

Field compensation as an alternative to magnetic shielding in searches for $n-\bar{n}$ transitions

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Application of suitable *additional* intermittent magnetic fields is proposed as an alternative to magnetic shielding in searches for $n-\bar{n}$ transitions. The quenching effect of the Earth's field can be negated by assuring that, within a characteristic time interval, a neutron experiences zero field on average.

If a free neutron can transform^{1,2} into an antineutron, the transition must be very slow—since it has never been seen—which means that the responsible $\Delta B = 2$ interaction must be very weak. Therefore, to search for such transitions, one must be careful to avoid perturbations which remove the $n-\bar{n}$ degeneracy and suppress the effect of the $n-\bar{n}$ transition potential ϵ , whose magnitude cannot exceed 10^{-21} eV according to the best direct limit³ on $n-\bar{n}$ transitions. In particular, the energy of an antineutron, whose magnetic moment μ is opposite to that of a neutron, would differ from that of a neutron by a quantity of order 10^{-12} eV in the Earth's magnetic field, almost completely quenching⁴ $n-\bar{n}$ transitions. It has been noted⁵ that the inhibiting effect of a magnetic field takes time to develop and that, under realistic assumptions about the time ($T \leq 10^{-1}$ s) during which one can observe a neutron beam, reduction of the ambient magnetic field to 10^{-3} G suffices to make its inhibiting effect completely innocuous. In the present note, we show that overall magnetic shielding to this level is *not* required, and a suitable arrangement of intermittent corrective field regions along the neutron flight path achieves the same purpose. Since increased sensitivity comes mainly from greater T , and correspondingly longer flight paths, this alternative arrangement may offer advantages over the previously proposed solution of magnetic shielding over the entire region.

As usual, we represent the state of a neutron (with given spin orientation which we take to be along⁶ the magnetic-field direction) by a two-component wave function

$$\Psi = \begin{pmatrix} \Psi_n \\ \Psi_{\bar{n}} \end{pmatrix},$$

whose time evolution in the interaction representation is given by

$$i \frac{\partial \Psi}{\partial t} = M \Psi, \tag{1}$$

with $\hbar = c = 1$, and

$$M = \begin{pmatrix} \Delta & \epsilon \\ \epsilon & -\Delta \end{pmatrix} = \epsilon \rho_x + \Delta \rho_z, \tag{2}$$

where $\Delta = \mu B_0$ and B_0 is the strength of the magnetic field, assumed to be constant⁷ over the flight path; the ρ_i are standard Pauli matrices acting in the $n-\bar{n}$ space. According to Eqs. (1) and (2), an initial state Ψ_0 evolves in time τ into

$$\Psi_1 = U \Psi_0, \tag{3}$$

with

$$U = \exp[-i\tau(\epsilon\rho_x + \Delta\rho_z)] \simeq \exp(-i\tau\Delta\rho_z) - i\epsilon\Delta^{-1}\rho_x \sin\tau\Delta$$

to lowest order in ϵ . As noted in Ref. 5, for $\Delta\tau \ll 1$ the amplitude of \bar{n} , arising from an initial *neutron* state

$$\Psi_0 = \begin{pmatrix} 1 \\ 0 \end{pmatrix},$$

approaches $-i\epsilon\tau$, the same as for $\Delta = 0$.

Now suppose that, after time τ , a magnetic field $B_1 \gg B_0$ is applied antiparallel to B_0 for a time $\theta \ll \tau$. For⁷ $\theta \rightarrow 0$ and $\mu B_1 \theta = \phi$, Ψ_1 will be transformed to

$$\Psi_2 = \Theta \Psi_1 = \Theta U \Psi_0 \tag{4}$$

with

$$\Theta U = \exp(i\phi\rho_z) U \simeq \exp i(\phi - \tau\Delta) - i\rho_n \epsilon \Delta^{-1} \sin\tau\Delta,$$

to lowest order in ϵ , with $\rho_n = \rho_x \cos\phi - \rho_y \sin\phi$. If the compensating field is adjusted⁸ to cancel the phase difference which the magnetic field B_0 has caused to develop between the n and \bar{n} components of Ψ , $\phi = \tau\Delta$, this simplifies to

$$\Xi = I - i\rho_n \epsilon \Delta^{-1} \sin\tau\Delta, \tag{5}$$

which is very similar to the unhindered action of the matrix $M_0 = \epsilon\rho_x$, viz., when $\Delta = 0$. The only differences are that Ξ represents a rotation about an axis

$$\hat{n} = \hat{x} \cos\phi - \hat{y} \sin\phi$$

instead of \hat{x} , and the angle of rotation is reduced by a factor $(\tau\Delta)^{-1} \sin\tau\Delta$, which approaches unity for $\tau\Delta \ll 1$. It is then easy to see that result of repeated applications of Ξ . If a neutron beam, represented initially by Ψ_0 , passes through N regions of magnetic field B_0 , after each of which a corrective field B_1 applies a phase $\phi\rho_z$, the final "neutron" wave function will be

$$\Psi_N = \Xi^N \Psi_0,$$

with

$$\Xi^N \simeq I - i\rho_n N \epsilon \Delta^{-1} \sin\tau\Delta, \tag{6}$$

again to lowest order in ϵ .

Consequently, the amplitude of \bar{n} which develops in time

$T = N\tau$ from

$$\Psi_0 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

is $(\tau\Delta)^{-1} \sin\tau\Delta$ times the magnitude it would acquire if Δ were negligible. Thus we see that, to avoid the suppressive effect on Δ on $n-\bar{n}$ transitions, one does not necessarily have to eliminate Δ . It suffices to provide a counteractive field which cancels⁹ Δ on average provided that this is done at time intervals τ satisfying $\Delta\tau \ll 1$. For Δ arising from

the Earth's magnetic field, this requires $\tau \ll 10^{-3}$ s, so if we consider neutrons with velocity 400 m/s, the corrective fields would have to be applied at intervals of less than 40 cm. If a rough form of magnetic shielding were used to reduce the field seen by the neutrons, the spacing could be correspondingly increased.

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¹V. Kuzmin, Pisma Zh. Eksp. Teor. Fiz. 12, 335 (1970) [JETP Lett. 12, 228 (1970)].

²For a recent review in the context of current theories, see R. N. Mohapatra, in *ICOBAN*, proceedings of the International Conference on Baryon Nonconservation, Bombay, 1982, edited by V. S. Narashinham, P. Roy, K. V. Sarma, and B. V. Sreekantan (Indian Academy of Sciences, Bangalore, 1982).

³G. Puglierin reported a preliminary limit of $\tau_{n\bar{n}} > 10^6$ s from the Institut Laue-Langevin experiment at International Conference on Matter Nonconservation, Frascati, 1983 (unpublished).

⁴S. L. Glashow, in *Quarks and Leptons*, proceedings of the Summer Institute, Cargèse, France, 1979, edited by M. Lévy *et al.* (Plenum, New York, 1981).

⁵R. N. Mohapatra and R. E. Marshak, Phys. Lett. 94B, 183 (1980); M. Baldo-Ceolin and R. Wilson (unpublished), cited in Ref. 2.

⁶For the opposite spin orientation, the sign of Δ is simply reversed and the discussion proceeds in exactly the same way.

⁷These assumptions are made only to simplify the mathematical description and are not at all necessary for the validity of the general argument.

⁸Note that the compensation condition $\theta B_1 = \tau B_0$ applies equally for all neutron velocities.

⁹Another way of implementing this was suggested by G. Costa and P. Kabir [Phys. Rev. D 28, 667 (1983)].