

## Homework 4

Due date: 2 July 2015, by email or in my mailbox

### 1. Weighted cardinality estimation (from Liran Katzir)

Extend the cardinality estimation scheme we saw in class to a weighted version. In this version when we encounter an element  $e_i$ , we also get  $w_i$ , and the objective is to estimate  $w = \sum_i w_i$  (counting every element only once of course). In case all  $w_i = 1$ , we get the original cardinality estimation problem.

Derive an explicit formula using  $m$  cells of memory as we did in class for the non-weighted case.

**Hint:** Carefully review the properties of Beta distributions in Section 3.1 of Liran's writeup and try to figure out how to generalize the use of  $U(0, 1) = \text{Beta}(1, 1)$  variables in the non-weighted case to our case. Note the property  $\text{Beta}(\alpha, \beta) = 1 - \text{Beta}(\beta, \alpha)$  is a statement about the cumulative probabilities (hence the densities are mirror images around 0.5).

### 2. Inferring rotations in Cryo-EM (from Yoel Shkolnisky)

Let  $R_1, \dots, R_n$  be unknown  $3 \times 3$  rotation matrices. Suppose we are given the products  $R_i R_j^T$  for  $1 \leq i < j \leq n$ . Let  $S$  be a  $3n \times 3n$  matrix whose  $(i, j)$  block of size  $3 \times 3$  is equal to  $R_i R_j^T$ ,  $i, j = 1, \dots, n$ .

- As only blocks of  $S$  above the diagonal are given, show how to fill the blocks below the diagonal, that is,  $R_i R_j^T$  for  $1 \leq j \leq i \leq n$ .
- Denote the three columns of  $R_i$  by

$$R_i = \begin{pmatrix} | & | & | \\ R_i^{(1)} & R_i^{(2)} & R_i^{(3)} \\ | & | & | \end{pmatrix}.$$

Show that the three vectors of length  $3n$  given by

$$v_j = \left( \left( R_1^{(j)} \right)^T, \dots, \left( R_n^{(j)} \right)^T \right)^T, j = 1, 2, 3,$$

(that is, the concatenation of the first, second, and third columns of all the  $R_i$ s) are eigenvectors of  $S$  corresponding to the same eigenvalue. What is the eigenvalue?

- Using the previous result, explain how to recover  $R_1, \dots, R_n$  from  $S$  (or more precisely, how to recover  $R_1 O, \dots, R_n O$ , where  $O$  is an arbitrary orthogonal  $3 \times 3$  matrix).
- Denote the  $(i, j)$  block of size  $3 \times 3$  of  $S$  by  $B_{ij}$ . Now, we randomly perturb some of the blocks  $B_{ij}$ , and assume that we have  $n^2$  variables  $w_{ij}$ ,  $i, j = 1, \dots, n$ , indicating whether  $B_{ij}$  was perturbed or not. Namely,

$$w_{ij} = \begin{cases} 1, & B_{ij} = R_i R_j^T \\ 0, & B_{ij} \text{ was perturbed} \end{cases}$$

Now we want to recover  $R_1, \dots, R_n$  from the perturbed  $S$  and the information given by  $w_{ij}$ .  
Proposed approach:

- i. Denote by  $\tilde{S}$  the matrix whose blocks are  $w_{ij}B_{ij}$  (that is, perturbed blocks are zeroed). What is  $\tilde{S}v_j$ ?
- ii. Now, try to rescale the rows of  $\tilde{S}$  so that  $v_j$  will be an eigenvector of the rescaled version.
- iii. How can you now recover the  $R_i$ 's from this matrix?