

Reductions

Or

- How to link between problems' complexity, while not knowing what they are



Goal:

- Formalize the notion of "reductions"

Plan:

- Define **Karp** reductions
- Example: show HAMPATH \leq_p HAMCYCLE
- Closeness under reductions
- Define **Cook** reductions
- Discuss Completeness

Reductions

an efficient procedure for A
using

an efficient procedure for
 B

Notation



A cannot be
radically harder
than B

• In other words:

B is at least as
hard as A

Karp reductions - Definition

A is polynomial-time reducible to B
(denote $A \leq_p B$)

If
there
exists a

poly-time-computable
function $f: \Sigma^* \rightarrow \Sigma^*$

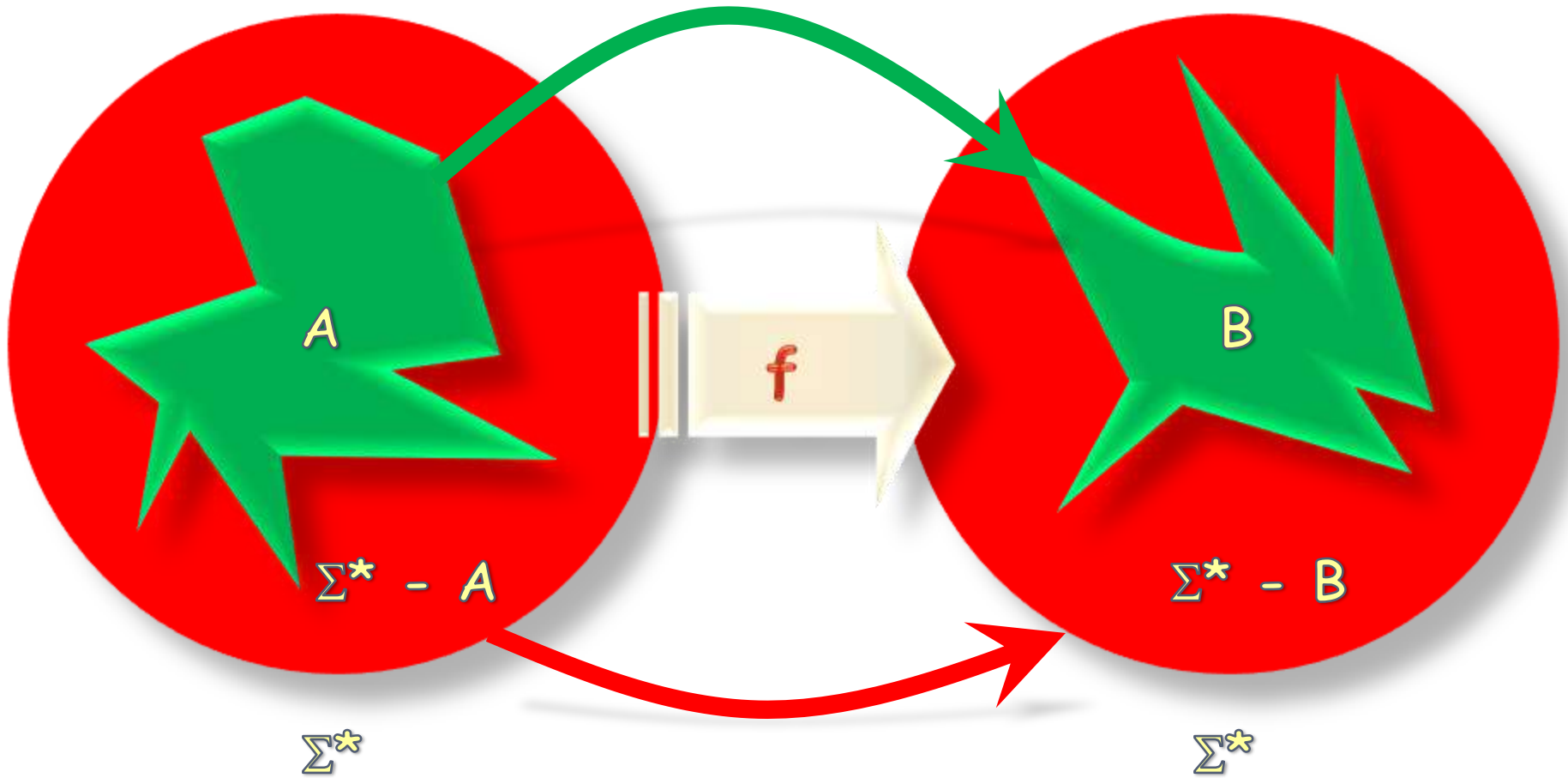
i.e., \exists poly-time
TM that outputs
 $f(w)$ on input w

s.t. for
every w

$w \in A \Leftrightarrow f(w) \in B$

f is a poly-time
reduction of A to B

Karp Reductions - Illustrated



To Do:

Reducing

Come up with a reduction-function f

Show f is polynomial time computable

Prove f is a reduction, i.e., show:

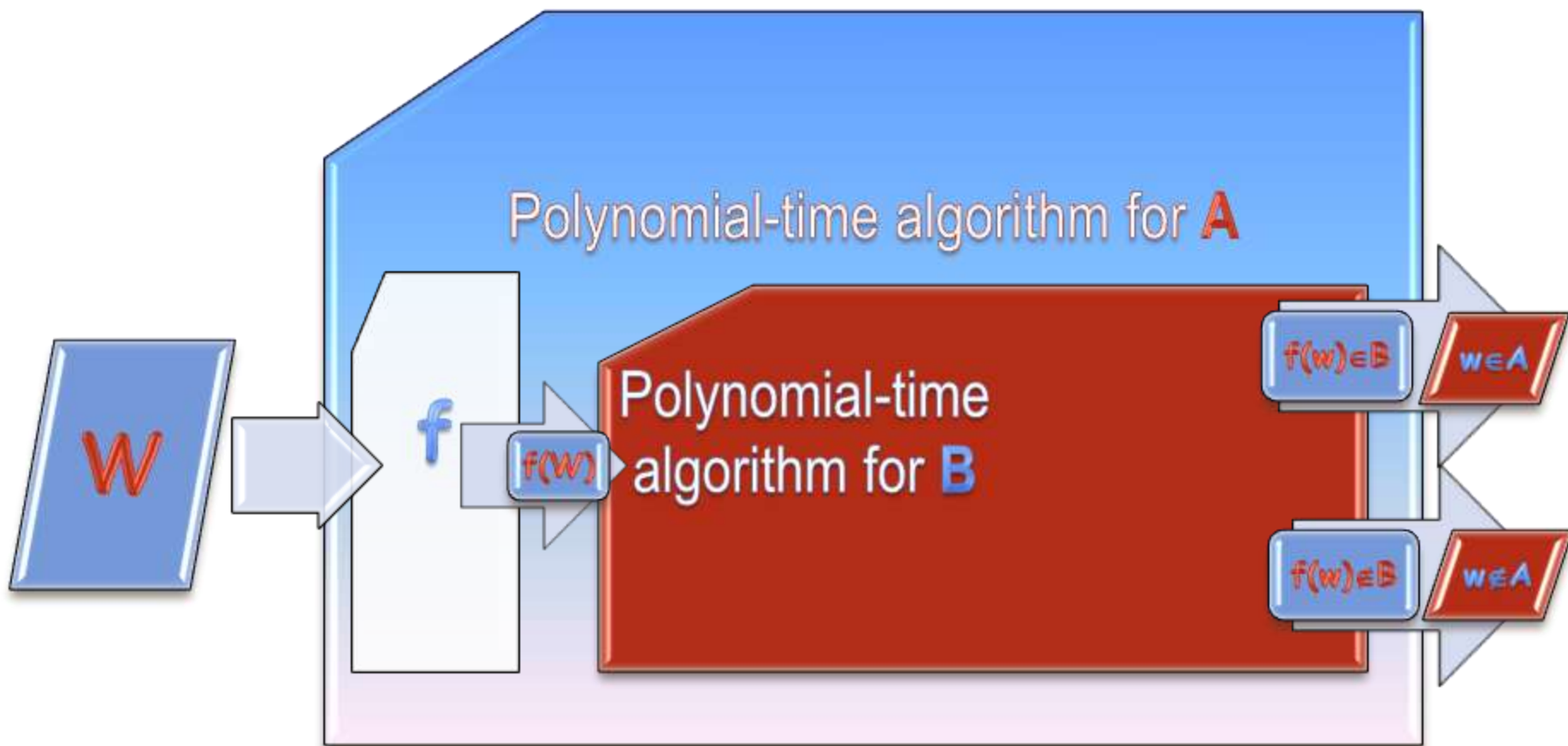
- $w \in A \implies f(w) \in B$
- $w \in A \iff f(w) \in B$



- We'll use reductions that, by default, would be of this type, which is called:
 - *Polynomial-time mapping reduction*
 - *Polynomial-time many-one reduction*
 - *Polynomial-time Karp reduction*



Reductions and Efficiency

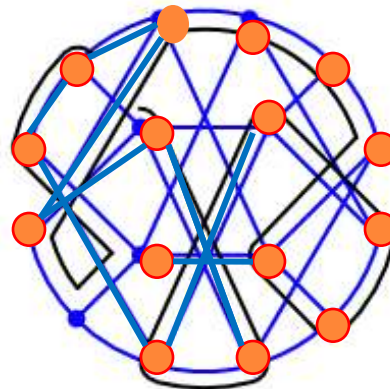
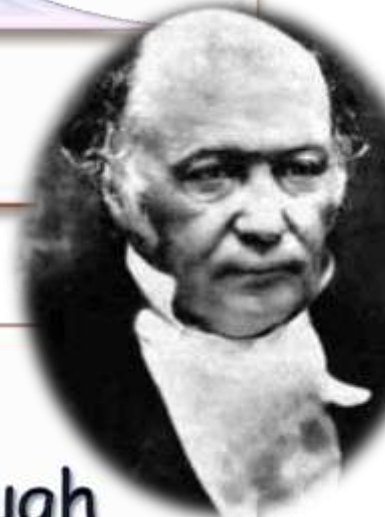


Hamiltonian Path Instance:

- A directed graph $G=(V,E)$

Decision Problem:

- Is there a path in G , which goes through every vertex exactly once?

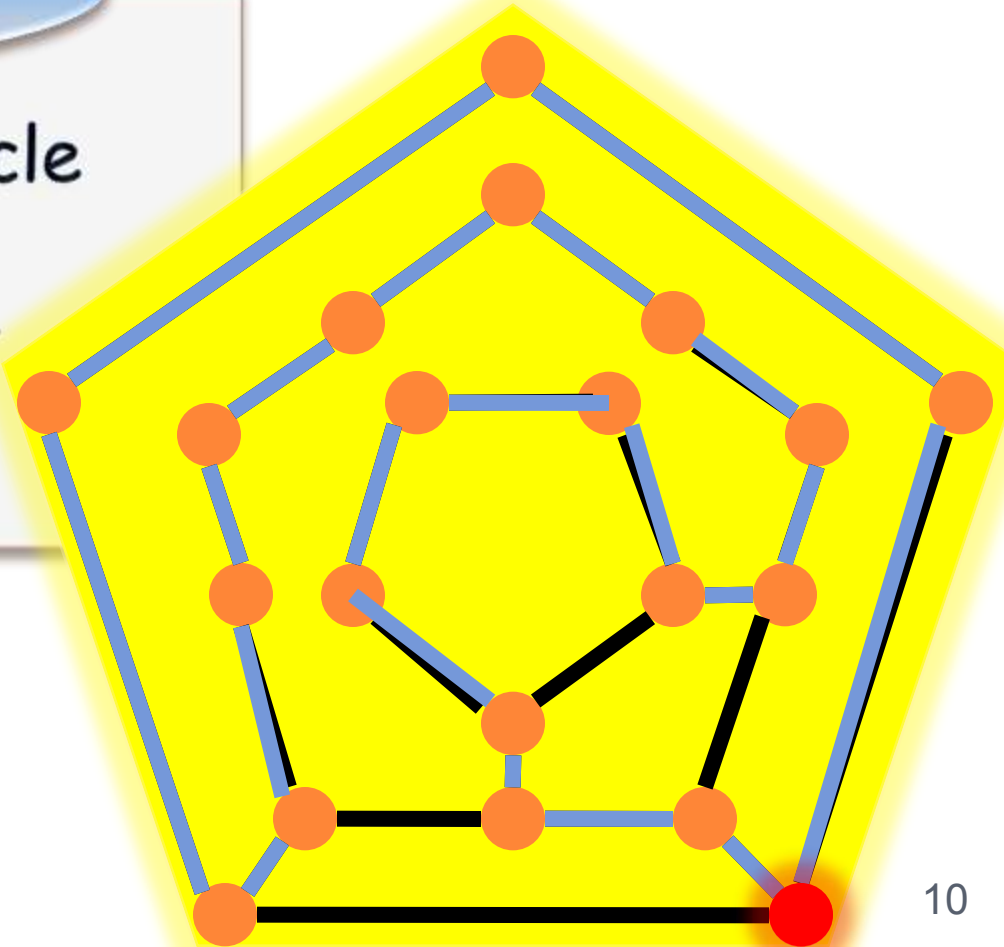


Hamiltonian Cycle Instance:

- a directed graph $G=(V,E)$.

Decision Problem:

- Is there a simple cycle in G that paths through each vertex exactly once?



HAMPATH \leq_p HAMCYCLE

$$f(\langle V, E \rangle) = (\langle V \cup \{u\}, E \cup V \times \{u\} \rangle)$$



Completeness:

- Given a Hamiltonian path (v_0, \dots, v_n) in G , (v_0, \dots, v_n, u) is a Hamiltonian cycle in G'

Soundness:

- Given a Hamiltonian cycle (v_0, \dots, v_n, u) in G' , removing u yields a Hamiltonian path.

Check list

To Do:

✓ Come up with a reduction-function f

? ✓ Show f is polynomial time computable

Prove f is a reduction, i.e., show:

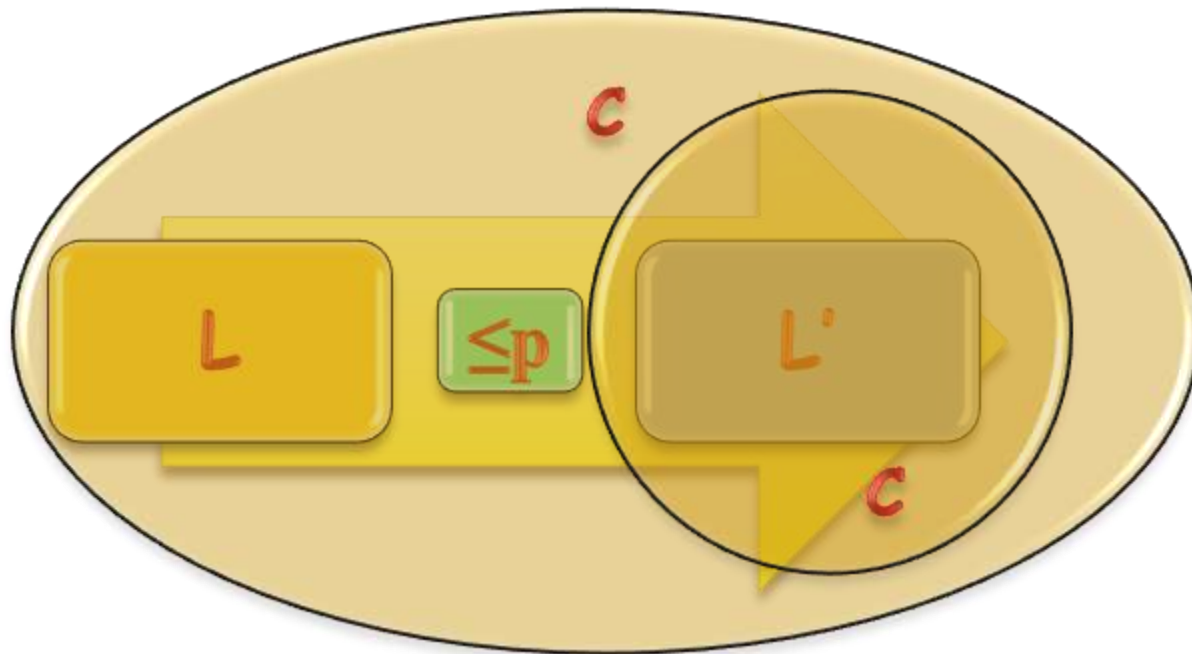
- ✓ $w \in \text{HAMPATH} \implies f(w) \in \text{HAMCYCLE}$
- ✓ $w \in \text{HAMPATH} \implies f(w) \in \text{HAMCYCLE}$



Closeness Under Reductions: Definition

A complexity class C is closed under poly-time reductions if:

- L is reducible to L' and $L' \in C \Rightarrow$
 L is also in C .



Observation

Theorem:

- P, NP, PSPACE and EXPTIME are closed under polynomial-time **Karp** reductions

Proof:

- Do it yourself !!



Log-space Reductions

A is log-space reducible to B
(denote $A \leq_L B$)

If
there
exists a

log-space-computable
function $f: \Sigma^* \rightarrow \Sigma^*$

s.t. for
every w

$w \in A \Leftrightarrow f(w) \in B$

i.e., \exists log-space
TM that outputs
 $f(w)$ on input w

f is a log-space
reduction of A to B

Theorem:

- L, NL, P, NP, PSPACE and EXPTIME are closed under log-space reductions.



Reductions: General

Cook Reduction:

- Assuming an efficient procedure that decides **B**, construct one for **A**.

an efficient procedure for **A**
using

an efficient procedure for
B

Karp is a special case
of **Cook reduction**:

It allows only **1**
call to **B**, whose
outcome must be
outputted as is

Cook red. : HAMCYCLE \rightarrow HAMPATH.

1 Let $E' = E$

2 If $E' = \emptyset$ reject

3 choose (any) $\langle u, v \rangle$ in E'

4 If $\text{HAMPATH} (\langle V + \{w, z\}, E' + \{\langle w, u \rangle, \langle v, z \rangle\} \rangle)$ accept

5 $E' = E' - \{\langle u, v \rangle\}$

6 Go to step 2

Definition: C -complete

Completeness



- For a class C of decision problems and a language $L \in C$, L is C -complete if:
 $L' \in C \Rightarrow L'$ is reducible to L .

Theorem:

- L is complete for classes $C, C' \Rightarrow C=C'$

Proof:

- All languages in C and in C' are reducible to L , which is in both. Since both are closed under reductions, they're the same ■

Theorem:

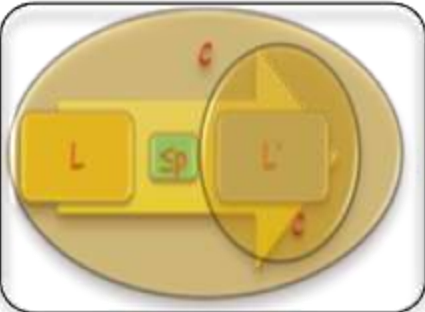
- Any $L \in NPC, L \in P \Rightarrow P=NP$

Summary



Discussed types of **reductions**:

- **Cook** vs. **Karp** reductions
- **Poly-time** vs. **log-space**



Defined:

• "completeness"

Find

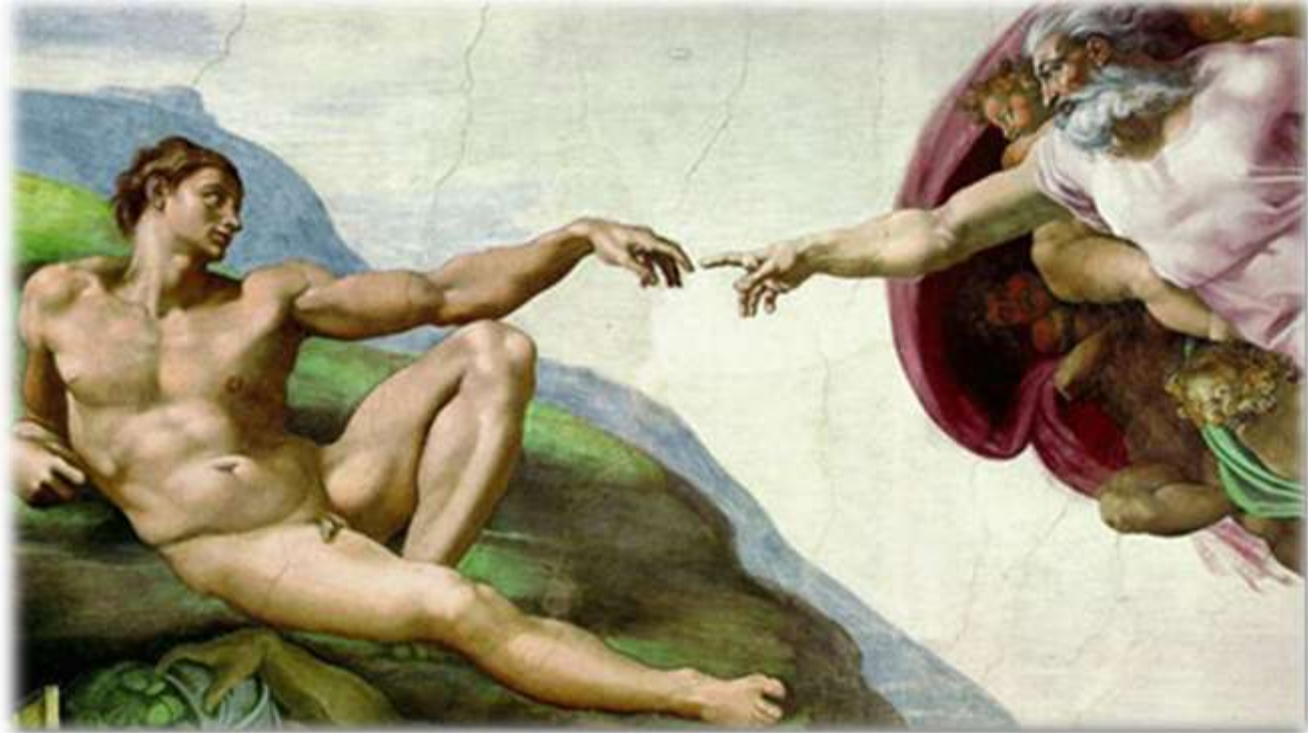
L and **C** s.t. **L**
is **C**-complete



Discussed a way to show:

equality between **complexity classes**

The Cook/
Levin
theorem:



SAT is NP-Complete:



Goal:

- In the beginning...
of NP-Completeness

Plan:

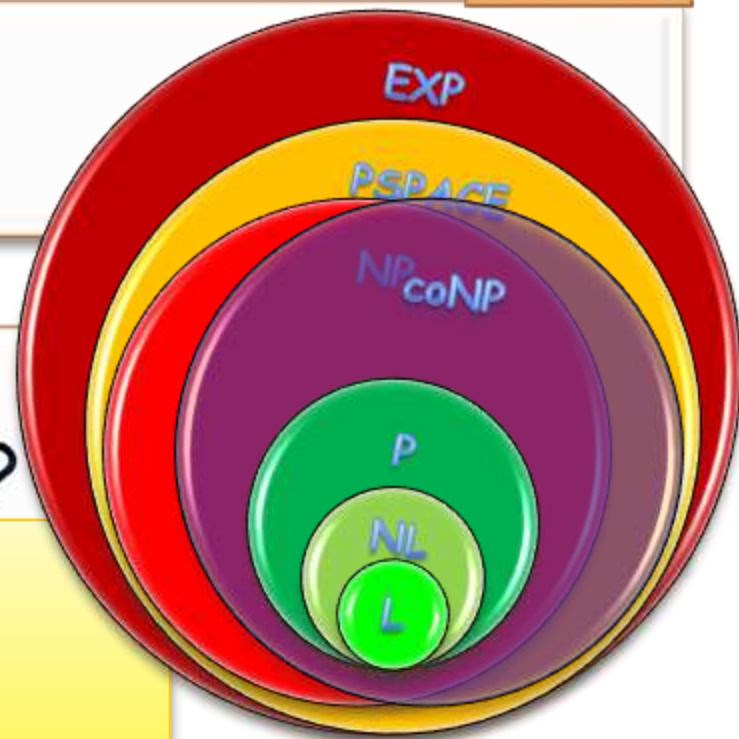
- SAT - definition and examples
- The Cook-Levin Theorem
- Look ahead

SAT Instance:

- A Boolean formula.

Decision Problem:

- Is the formula satisfiable?



SAT or
unsAT?

$$x_1 \wedge \neg x_1$$

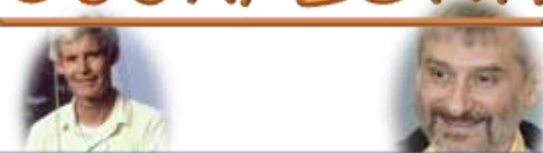
$$((x_1 \vee x_2 \vee \neg x_3) \wedge \neg x_1) \vee \neg(x_3 \wedge x_2)$$

Theorem:

- SAT is in NP

Proof:

- Can verify an ass. efficiently

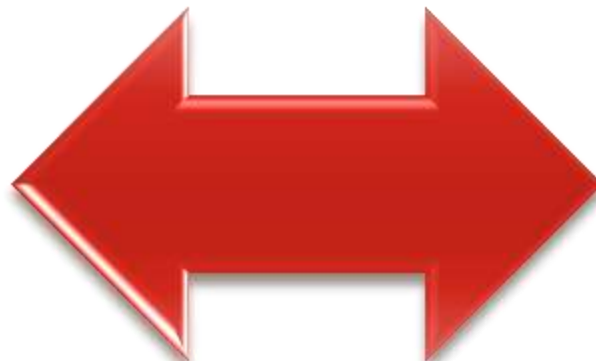


Theorem:

- SAT is NP-Complete

Proof Outline:

- Given an NP machine M and an input w , construct a *Boolean* formula $\varphi_{M,w}$
 $\varphi_{M,w}$ satisfiable $\Leftrightarrow M$ accepts w .



Tableaux

Represent a computation as a configurations' table

cn^e

machine's state

Input

Tape ends



Example

$Q = \{q_0, q_1, q_{\text{accept}}, q_{\text{reject}}\}$

$\Sigma = \{0, 1\}$

$\Gamma = \{0, 1, _ \}$

δ

- $\delta(q_0, 1) = \{(q_1, _, R)\}$
- $\delta(q_1, 1) = \{(q_0, _, R)\}$
- $\delta(q_0, 0) = \{(q_0, _, R)\}$
- $\delta(q_1, 0) = \{(q_1, _, R)\}$
- $\delta(q_0, _) = \{(q_{\text{acc}}, _, L)\}$
- $\delta(q_1, _) = \{(q_{\text{rej}}, _, L)\}$

#	q_0	0	1	1	1	#
#	_	q_0	1	1	1	#
#	_	_	q_1	1	1	#
#	_	_	_	q_0	1	#
#	_	_	_	_	q_1	#
#	_	_	_	q_{rej}	_	#

$$Q = \{q_0, q_1, q_{\text{accept}}, q_{\text{reject}}\}$$

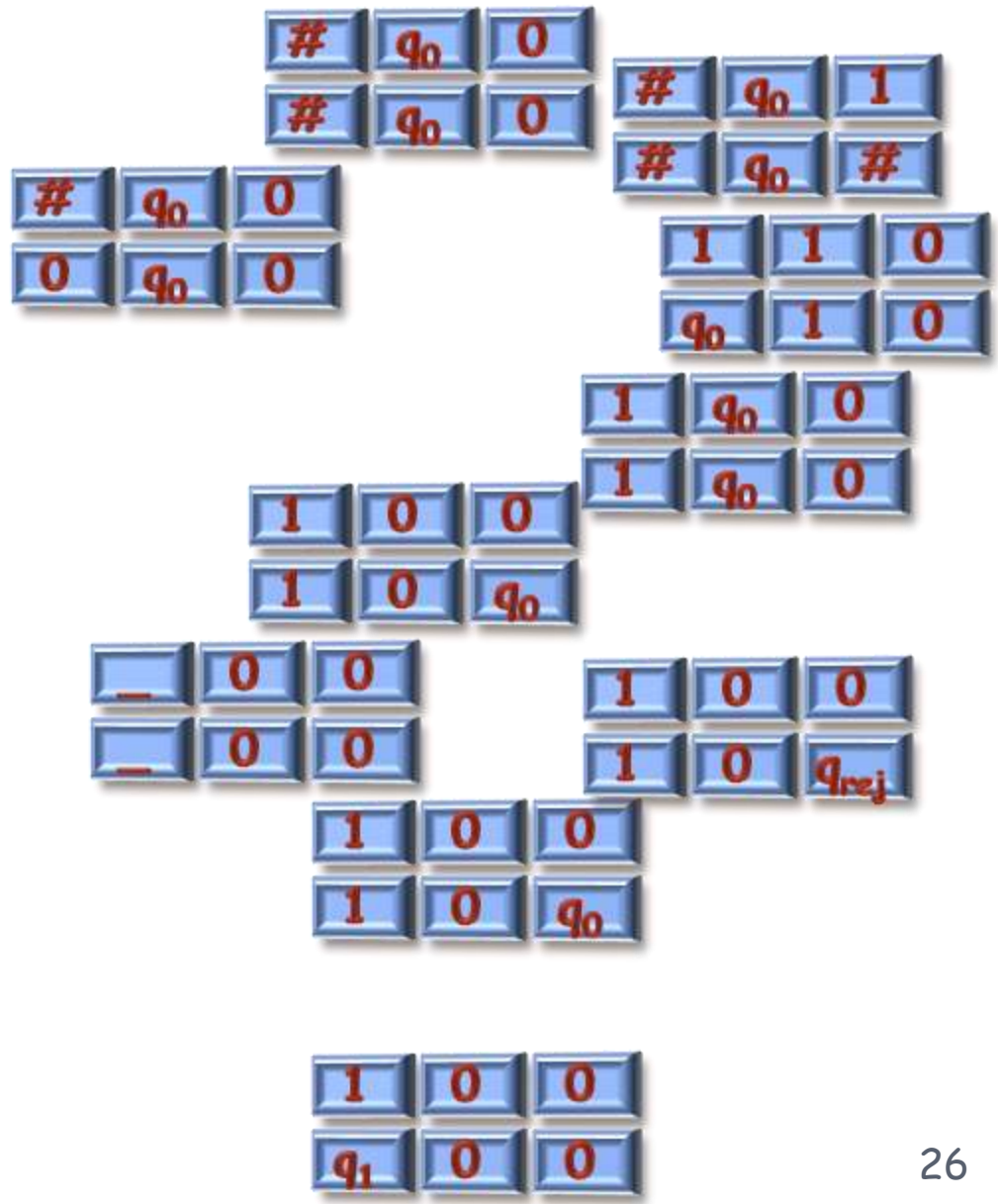
$$\Sigma = \{0, 1\}$$

$$\Gamma = \{0, 1, _ \}$$

$$\delta$$

- $\delta(q_0, 1) = \{(q_1, _, R)\}$
- $\delta(q_1, 1) = \{(q_0, _, R)\}$
- $\delta(q_0, 0) = \{(q_0, _, R)\}$
- $\delta(q_1, 0) = \{(q_1, _, R)\}$
- $\delta(q_0, _) = \{(q_{\text{acc}}, _, L)\}$
- $\delta(q_1, _) = \{(q_{\text{rej}}, _, L)\}$

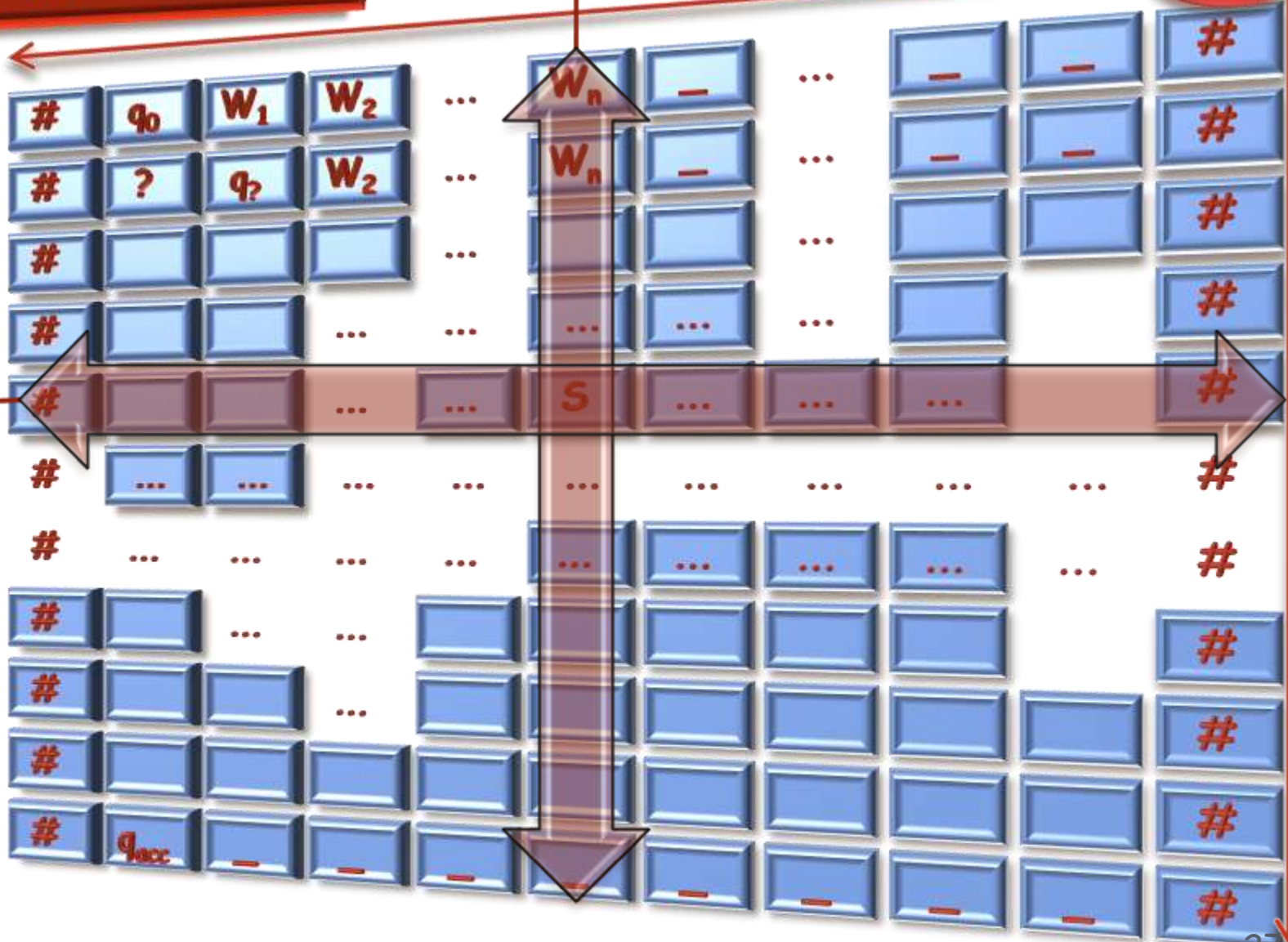
$$\Delta_M \subseteq (\Gamma \cup Q \cup \{\#\})^6$$



Boolean $X_{i,j,s}$ standing for:
does cell i,j has value s ?

$\varphi_{M,w}$ variables

cn^e



$$\varphi_{M,w} =$$

$$\varphi_{M,w}$$

≥ 1 value

< 2 values

1 value to each entry

$$\bigwedge_{1 \leq i, j \leq cn^e} \left[\left(\bigvee_{s \in (\Gamma \cup Q \cup \{\#\})} X_{i,j,s} \right) \wedge \left(\bigwedge_{s \neq t \in (\Gamma \cup Q \cup \{\#\})} (\overline{X_{i,j,s}} \vee \overline{X_{i,j,t}}) \right) \right]$$

start

input

blanks

input consistent

$$\bigwedge X_{0,0,\#} \wedge X_{0,1,q_0} \wedge X_{0,2,w_1} \wedge \dots \wedge X_{0,n+1,w_n} \wedge X_{0,n+2,-} \wedge \dots \wedge X_{0,cn^e,-} \wedge X_{0,cn^e+1,\#}$$

locally legal transition

transitions legal

$$\bigwedge_{0 \leq i, j \leq cn^e} \left[\left\langle s_{0,0}, s_{0,1}, s_{1,0}, s_{1,1}, s_{2,0}, s_{2,1} \right\rangle \in \Delta_M \left[\bigwedge_{i'=0,1,2, j'=0,1} \left[X_{i+i', j+j', s_{i',j'}} \right] \right] \right]$$

\exists accepting configuration

machine accepts

$$\bigwedge_{0 \leq i, j \leq cn^e} \bigvee X_{i,j,q_{acc}}$$

Q.E.D.

$\varphi_{M,w} =$

$$\bigwedge_{1 \leq i, j \leq cn^e} \left[\left(\bigvee_{s \in (\Gamma \cup Q \cup \{\#\})} X_{i,j,s} \right) \wedge \left(\bigwedge_{s \neq t \in (\Gamma \cup Q \cup \{\#\})} \overline{(X_{i,j,s} \vee X_{i,j,t})} \right) \right]$$

$$\wedge X_{0,0,\#} \wedge X_{0,1,q_0} \wedge X_{0,2,w_1} \wedge \dots \wedge X_{0,n+1,w_n} \wedge X_{0,n+2,-} \wedge \dots \wedge X_{0,cn^e,-} \wedge X_{0,cn^e+1,\#}$$

$$\bigwedge_{0 \leq i, j \leq cn^e} \left[\bigvee_{\langle s_{0,0}, s_{0,1}, s_{1,0}, s_{1,1}, s_{2,0}, s_{2,1} \rangle \in \Delta_M} \left[\bigwedge_{i'=0,1,2, j'=0,1} \left[X_{i+i', j+j', s_{i',j'}} \right] \right] \right]$$

$$\bigwedge_{0 \leq i, j \leq cn^e} \bigvee X_{i,j,q_{acc}}$$

Claim:

- $\forall i, j$ transition is locally legal \Leftrightarrow tableau legal

Corollary:

- $\varphi_{M,w}$ Satisfiable $\Leftrightarrow W \in L_M$

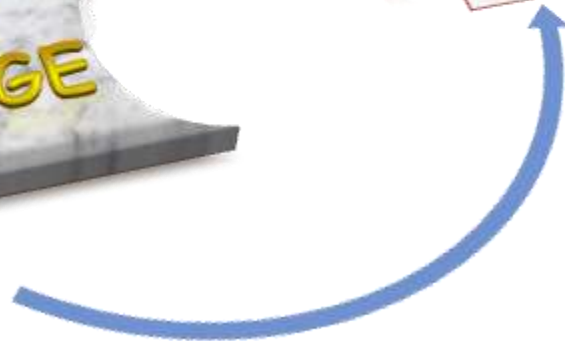
Claim:

- Size of $\varphi_{M,w}$ polynomial in $|W|$

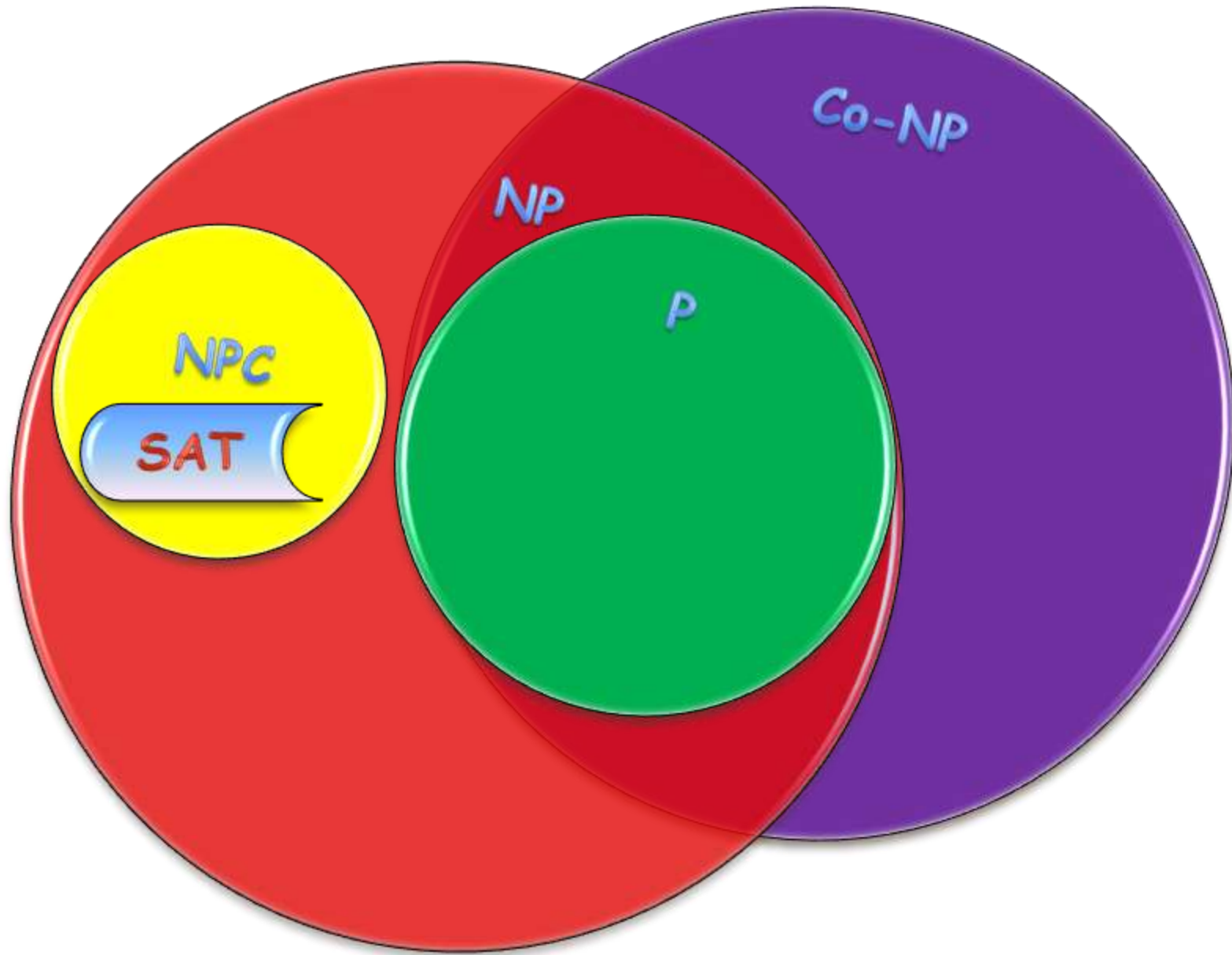


We have just shown
SAT is **NP-hard**, as
any **NP** language can
be reduced to **SAT**

SAT is NPC



P, NP, co-NP and NPC



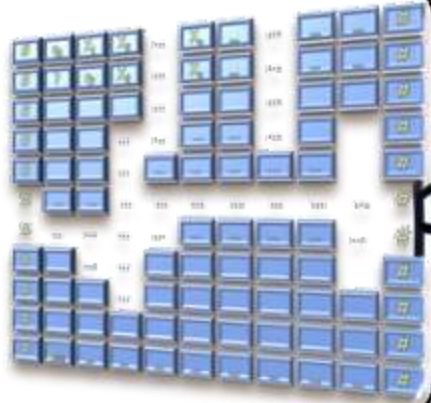
Henceforth, to show
a problem **A** is **NP-**
hard, it suffices to
reduce **SAT** to **A**



Furthermore, once we've shown A is NP-hard, we can reduce from it to show other problems NP-hard



Summary



proved **SAT** is **NP-Complete**



Consider **SAT** the Genesis problem, and explored how to proceed and show other problems are **NP-hard**

Goal:

- introduce some additional NP-Complete problems.

Plan:

- 3SAT
- CLIQUE & INDEPENDENT-SET

Recall: L is NPC if

- L In NP
- L NP-hard - via Karp-reduction

SAT and NPC

So far we only showed one such problem: **SAT**

- which, however, is not up for the tasks ahead

Next we show a special case of **SAT** is **NPC**:

- **3SAT**

3SAT Instance:

- **3CNF** formula

Conjunctive Normal Form -
3 literals in each clause

Decision Problem:

- Is it **satisfiable**?

3CNF:

$$(x \vee y \vee \neg z) \wedge (x \vee \neg y \vee z) \\ (x \vee x \vee x) \wedge (\neg x \vee \neg x \vee \neg x)$$

3SAT is NPC

Claim:

• 3SAT ∈ NP ♦

3SAT is a special case of SAT.

Claim:

• 3SAT ∈ NP-hard

Proof:

- amend our **SAT** formula, so it becomes **3CNF**
- First make it a **CNF**: use **DNF → CNF** on 3rd line

Does this suffice?

Are all others OK?

What is the size of new formula?

$$\varphi_{M,w} = \bigwedge_{1 \leq i, j \leq cn^e} \left[\left(\bigvee_{s \in (\Gamma \cup Q \cup \{\#\})} X_{i,j,s} \right) \wedge \left(\bigwedge_{s \neq t \in (\Gamma \cup Q \cup \{\#\})} \overline{(X_{i,j,s} \vee X_{i,j,t})} \right) \right]$$

$$\wedge X_{0,0,\#} \wedge X_{0,1,q_0} \wedge X_{0,2,w_1} \wedge \dots \wedge X_{0,n+2,w_n} \wedge X_{0,n+3,-} \wedge \dots \wedge X_{0,cn^e,-} \wedge X_{0,cn^e+1,\#}$$

$$\bigwedge_{0 \leq i, j \leq cn^e} \left[\bigvee_{\langle s_{0,0}, s_{0,1}, s_{1,0}, s_{1,1}, s_{2,0}, s_{2,1} \rangle \in \Delta_M} \left[\bigwedge_{i'=0,1,2, j'=0,1} \left[X_{i+i', j+j', s_{i',j'}} \right] \right] \right]$$

$$\wedge \bigvee_{0 \leq i, j \leq cn^e} X_{i,j,q_{acc}}$$

CNF \rightarrow 3CNF

$$(x \vee y) \wedge (x_1 \vee x_2 \vee \dots \vee x_t) \wedge \dots$$

clauses with 1 or 2 literals

clauses with more than 3 literals

replication

split

$$(x \vee y \vee x)$$

$$(x_1 \vee x_2 \vee c_{11}) \wedge (\neg c_{11} \vee x_3 \vee c_{12}) \wedge \dots \wedge (\neg c_{1t-3} \vee x_{t-1} \vee x_t)$$

QED 3SAT is NP-Complete

CLIQUE is NPC

CLIQUE instance:

- A graph $G=(V,E)$ and a threshold k

Decision problem:

- Is there a set of nodes

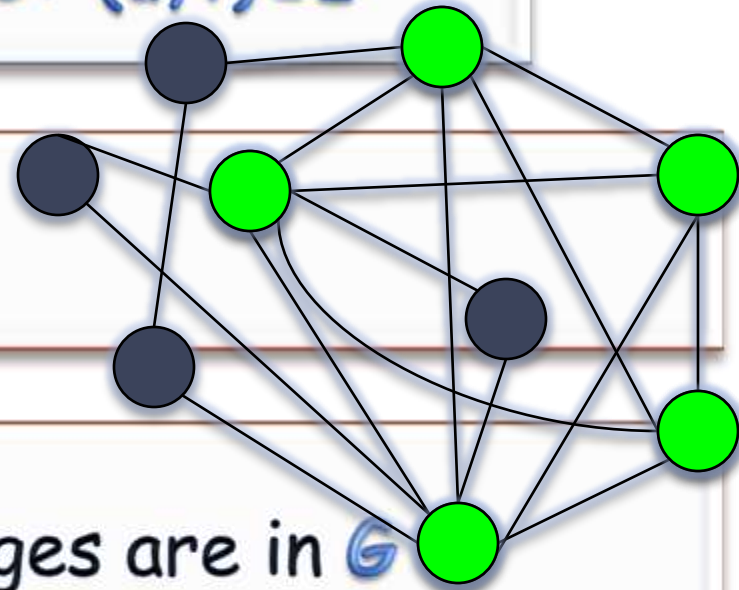
$$C=\{v_1,\dots,v_k\}\subseteq V, \text{ s.t. } \forall u,v\in C: (u,v)\in E$$

Observation:

- $CLIQUE \in NP$

Proof:

- Given C , verify all inner edges are in G



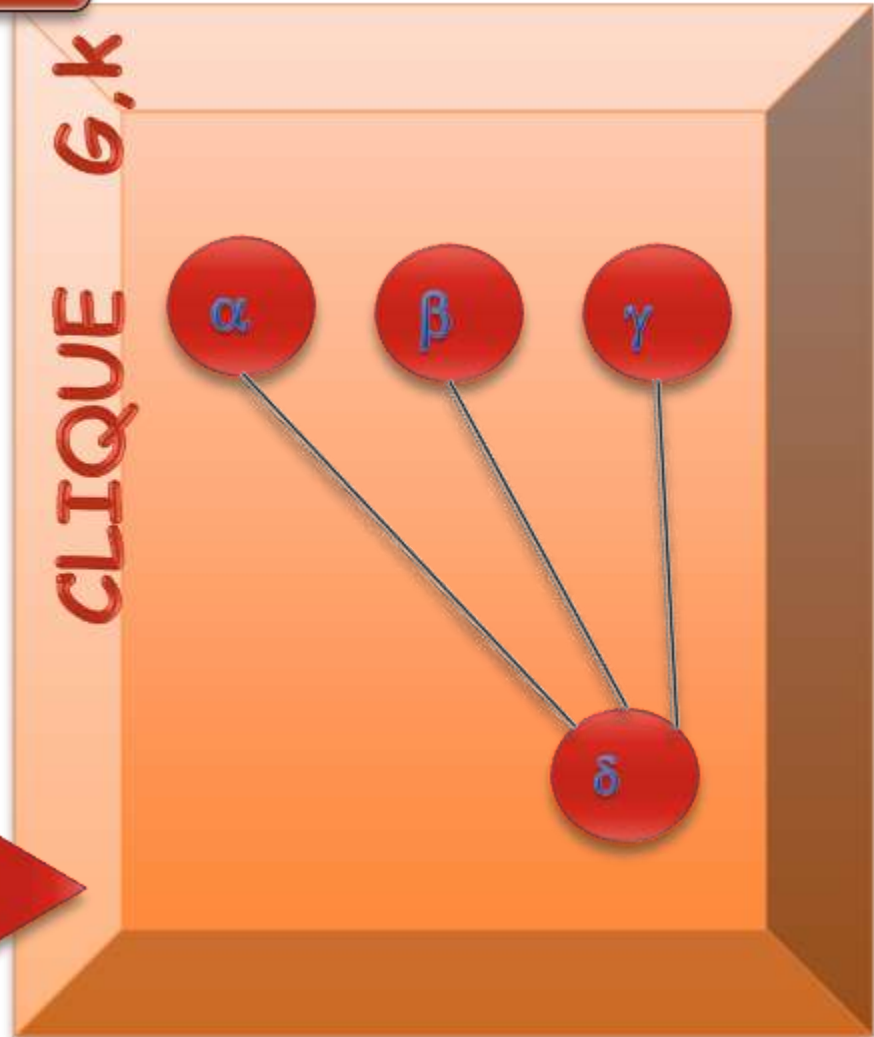
1 vertex for 1 occurrence

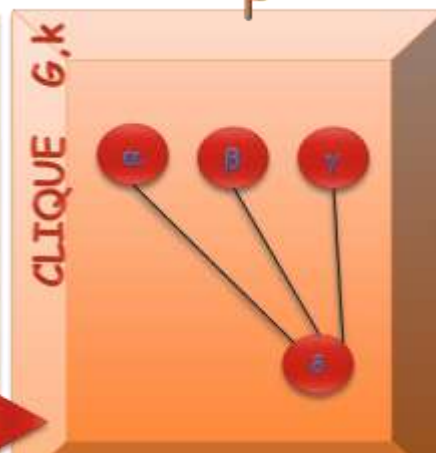
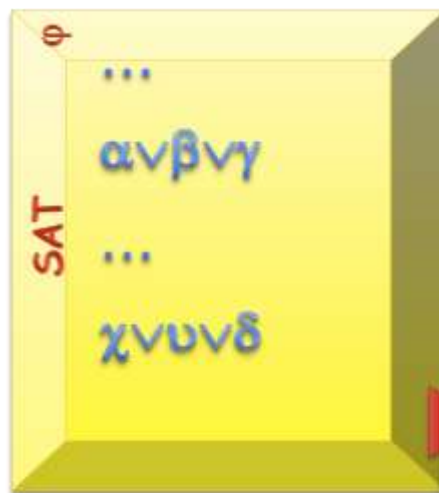
inconsistency \Leftrightarrow non-edge

• within triplets $\alpha = -\delta$

K = number of clauses

SAT \leq_p CLIQUE



SAT \leq_p CLIQUE: proof

each triplet disconnected
k-clique has 1 vertex in each

Completeness:

- Let A be a satisfying assignment to φ , $C(A)$ contains 1 v_α s.t. $A(v_\alpha)$ for every clause

Soundness:

- In a clique C in G of size k , each variable has ≤ 1 of its literals-vertex in C
- extend to a satisfying assignment to φ

INDEPENDENT-SET is NPC

IS instance:

- A graph $G=(V,E)$ and a threshold k

Decision problem:

- Is there a set of nodes $I=\{v_1, \dots, v_k\} \subseteq V$, s.t. $\forall u, v \in I: (u, v) \notin E$

Observation:

- $IS \in NP$

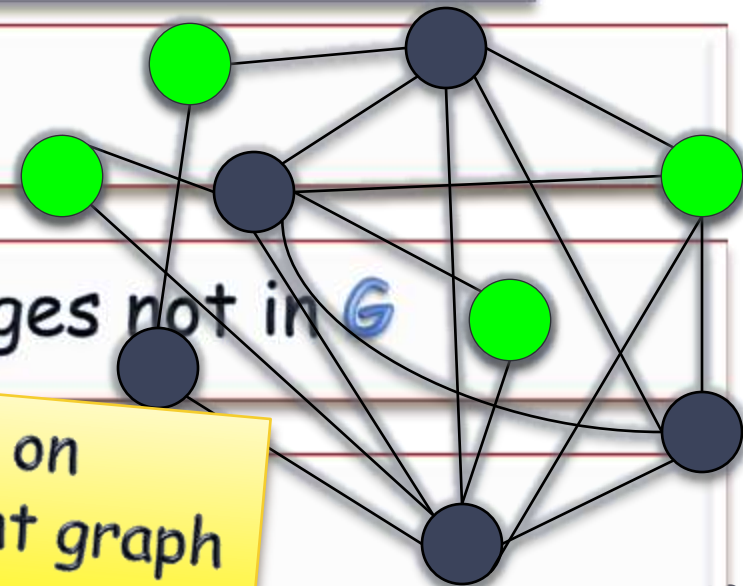
Proof:

- Given I , verify all inner edges not in G

Observation:

- IS is NP-hard

Clique=IS on
complement graph



Reductions

Polynomial
Time
Reductions

Completeness



Hamiltonian
Path

Log Space
Reductions

Completeness



Complexity
Classes

NP

co-NP

P

L

NL

EXPTIME

PSPACE

WWindex



Hamilton, William
Rowan



Karp, Richard



Cook, Stephen
Arthur



Levin, Leonid

WWindex

SAT

Cook-Levin
Theorem



3SAT

Cook-Levin
Theorem



Clique

Independent
Set

Subset Sum

CNF

NPC

NP Hard