the asymptotic properties of \( p(\ell, 0) \) in the \( \ell \to 1 \) limit as derived for the \( d = 1 \) case in Sec. II. As in the one-dimensional case we may assume that the length of the longest loop can be approximately thought of as a function of the overall displacement \( Q_0 \) (end-to-end vector) of the entire walk. Under such an assumption we expect \( L \approx N - q'|Q|_2^2 \), which is analogous to the one-dimensional case, except for the overall charge \( Q_0 \) that is replaced by the modulus (length) of the vector \( Q_0 \). The generalization of Eq. (6) to \( d \) dimensions is

\[
p^{(d)}(\ell, 0) \approx \frac{N}{2} \lambda_N^{(d)}(||Q_0(L)||) \left| \frac{d||Q_0||}{dL} \right|,
\]

where the one-dimensional \( \lambda_N(Q_0) \) of Eq. (6) has been replaced by \( \lambda_N^{(d)}(||Q_0||) \), which is the probability that the length of a \( d \)-dimensional end-to-end vector of an \( N \)-step RW is \( ||Q_0|| \). Near \( Q_0 = 0 \) this probability is proportional to \( N^{-d/2} ||Q_0||^{d-1} \). Substituting this expression into Eq. (29) and using the relation between \( L \) and \( ||Q_0|| \) we find \( p(\ell, 0) \sim (1 - \ell)^{(d-2)/2} \). Thus, we expect the probability density to approach a constant in the \( \ell \to 1 \) limit in \( d = 2 \), and to decay to zero as \( \sqrt{1 - \ell} \) in \( d = 3 \).

The relations that have been demonstrated from an approximate argument above can be proven exactly by generalizing Eq. (15) to \( d \) dimensions. The generalization is straightforward and leads to the form

\[
p^{(d)}(\ell, q) = \frac{1}{2(1 - \ell)} \left( \frac{1 - \ell}{\pi(2\ell - 1)} \right)^{d/2} \int_{-\infty}^{+\infty} d_q' e^{-\frac{|q - q'|^2}{2(1 - \ell)}} p \left( \frac{1}{2}, q' \right),
\]

Thus, for the \( \ell \to 1 \) limit we obtain
\[ p^{(d)}(\ell \to 1, q) = \frac{A^{(d)}_{1/2}}{2\pi^{d/2}} (1 - \ell)^{\frac{d}{2} - 3} e^{-\|\mathbf{q}\|^2/2}. \] (31)

Figure 14 depicts \( p^{(d)}(\ell, 0) \) for \( d = 1, 2, \) and 3, obtained from MC simulations \( N = 1000 \) with samples of \( 10^8, 10^6, \) and \( 10^6 \) RW's, respectively. The peak of the distribution shifts towards \( \ell = 0 \) as the dimensionality is increased. Figure 14 also demonstrates the verification of the form \( p^{(d)}(\ell \to 1, 0) \sim (1 - \ell)^{(d-2)/2} \) for these dimensions.

The asymptotic relation described above assumes that \( A^{(d)}_{1/2} \) does not vanish. Note that

\[ A^{(d)}_{1/2} = \lim_{N \to \infty} \frac{N^{1-d/2}}{2} \sum_{\mathbf{Q}} P_N^{(d)}(N/2, \mathbf{Q}). \]

For each sequence \( \omega \), there are at most \( N \) nonzero terms in the summation over \( \mathbf{Q} \), and \( P_N^{(d)}(L, \mathbf{Q}) < 1 \) since it is a probability. Thus, \( A^{(d)}_{1/2} \leq \lim_{N \to \infty} N^{2-d/2} \). This implies that in dimensions higher than 4, \( p^{(d)}(\ell, q) = 0 \) for \( \ell > 1/2 \). It is easy to understand why \( d = 4 \) is a special dimension in this problem: It is known from the study of the self-avoiding random walks [2] that large loops are absent in space dimensions \( d > 4 \). Thus we expect that in terms of the reduced variable \( \ell \), all loops will have reduced “length” \( \ell = 0 \), i.e., \( p^{(d)}(\ell, 0) = \delta(\ell) \) in this regime.

While we expect an asymptotic probability density \( \delta(\ell) \) for \( d > 4 \), it should be noted that for finite \( N \) the probability \( P_N(L, 0) \) is a monotonically increasing function of \( L \) for small values of \( L \). Therefore, the probability density \( p(\ell, 0) \) measured for finite \( N \) will have a peak at finite (small) value of \( \ell \). As \( N \) increases the entire distribution should drift towards \( \ell = 0 \). Figure 15 depicts such a trend for \( d = 5 \). A convenient measure of such behavior is calculation of value of \( L \) such that most of the statistical weight corresponds to loops shorter than the threshold value. We verified the approach of the distribution to a \( \delta \) function by examining the finite size scaling of the 90% threshold \( L^*_d(N) \), defined through \( \sum_{L=0}^{L^*_d(N)} P_N^{(d)}(L, 0) = 0.9 \). This means that 10% of the time, there is a loop larger than \( L^*_d(N) \) in a \( d \)-dimensional RW of size \( N \). We examined the cases \( d = 5, 6, \) and 7 using the MC method.

FIG. 14. (a) The distribution functions \( p^{(d)}(\ell, 0) \) in 1, 2, and 3 dimensions. (b) The \( \ell \to 1 \) limit of the distributions.

FIG. 15. (a) The distribution function \( p^{(5)}(\ell, 0) \) approaches a \( \delta \) function with increasing \( N \). (b) The 90% threshold \( L^*_d(N) \) scales with the RW size \( N \), the slope in the log-log plot gives \( \beta_d \) for \( d = 5, 6, 7 \).
described in the Appendix, for \( N \) ranging from 14 to 896 and sample sizes of \( 10^5 \). The threshold lengths are also shown in Fig. 15. We find that \( L_d^*(N) \sim N^{1-\beta_d} \), where \( \beta_5 \approx 0.27, \beta_6 \approx 0.44 \), and \( \beta_7 \approx 0.55 \). Since the exponents \( \beta_d \) are positive, the threshold in the terms of the reduced variable \( \ell_d^*(N) \sim N^{-\beta_d} \) vanishes with increasing \( N \).

The above arguments do not provide a definite answer for the borderline dimension of \( d = 4 \). (The reader is reminded that the self-avoiding walk problem at the critical dimension \( d = 4 \) slightly differs from the \( d > 4 \) cases: e.g., regular power laws are modified by logarithmic corrections.) Through MC calculations with up to \( 10^7 \) RW samples and values of \( N \) up to 5000, we find that in \( d = 4 \) the entire distribution \( p^{(d)}(\ell, \delta) \) can be fitted very well to the form \( \ell^{-\alpha_0} e^{-a_2/\ell} \), for finite values of \( N \). Figure 16 depicts such curve for \( N = 1000 \). (The sample size is \( 10^7 \).) The peak position \( a_2/a_1 \) approaches 0 either logarithmically \( (a_2/a_1 \sim 1/\ln N) \), or with a very small power of \( N \), i.e., \( a_2/a_1 \sim N^{-\beta_4} \) where \( \beta_4 \approx 0.16 \). Thus, the distribution still converges to a \( \delta \) function in the continuum limit. Although the qualitative behavior of \( p^{(d)}(\ell, \delta) \) is easily understood, it would be interesting to obtain a quantitative understanding of the distribution, especially at the borderline dimension of four.

VII. DISCUSSION

The problem of extremal segments originated from the desire to consider a simplified description of the ground states of randomly charged polymers. We used MC, exact enumeration, and analytical techniques to analyze the problem, and our results provide convenient tools for a semiquantitative analysis of the ground states of PA’s. In particular, we show that a “typical” RS contains very large neutral segments, i.e., it is possible to construct a ground state from a single very large blob with relatively short ends of the chain dangling outside the blob.

Besides the original motivation, the problem of extremal segments is interesting in its own right. It looks like one of the classical problems of random walks and, nevertheless, is highly nontrivial, and the results indicate a solution with very rich and unexpected structure. The problem can be related to other interesting problems of the RW’s, such as the “staircase problem.” While several features of the problem have been established analytically, we did not find a complete analytical solution of the problem. We think that such a solution is possible and further attempts of finding it are worthwhile. Generalization of the problem to arbitrary space dimension \( d \) is not related to the original problem of charged polymers, nevertheless interesting in its own right.

While the similarity between certain features of our solution and the DF random map results [14] may appear somewhat superficial, we think that this point should be thoroughly investigated in an attempt to establish at least a partial connection between the problems. This may shed some light on the nature of the singularity at \( \ell = 1/2 \) and provide some indications about other possible singularities at smaller \( \ell \)’s which, at the present accuracy, cannot be observed numerically.

The numerical “proof” of the continuum limit in our work was limited to a particular class of RW’s, in which a unit displacement appears at each step. Within that class we presented evidence of a continuum limit where the properly scaled functions become independent of \( N \). Preliminary results within a slightly broader class of RW’s, in which the size of the step has a binomial distribution, indicate that the same universal curves are attained even within this broader class of RW’s. It may be possible to prove the universality of the continuum limit by attempting to perform a renormalization-group-like treatment of the problem, i.e., attempting to define the problem in the limit where the RW becomes a true Gaussian walk (walk of idealized Brownian particle). This limit, however, is far from being trivial. In particular the definition of what is called a loop (i.e., how close two different points of the walk should be located so that the segment will be called a closed loop) presents a nontrivial problem in the continuum limit. Such a short distance scale can undergo a nontrivial scaling, similarly to the excluded volume pa-
rameter in the treatment of self-avoiding walks. A different approach to the question of universality may begin from an expansion of the solution near the dimension $d = 4$, as in the treatment of self-avoiding walks.

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APPENDIX: NUMERICAL METHODS

In this Appendix, we describe the numerical methods used in our study. All of the algorithms were implemented on a Silicon Graphics R4000 workstation.

We use two approaches to attack the problem numerically: The first approach is to compute the exact distribution $P_N(L, Q)$ for small values of $N$ by considering all possible $N$-step walks. Since the computational time increases exponentially with $N$, this method practical only up to $N \approx 30$, and we have analyzed RW’s with up to 36 steps this way. Thus, in order to determine the scaling form $p(\ell, q)$, it is necessary to use a random sampling of the set $\Omega_N$ for large values of $N$. Using such a Monte Carlo procedure, we have investigated RW’s of up to 1024 steps. Since the $q = 0$ case is especially interesting, we have used more efficient algorithms to determine $p(\ell, 0)$ to a higher accuracy. For both the exact enumeration and MC calculations, our algorithms require $O(N)$ operations to process one sample from $\Omega_N$ for $p(\ell, 0)$, and $O(N^{3/2})$ operations to process the full probability distribution $p(\ell, q)$. Further details on the individual algorithms, as well as the algorithm used to determine $p^{(d)}(\ell, 0)$ are given below.

1. Algorithm for $p(\ell, 0)$

The only difference between exact enumeration and MC algorithms involve the number of RW’s analyzed: In exact enumeration, the number of analyzed RW’s increases exponentially with $N$, whereas the samples are chosen at random in the MC routines, and the sample size is usually set to a constant. Standard random number generators are used to generate the RWs in the MC algorithm. For each RW, the size of the largest loop is determined and this is recorded in a histogram (with sizes from 0 to $L$) that eventually represents the probability distribution we are looking for. The determination of the largest neutral segment in a given sequence is identical in both enumeration and MC algorithms, and is described below.

Given a RW $\omega$, an array $F(Q)$ stores the step number $i$ when $S_i(\omega) = Q$ for the first time. Initially, $F(Q) = -1$ for all $Q$. At each step of the RW (including step 0), the current step number $i$ is recorded in $F(S_i(\omega))$ if the site is visited for the first time, i.e., if $F(S_i(\omega)) = -1$. If the site was visited earlier, the maximum loop size is replaced by the maximum of itself and the difference $i - F(S_i)$. Since $F(S_i)$ stores the first time a site is visited, the largest loop in the walk must correspond to one of such differences. A finite number of operations are needed for each step, therefore this part of the algorithm involves $O(N)$ operations.

2. Algorithm for $p(\ell, q)$

The selection of RW’s (enumeration or MC) and the creation of the histogram are also straightforward for this more general problem. The main task is to find an efficient algorithm that produces the sizes of largest $Q$-segments (for all $Q$) in a given sequence $\omega$. A straightforward generalization of the algorithm for $p(\ell, 0)$ would have required $O(N^2)$ operations per sequence. However, our algorithm takes advantage of the fact that the same positions are visited many times, and it requires only $O(N^{3/2})$ operations instead. As usual, the algorithm traces the sequence one by one. There are two main arrays. At a given step $i$, one of them keeps track of the sizes of largest $Q$-segments encountered that far. The second array is actually a dynamically allocated list of pairs of integers. Each pair in the list stores a charge $q$ and size of the largest $q$-segment that ends at the current step $i$. The size of this array grows as $\sqrt{i}$ on the average. At each increment in step size, all pairs in the list are updated by adding the next element in the sequence to $q$ and incrementing the corresponding lengths by one. These lengths are then compared with the corresponding values in the first array, which is updated if the new length is larger. A new element is added to the list of pairs whenever the walk reaches a position for the first time, a condition that is checked for separately. All the operations in an update can be accomplished by a single pass through the list of pairs, thus the whole algorithm requires only $O(N^{3/2})$ operations to complete, as mentioned earlier.

3. Algorithm for $p^{(d)}(\ell, 0)$

For the MC determination of $p^{(d)}(\ell, 0)$ at higher dimensions, the $O(N)$ algorithm described in Sec. A.1 of this appendix requires $O(N^d)$ storage elements for the array $F(Q)$, which quickly becomes prohibitive with increasing $d$. The storage requirement can be reduced to $O(dN)$ by storing the time series of the position $S_i(\omega)$ of the RW instead. However, the simplest algorithms would require $O(N^2)$ operations to find the largest 0-segment given such a data structure. Note that the typical RW in dimensions $d \geq 2$ does not revisit the same site more than a few times, and therefore the total number of 0-segments in a RW should be only of $O(N)$. We have taken advantage of this fact in order to devise an algorithm that requires only $O(N \log N)$ operations to do the
job. The algorithm is as follows:

After the position array $S(i)$ is formed, its contents [which are the position vectors $(Q_1, \ldots, Q_d)$] are indexed in lexicographical order. This operation requires only $O(N \log N)$ operations, when an efficient sorting algorithm like Heapsort [18] is used. All 0-segments in the sequence start and end at the same position by definition; therefore, the two end points will be adjacent in the lexicographical index. Going through the index sequentially, it is then possible to determine the largest of the 0-segments in only $O(N)$ operations. The extraordinary speedup of this algorithm makes it possible to go up to sample sizes of $10^8$ for 1000-step RW’s in seven dimensions.

[12] In the language of RW’s, the term “0-segment” corresponds to a loop. Throughout this paper we will use the “language of charged N-mers” and the “language of RW’s” interchangeably.