

# Interlayer Interactions in Low-Dimensional Layered Hetero-Structures: Modeling and Applications

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# Contents

1	Introduction	2
2	Intralayer Interactions	4
3	Interlayer Interactions	6
4	Applications	11
5	Summary	16
Re	ferences	17

#### Abstract

The field of nanoscale material science has experienced a true revolution over the past 30 years with the discovery of the quasi-zero- and one-dimensional cage-like structures of fullerenes and nanotubes. The successful isolation of graphene about a century ago has further triggered an avalanche of studies unraveling its unique physical and chemical properties. This, in turn, has led to numerous breakthroughs of basic science nature as well as diverse potential technological applications in the fields of nanoscale electronics, flexible displays, solar cells, DNA sequencing, chemical sensing, composite materials, solid lubrication, and many others.

Following extensive studies of the properties of graphene, much attention was recently paid to other members of the two-dimensional (2D) hexagonal layered materials family including hexagonal boron nitride (h-BN) and several transition metal dichalcogenides. Interestingly, stacking individual layers of these materials to form homogeneous and heterogeneous structures results in unique

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physical characteristics that depend on the specific chemical composition of the system and can be tuned via the application of external perturbations. This opens numerous opportunities for combinatorial materials design with versatile structure-function relations. Understanding what determines the properties of such complex structures and how to control them remains a challenge yet to be met in order for these materials to fulfill their full potential.

Theory and computation may offer a valuable microscopic perspective toward achieving this goal. The reduced-dimensions of materials at the nanoscale allow for a unique interplay between theory, computation, and experiment. Here, accurate fully atomistic simulations can complement experiments both in analyzing and rationalizing experimental results and in providing reliable predictions that can minimize the need for demanding trial and error experimental efforts.

Such theoretical treatments of 2D materials require special attention to their anisotropic nature characterized by a strong in-plane covalent bonding network and weaker interlayer interactions. While state-of-the-art quantum mechanical approaches can simultaneously describe these interactions with high accuracy, their computational demand often limits their applicability to relatively small systems. An efficient alternative can be provided by carefully tailored classical force-fields. When appropriately parameterized against experimental results or high accuracy calculations of small model systems, these can provide a reliable description of the structural, mechanical, tribological, and heat transport properties of realistic nanoscale systems with atomic scale resolution. Such force-fields that provide a proper description of intralayer interactions in a variety of 2D materials have been developed over the years and are accessible via standard molecular dynamics simulation codes. Surprisingly, despite the great scientific interest in 2D layered materials, complementary interlayer force-fields that can accurately capture both their binding and sliding energy landscapes are currently available for a very limited set of systems.

In the present chapter, I provide a brief review of recent developments of reliable, efficient, and transferable anisotropic interlayer force-fields for homogeneous and heterogeneous low-dimensional hexagonal layered materials. To demonstrate the performance of these methods, a few applications to the study of the structural and tribological properties of quasi-one- and quasi-two dimensional layered structures will be presented.

## 1 Introduction

The successful isolation of graphene, a one atom thick hexagonal carbon layer, by Novoselov and Geim in 2004 marked the opening of a new era in materials science (Novoselov et al. 2004; Geim and Novoselov 2007; Li and Kaner 2008; Geim 2009; Rao et al. 2009). The study of its unique physical properties including exceptional mechanical strength (Lee et al. 2008), superlubric tribological characteristics (Dienwiebel et al. 2004; Koren et al. 2015), remarkable room temperature electron mobilities (Novoselov et al. 2005a; Morozov et al. 2008), high thermal

conductivity (Balandin et al. 2008; Cai et al. 2010; Xu et al. 2014), quasi-relativistic electronic structure (Geim and Novoselov 2007), and controllable optical properties is flourishing even more than a decade later. Nevertheless, despite this wealth of outstanding material characteristics, the semi-metallic nature of graphene limits its applicability in switchable nanoscale electronic devices. This has triggered the scientific community to search for graphene alternatives within the diverse family of layered inorganic materials (Novoselov et al. 2005b, 2016; Deng et al. 2016).

Currently, two-dimensional (2D) inorganic materials are at the forefront of scientific research with an ever-growing number of chemical compositions including hexagonal boron nitride (*h*-BN), germanene, silicene, phosphorene, transition metal dichalcogenides, such as molybdenum and tungsten disulfide (2H-MoS<sub>2</sub> and 2H-WS<sub>2</sub>) and diselenide (2H-MoSe<sub>2</sub> and 2H-WSe<sub>2</sub>), among others (Heine 2015; Li and Zhu 2015). Similar to graphene, these materials exhibit diverse physical properties and appear in many structural forms ranging from planar configurations to nanotubes, scrolls, onions, and cones.

The recently demonstrated ability to stack such 2D materials in homogeneous as well as heterogeneous few-layered structures (Novoselov et al. 2016; Deng et al. 2016; Dean et al. 2010; Geim and Grigorieva 2013; Wang et al. 2014; Das et al. 2015) opens a vast combinatorial material space enabling the design of novel structures exhibiting desired physical properties. Furthermore, electromechanical manipulation of such structures can be used to gain control over their physical properties – a basic requirement for their future technological application (Koren et al. 2015, 2016; Leven et al. 2013).

Here, theory and computation play a prominent role in efficiently scanning the vast material space, identifying potential candidates that are expected to exhibit the desired physical properties, and studying their sensitivity towards external perturbations. This can focus the demanding experimental efforts on a selected group of predesigned structures and increase the probability of obtaining the required 2D material functionality. Moreover, a synergic cooperation between theory, computation, and experiment, where experimental data are used to refine theoretical models and computational algorithms that, in turn, provide more accurate predictions, can formulate a feedback cycle that will considerably enhance the efficiency of 2D materials design.

An accurate theoretical account of the physical and chemical properties of layered (and other) materials requires a full quantum mechanical treatment of their electronic structure. Computational methodologies that may provide such ultimate accuracy include wave function-based configuration interaction or coupled clusters methods as well as quantum Monte-Carlo procedures (Nightingale and Umrigar 1999; Pang 2016). These methods, however, are quite unfavorable in terms of the scalability of their computational burden with system size and are hence limited to very small molecular structures. Green's function-based methods that can efficiently sum high-order terms in a perturbative expansion scale better with system size and hence can treat somewhat larger systems (Sakai et al. 2015). Density functional theory (DFT) (Hohenberg and Kohn 1964; Kohn and Sham 1965) is currently probably the most popular method to study the physical properties of large systems

(Sakai et al. 2015). While being exact in principle, its practical approximations provide a good balance between computational efficiency and accuracy. Nowadays, DFT calculations of material properties involving hundreds of atoms are being routinely performed in many research groups (Barone et al. 2011). If one desires to treat even larger systems on a fully atomistic and quantum mechanical basis, accuracy is often further compromised to gain computational efficiency. Here, methods like the variational Hartree-Fock formalism (Szabo and Ostlund 1989), semi-empirical approaches (Pople 1970), density functional based tight-binding approximations (Porezag et al. 1995; Kwon and Tománek 2000; Miró et al. 2013; Zahid et al. 2013), or empirical tight-binding (Szabados et al. 2006; Carlson and Dumitrică 2007) can be used to provide approximate descriptions of 2D material properties.

Often, however, a fully quantum mechanical treatment is not required and a much simplified classical picture is sufficient to efficiently and accurately describe many material properties. Specifically, when considering static structural and mechanical properties of various materials (Chen et al. 2013; Butz et al. 2014; van Wijk et al. 2015) as well as their dynamic tribological (Guo et al. 2007; Guerra et al. 2010; Reguzzoni et al. 2012a; Vanossi et al. 2013; van Wijk et al. 2013; Xu et al. 2013; Ze 2014; Kang and Lee 2014) and heat transport characteristics (Jiang 2014a), Newtonian dynamics with carefully designed force-fields (FF) can provide valuable insights (Frenkel and Smit 2002; Allen and Tildesley 2009; Rapaport 2009). Obviously, this results in considerable computational gain enabling the treatment of extremely large atomistic models including tens of thousands of atoms for relatively long timescales. Furthermore, it allows for devising multiscale approaches, where the information gained from fully atomistic calculations serves to design coarse-grained and continuum models. Nevertheless, this comes at the expense of neglecting explicit quantum mechanical effects and even more importantly the need to design system specific interatomic potentials with limited transferability.

With this respect, the formulation of dedicated force-fields for 2D materials and their layered constructs has to account for their inherent structural anisotropy. The individual layers can be viewed as a network of covalently bonded atoms organized in a periodic hexagonal lattice structure. Upon stacking, each layer interacts with its neighboring counterparts via long-range dispersion and electrostatic interactions. Hence, a strategy involving a separate treatment of intralayer and interlayer interactions is often invoked.

#### 2 Intralayer Interactions

The intralayer force-field term usually involves six main ingredients including (see Fig. 1): (http://cbio.bmt.tue.nl/pumma/index.php/Theory/Potentials; Rappe et al. 1992) (i) bonded two-body interactions describing the bond stretching and compression energy; (ii) bonded three-body interactions accounting for angle bending penalties; bonded four-body interactions depicting (iii) improper and (iv) dihedral



**Fig. 1** Illustration of several intralayer force-field term contributions: (**a**) Bond stretching and compression; (**b**) angle bending; (**c**) improper angle deformation; (**d**) torsional angle deformation; (**e**) van der Waals interactions; (**f**) electrostatic interactions

torsional deformations; (v) nonbonded van der Waals (vdW) interactions; and (vi) nonbonded electrostatic interactions.

The first two components are often represented by simple harmonic springs of the form  $V_{ij}^{(i)}(r_{ij}) = k_{ij} \left(r_{ij} - r_{ij}^0\right)^2$  and  $V_{ijk}^{(ii)}(\theta_{ijk}) = k_{ijk} \left[\cos(\theta_{ijk}) - \cos(\theta_{ijk}^0)\right]^2$ . Here,  $r_{ij}$  is the distance between atomic center *i* and *j*,  $\theta_{ijk}$  is the angle defined by atomic centers *i*, *j* and *k* (see Fig. 1a, b),  $r_{ij}^0$  and  $\theta_{ijk}^0$  are the equilibrium *ij* pair interatomic distance and *ijk* triad angle, respectively, and  $k_{ij}$  and  $k_{ijk}$  are the corresponding force constants. Improper torsion is often also described by a harmonic potential of the form  $V_{ijkl}^{(\text{iii})}(\delta_{ijkl}) = k_{ijkl}^{(\text{iii})}(\delta_{ijkl} - \delta_{ijkl}^0)^2$ ,  $\delta_{ijkl}$  being the improper angle (see Fig. 1c) and  $k_{ijkl}^{(iii)}$  and  $\delta_{ijkl}^0$  being the corresponding force constant and equilibrium improper angle, respectively. Dihedral angle torsion can be depicted by a periodic potential of the form  $V_{ijkl}^{(iv)}(\phi_{ijkl}) = k_{ijkl}^{(iv)} \left[1 + \cos\left(\eta_{ijkl}\phi_{ijkl} - \phi_{ijkl}^0\right)\right]$ , where  $\phi_{ijkl}$  is the dihedral angle (see Fig. 1d),  $k_{ijkl}^{(iv)}$  is the corresponding force constant,  $\phi_{ijkl}^0$  sets the equilibrium dihedral angle, and  $\eta_{ijkl}$  is the multiplicity factor signifying the number of minima that this potential term possesses. The nonbonded vdW term is often described by the two-body Lennard-Jones (LJ) potential of the form  $V_{ij}^{(v)}(r_{ij}) = 4\epsilon_{ij} \left[ (\sigma_{ij}/r_{ij})^{12} - (\sigma_{ij}/r_{ij})^6 \right]$  where  $\epsilon_{ij}$  and  $\sqrt[6]{2}\sigma_{ij}$  are the binding energy and equilibrium distance of the *ij* atomic pair, respectively (see Fig. 1e). Note that this expression accounts not only for the long-range attractive vdW interactions but also for short-range repulsions. Finally, interatomic monopolar electrostatic interactions are calculated using Coulombs law  $V_{ii}^{(\text{vi})}(r_{ij}) = q_i q_j / (4\pi \epsilon_0 r_{ij})$ , where  $\epsilon_0$  is the vacuum permittivity and  $q_k$  is the effective partial charge of atom k (see Fig. 1f).

It should be noted that while the expressions described above are commonly used to describe the intralayer interactions in layered materials they are, by no means, the only ones available. For example, if a reactive force-field is required, the harmonic bonded two-body terms can be replaced by an anharmonic potential that allows for bond breaking and formation. Furthermore, the force-field parameters can be varied according to the local chemical environment, thus providing flexibility to describe different bond-orders and accounting for various chemical binding schemes.

The various force-field parameters have to be determined separately for each material. The fitting procedure can be performed against experimentally measured material properties, such as the Young modulus, the shear modulus, lattice constants, phonon spectra, and heats of formation. Alternatively, they can be calibrated to fit results of higher accuracy methods such as state-of-the-art DFT calculations. Dedicated intralayer force-field parameterizations are available for a variety of layered materials including graphene and its derivatives (Al-Jishi and Dresselhaus 1982; Tersoff 1988; Brenner 1988, 1990; Stuart et al. 2000; Brenner et al. 2002; Los and Fasolino 2003; Ghiringhelli et al. 2005a, 2008; Los et al. 2005; Perebeinos and Tersoff 2009; Lindsay and Broido 2010; Jiang 2015; O'Connor et al. 2015), h-BN (Sevik et al. 2011), and 2H-MoS<sub>2</sub> (Jiang 2015; Wakabayashi et al. 1975; Jiménez Sandoval et al. 1991; Brunier et al. 1992; Morita et al. 2008; Liang et al. 2009; Varshney et al. 2010; Jiang et al. 2013; Nicolini and Polcar 2016), many of which are implemented in open source or commercial software packages. These have been successfully used to describe a variety of material properties including the structural and mechanical behavior (Tersoff 1992; Lu 1997; Hertel et al. 1998; Fasolino et al. 2007; Bets and Yakobson 2009; Costamagna et al. 2012; Singh et al. 2013, 2015; Bucholz and Sinnott 2013; Jin-Wu et al. 2013; Jiang 2014b; Jiang and Park 2014), thermal transport characteristics (Varshney et al. 2010; Che et al. 2000; Mohamed and Deepak 2001; González Noya et al. 2004; Yao et al. 2005; Lindsay and Broido 2011), crack propagation (Xiaonan et al. 2015), and melting dynamics of 2D monolayers (Singh et al. 2015).

#### 3 Interlayer Interactions

The interlayer force-field term usually involves three main contributions: longrange attractive vdW interactions, short-range Pauli repulsions, and electrostatic interactions. The latter, which is required when atoms in different layers have a sizable partial charge, can often be described by a simple Coulombic term similar to the  $V_{ij}^{(vi)}$  intralayer expression given above (see Fig. 1f). To describe the attractive vdW and repulsive Pauli interactions, the LJ (or Morse (Los and Fasolino 2003; Los et al. 2005; Ghiringhelli et al. 2005b; Karssemeijer and Fasolino 2011)) potential is often chosen similar to the intralayer  $V_{ij}^{(v)}$  expression (see Fig. 1e) (Nicolini and Polcar 2016; Lebedeva et al. 2011a; Shibuta and Elliott 2011; Ye et al. 2012, 2015; Jayasena et al. 2013; Liu et al. 2015; Kushima et al. 2015). With appropriate parameterization, this expression can provide a good description of the interlayer



**Fig. 2** Anisotropic Pauli repulsion term: (a) illustration of the anisotropic  $p_z$  orbital overlap variations during interlayer sliding; (b) definition of the lateral interatomic distance; (c) definition of the local surface normal. (Reprinted with permission from Oz et al. (2016). Copyright (2016) American Chemical Society)

binding energy curve (Szabados et al. 2006; Jiang 2015; Brunier et al. 1992; Varshney et al. 2010; Jiang et al. 2013; Lu 1997; Bucholz and Sinnott 2013; Jiang and Park 2014; Singh et al. 2015; Girifalco and Lad 1956; Green et al. 1974; Weiss and Phillips 1976; Kuzuba et al. 1985; Lu et al. 1992; Tersoff and Ruoff 1994; Kwon and Tománek 1998; Buldum and Lu 1999; Girifalco et al. 2000; Girifalco and Hodak 2002; Qian et al. 2003; Michel and Verberck 2011; Tolga et al. 2016). However, using the same parameters to study relative interlayer sliding fails to reproduce the corrugated sliding energy landscape and results in too shallow energy barriers (Carlson and Dumitrică 2007; Stuart et al. 2000; Palser 1999; Kolmogorov and Crespi 2000, 2005; Shtogun and Woods 2010; Lebedeva et al. 2011b; Reguzzoni et al. 2012b; Neek-Amal and Peeters 2014; Strutyński et al. 2014; Korhonen and Koskinen 2015; Jiang and Park 2015). Hence, the ability of LJ type potentials to reliably describe many structural, mechanical, and tribological properties of layered materials may be considerably hindered.

The origin of this deficiency in the LJ potential was identified by Kolmogorov and Crespi (KC) to be the use of isotropic expressions that depend only on interatomic distances to describe an anisotropic material property (Kolmogorov and Crespi 2000, 2005; Lebedeva et al. 2011b). Focusing on graphene, KC realized that when two layers slide upon each other, electron clouds associated with the  $p_z$  orbitals around carbon atoms residing on adjacent layers overlap as the atoms pass each other (see Fig. 2a). This, in turn, induces Pauli repulsion variations resulting in a corrugated sliding energy landscape. Since the electron density overlap depends on the lateral distance between the crossing atoms, an interlayer pair-potential of the following form was suggested (Kolmogorov and Crespi 2005):

$$V^{\text{KC}}(r_{in},\rho_{in}) = e^{-\lambda(r_{in}-z_0)} \left[C + f(\rho_{in}) + f(\rho_{ni})\right] - A(r_{in}/z_0)^{-6}.$$
 (1)

This expression includes a LJ type long-range attractive term scaled by A = 10.238; an isotropic Morse-like short-range exponential repulsive term with the equilibrium interlayer distance  $z_0 = 3.34$  Å, exponent  $\lambda = 3.629$  Å<sup>-1</sup>, and scaling factor C = 3.030; and an anisotropic short-range Gaussian repulsive term

of the form  $f(\rho) = e^{-(\rho/\delta)^2} \sum_n c_{2n} (\rho/\delta)^{2n}$  that depends on the lateral distance,  $\rho$ , between each pair of atoms on adjacent layers scaled by  $\delta = 0.578$  Å. The nonzero coefficients of the polynomial multiplying the Gaussian are given by  $c_0 = 15.71$ ,  $c_2 = 12.29$ , and  $c_4 = 4.933$ . The lateral distance,  $\rho_{in}$ , is defined as the shortest distance between atom *n* on one layer and the surface normal at atom *i* residing on an adjacent layer (see Fig. 2b). For a hexagonal lattice, the simplest definition of the local surface normal at a given atomic position is the unit vector perpendicular to the triangle formed by its three nearest neighbors (see Fig. 2c). Since for curved systems generally  $\rho_{in} \neq \rho_{ni}$  the pair potential is symmetrized to fulfill Newton's third law. With the inclusion of the anisotropic repulsive term, the KC potential was shown to simultaneously provide a good description of both interlayer binding and sliding energy landscapes (see Fig. 3) (Kolmogorov and Crespi 2000, 2005; Reguzzoni et al. 2012b).

Despite this notable success and the ever growing interest in 2D materials, the KC approach (and related methods (Lebedeva et al. 2011b, 2012; Popov et al. 2011)) has not been extended to describe other layered materials for more than a decade since its inception. Recently, however, the transferability of the method was demonstrated where a KC type potential was applied to the graphene/*h*-BN hetero-structure (van Wijk et al. 2014; Woods et al. 2016). In this study, the FF parameters have been set to reproduce experimentally observed moiré superstructures arising from the 1.8% intralayer lattice constant mismatch between graphene and *h*-BN. This indicated the ability of the KC force-field to describe the structural properties of homogeneous and heterogeneous junctions of 2D materials.

To harness the full predictive capabilities of KC-type FFs to describe the interlayer interactions in a variety homogeneous and heterogeneous layered materials structures, a slightly modified functional form, termed interlayer potential (ILP), was recently suggested. The ILP accounts for monopolar electrostatic interactions and allows for simple parameterization against state-of-the-art first-principles calculations based on pair-wise (Tkatchenko and Scheffler 2009; Marom et al. 2011) and many-body dispersion corrected (Tkatchenko et al. 2012; Ambrosetti et al. 2014) screened-hybrid (Heyd et al. 2003; Heyd and Scuseria 2004a, b) density functional theory calculations (Leven et al. 2014, 2016a; Maaravi et al. 2017; https://pubs.acs. org/doi/10.1021/acs.nanolett.8b02848).

The ILP consists of a modified KC **short-range anisotropic repulsive term** of the form:

$$V_{Rep}(r_{in},\rho_{in}) = \operatorname{Tap}(r_{in}) \times e^{\alpha_{in}\left(1 - \frac{r_{in}}{\beta_{in}}\right)} \left[ \varepsilon_{in} + C_{in} \left( e^{-\left(\frac{\rho_{in}}{\gamma_{in}}\right)^2} + e^{-\left(\frac{\rho_{ni}}{\gamma_{in}}\right)^2} \right) \right], \quad (2)$$

where  $\varepsilon_{in}$  and  $C_{in}$  are constants setting the energy scales associated with the isotropic and anisotropic repulsion, respectively,  $\beta_{in}$  and  $\gamma_{in}$  set the corresponding interaction ranges, and  $\alpha_{in}$  is a parameter defined to set the steepness of the isotropic repulsion term. Note that for computational efficiency, the 4th degree polynomial multiplying the anisotropic Gaussian



**Fig. 3** Interlayer (**a**) binding and (**b**) sliding energy curves of bilayer graphene calculated using the LJ (full blue circles) and KC (full black circles) interlayer potentials compared to a reference dispersion corrected DFT calculation (full green squares). (Reprinted with permission from Reguzzoni et al. (2012b). Copyright (2012) by the American Physical Society)

repulsion term appearing in the original KC expression (see Eq. (1) above) is replaced by a constant factor. Furthermore, a taper function of the form  $\text{Tap}(r_{in}) = 20(r_{in}/R_{cut})^7 - 70(r_{in}/R_{cut})^6 + 84(r_{in}/R_{cut})^5 - 35(r_{in}/R_{cut})^4 + 1$ , which provides a continuous (up to third derivative) cutoff for interatomic separations exceeding  $R_{cut}$ , is used to damp the long-range contribution of the repulsive term. These modifications simplify the FF expressions and reduce the computational cost while providing a satisfactory description of the interlayer interactions (Leven et al. 2014, 2016a; Maaravi et al. 2017).

To treat the **long-range attractive interactions**, the Tkatchenko and Scheffler (TS) dispersion correction scheme to DFT is considered (Tkatchenko and Scheffler 2009). Within this approach, widely used semi-local or hybrid exchange-correlation

density functional approximations that are known to provide an inadequate description of long-range van der Waals (vdW) interactions are augmented by a term that decays asymptotically with the interatomic distance as  $r^{-6}$ . This term is damped at short distances to avoid double-counting of short-range correlation effects. In the ILP, the following pair-wise long-range attractive term is adopted:

$$V_{Att}(r_{in}) = \text{Tap}(r_{in}) \left\{ -\left[1 + e^{-d\left[\left(r_{in}/\left(S_R \cdot r_{in}^{eff}\right)\right) - 1\right]}\right]^{-1} \cdot \frac{C_{6,in}}{r_{in}^6} \right\}.$$
 (3)

Here,  $r_{in}^{eff}$  is the sum of effective equilibrium vdW atomic radii of atom *i* and atom *n* residing on different layers,  $C_{6, in}$  is the pair-wise dispersion coefficient of the two atoms in the solid-state environment, and *d* and  $S_R$  are unit-less parameters defining the steepness and onset of the short-range Fermi-Dirac type damping function. Similar to the repulsive term, long-range taper damping is implemented to reduce computational burden. This specific form is chosen as it allows the extraction of the various parameters directly from first-principles calculations avoiding the need for experimental data that is macroscopic by nature, very difficult to obtain, and mostly unavailable for many 2D layered materials and hetero-structures thereof.

In cases where atoms residing on the interacting layers bear sizable effective charges, electrostatic contributions should be taken into account. To this end, the formalism implemented in the ReaxFF scheme can be utilized (van Duin et al. 2001). Within this approach, a shielded Coulomb potential term of the form:

$$V_{Coul}(r_{in}) = \text{Tap}(r_{in}) \times \left[ k q_i q_n / \sqrt[3]{r_{in}^3 + (1/\lambda_{in})^3} \right]$$
(4)

is used. Here, *k* is Coulomb's constant and  $\lambda_{in}$  is a shielding parameter introduced to eliminate the short-range singularity of the classical monopolar electrostatic interaction expression. This shielding takes effect in regions where Pauli repulsions between overlapping electron clouds dominate the interlayer potential and hence has minor influence on the results. When considering periodic systems, the long-range taper cutoff can be replaced by Ewald summation techniques (Ewald 1921; Toukmaji and Board 1996) in order to avoid conditionally convergent sums (Hod 2012a).

In many cases, the effective ionic charges,  $q_i$  and  $q_n$ , can be treated as constant values throughout the simulation. Nevertheless, in order to provide a general description, they can be dynamically evaluated using the electronegativity equalization method (EEM) (van Duin et al. 2001; Mortier et al. 1986; Njo et al. 1998; Bultinck et al. 2002). This method relies on a principle formulated by Sanderson stating that when a molecule or a solid is formed, the electronegativities of the constituent atoms equalize to give a global electronegativity of the entire system (Sanderson 1951, 1983). Hence, the electronegativity of a given atom within the molecular or solid environment ( $\chi_i$ ) is written in terms of the corresponding

isolated atom electronegativity (Parr et al. 1978)  $(\chi_i^0)$  and hardness (Parr and Pearson 1983; Sanderson 1976)  $(\eta_i^0)$  as  $\chi_i = (\chi_i^0 + \Delta \chi_i) + 2(\eta_i^0 + \Delta \eta_i)q_i + \sum_{j \neq i} kq_j/\sqrt[3]{r_{ij}^3 + (1/\lambda_{ij})^3}$ . Here,  $\Delta \chi_i$  and  $\Delta \eta_i$  represent the electronegativity and hardness variations due to the embedding molecular or solid environment and the last term represents the electrostatic potential induced by all other atoms in the system (Weismiller et al. 2010). The effective atomic charges can then be obtained by enforcing the guiding principle that within the molecular or solid environment all atomic electronegativities should equal the equilibrated molecular electronegativity  $\chi_{i=1...N} = \chi_{eq}$ . To this end, the following matrix equation is solved:

$$\begin{pmatrix} 2\left(\eta_{1}^{0}+\Delta\eta_{1}\right) & k/\sqrt[3]{r_{12}^{3}+(1/\lambda_{12})^{3}} & \cdots & k/\sqrt[3]{r_{12}^{3}+(1/\lambda_{12})^{3}} & -1\\ k/\sqrt[3]{r_{21}^{3}+(1/\lambda_{21})^{3}} & 2\left(\eta_{2}^{0}+\Delta\eta_{2}\right) & \cdots & k/\sqrt[3]{r_{2N}^{3}+(1/\lambda_{2N})^{3}} & -1\\ \vdots & \vdots & \ddots & \vdots & \vdots\\ k/\sqrt[3]{r_{N1}^{3}+(1/\lambda_{N1})^{3}} & k/\sqrt[3]{r_{N2}^{3}+(1/\lambda_{N2})^{3}} & \cdots & 2\left(\eta_{N}^{0}+\Delta\eta_{N}\right) & -1\\ 1 & 1 & \cdots & 1 & 0 \end{pmatrix} \begin{pmatrix} q_{1}\\ q_{2}\\ \vdots\\ q_{N}\\ \chi_{eq} \end{pmatrix} = -\begin{pmatrix} \chi_{1}^{0}+\Delta\chi_{1}\\ \chi_{2}^{0}+\Delta\chi_{2}\\ \vdots\\ q_{N}\\ \chi_{eq} \end{pmatrix} = -\begin{pmatrix} \chi_{1}^{0}+\Delta\chi_{1}\\ \chi_{2}^{0}+\Delta\chi_{2}\\ \vdots\\ \chi_{N}^{0}+\Delta\chi_{N}\\ -Q \end{pmatrix}$$
(5)

where the isolated atomic electronegativities and hardnesses,  $\chi_i^0$  and  $\eta_i^0$ , their corresponding molecular or solid environment variations  $\Delta \chi_i$  and  $\Delta \eta_i$ , and the total charge, Q, are provided as input. The latter is dictated by the modeled system, whereas the former are used as fitting parameters.

While originally parameterized for homogeneous h-BN and graphene junctions (Leven et al. 2014; Maaravi et al. 2017), as well as for heterogeneous junctions thereof (Leven et al. 2016a), with appropriate parameterization the ILP should be transferable to a variety of layered materials such as different graphene allotropes including pentaheptite, haeckelite, dimerite, and octite (David et al. 2010); graphane; graphyne; germanene; silicene; stanene; phosphorene; and members of the transition metal dichalcogenides family such as molybdenum and tungsten disulfide and diselenide. As demonstrated in the next section, such an extension will make the ILP a versatile and powerful simulation tool for the study of the structural, mechanical, dynamic, and heat transport properties of homogeneous and heterogeneous layered material structures.

## 4 Applications

An illustrative demonstration of the performance of classical ILPs for studying interlayer interactions in layered materials is the case of the graphene/*h*-BN heterojunction. This heterojunction has gained great attention from the scientific community in recent years (Geim and Grigorieva 2013; Wang et al. 2014; Das et al. 2015; Leven et al. 2016a) due to its rich physical properties that include a controllable electronic band-gap (Chen et al. 2014; Fan et al. 2011; Jung et al. 2015; Yankowitz et al. 2012), ultrahigh electron mobility (Dean et al. 2010; Levendorf et

al. 2012; Tang et al. 2013), the demonstration of Hofstadter's butterfly phenomenon (Ponomarenko et al. 2013; Dean et al. 2013), and the manifestation of controllable hyperbolic meta-material characteristics (Dai et al. 2015).

Owing to the intrinsic lattice-constant mismatch between graphene and *h*-BN, the former tends to deform when placed on a multilayer *h*-BN substrate in order to adapt to the underlying crystal lattice (van Wijk et al. 2014; Yankowitz et al. 2012; Dean et al. 2013; Yang et al. 2013; Woods et al. 2014). The resulting moiré superstructures alter graphene's electronic and optical properties thus opening new opportunities for technological applications (Jung et al. 2015; Kumar et al. 2015). Naturally, modeling such superstructures from first-principles is a prohibitively demanding task. This, in turn, calls for the utilization of classical ILPs.

Figure 4 presents the fully relaxed structure of a free-standing graphene/*h*-BN bilayer supercell calculated using the graphene/*h*-BN ILP (Leven et al. 2016a). A clear moiré superstructure is obtained (see panel (d)), where regions of optimal interlayer registry (blue regions in panel (a)) and distance (blue regions in panel (b)) and intralayer bond lengths (red regions in panel (c)) are separated by sharp domain walls characterized by increased interlayer distance and compressed intralayer bond lengths in accordance with experimental findings (Yankowitz et al. 2012; Woods et al. 2014). Furthermore, due to the lack of rigid support, the calculation predicts that the entire structure should become highly corrugated. This latter observation was recently verified experimentally (Argentero et al. 2017).

Such moiré superstructures are expected to have considerable effect on the tribological properties of the heterojunctions. To investigate this, the graphene/*h*-BN ILP (Leven et al. 2016a) has been recently used to simulate the frictional



**Fig. 4** Fully relaxed graphene/*h*-BN free-standing bilayer. (**a**) Local registry index map, where blue and red colors represent optimal and worst interlayer stacking, respectively. The calculation is performed using the registry index method that defines a purely geometric quantitative measure of interlattice commensurability (Leven et al. 2013, 2016a; Koren et al. 2016; Marom et al. 2010; Hod 2010, 2012b, 2013; Blumberg et al. 2012; Garel et al. 2012; Oz et al. 2016; Leven et al. 2016b); (**b**) interlayer distance map; (**c**) graphene intralayer bond-length map; and (**d**) overall structure of a fully relaxed, free-standing, graphene/*h*-BN bilayer. (Reprinted with permission from Leven et al. (2016a). Copyright (2016) American Chemical Society)

behavior of the heterojunction (Mandelli et al. 2017). It was found that for the aligned interface (where the lattice vectors of the two layers are parallel), with contact size below the characteristic lateral dimension of the elevated superstructure ridges, the junction behaves like its homogeneous counterparts with friction forces that grow linearly with the contact area. Superlubricity sets in due to the progressive appearance of moiré patterns resulting in a transition to collective stick-slip motion of the ridges that eventually turns into smooth soliton-like sliding with increasing contact size (see Fig. 5). For angularly misaligned contacts (where the lattice vectors of the two layers are rotated with respect to each other), incommensurability effects, also appearing in homogeneous junctions, are enhanced and the friction coefficients further drop by orders of magnitude and remain extremely low, even under external loads. These simulations indicated the potential of achieving robust superlubricity, independent of the relative interfacial orientation, and sustainable under external loads, in practical applications utilizing two-dimensional layered materials heterojunctions.

A similar phenomenon is found to occur in homogeneous multiwalled nanotubes, where the lattice mismatch results from the curvature difference between adjacent nanotube walls. Due to the frustrated geometry of the tube's circumference, this may result in a pronounced faceted superstructure, where the circular cross-section is deformed into a more stable polygonal one (Garel et al. 2012, 2014; Liu and Cowley 1994; Gogotsi et al. 2000; Zhang et al. 2003, 2005; Celik-Aktas et al. 2005a; Golberg et al. 2007a, b; Nigues et al. 2014). For narrow nanotubes, the excessive stain involved in the formation of sharp vertices is not compensated by the energy gain of forming the planar facets; hence, faceting is suppressed. However, above a certain nanotube diameter, typically of 12 nm (Garel et al. 2012), the standard circular cross section can be strongly distorted and faceting may appear (see Fig. 6).

Here, as well, modeling such systems from first-principles is impractical and classical ILPs serve as a viable alternative for studying their structural and mechanical properties. Hence, to decipher the mechanism that underlies facet formation and dictates their character, elaborate geometry relaxations of a wide set of double-walled carbon and boron nitride nanotubes were performed (Leven et al. 2016b). It was found that regardless of the nanotube identity (namely, diameter, and chemical composition), chiral angle matching between adjacent layers is a necessary condition for the formation of faceting. Considering first achiral nanotubes, where



**Fig. 5** Snapshots of the soliton-like smooth sliding motion of the moiré superstructure ridges occurring upon shearing of a graphene/*h*-BN junction. (Reprinted with permission from Mandelli et al. (2017). Copyright (2017) American Chemical Society)



**Fig. 6** Schematic representation of achiral double-walled carbon (top two rows) and boronnitride (bottom two rows) nanotubes, showing their structure and local registry patterns prior to and after geometry relaxation. Each frame shows seven double-walled nanotubes with diameters in the range of 5–20 nm. Five groups of double-walled nanotubes are presented (from left to right): ZZ@ZZ (n,0)@(n + 8,0); AC@AC (n,n)@(n + 4,n + 4), (n,n)@(n + 5,n + 5) and (n,n)@(n + 6,n + 6); and ZZ@AC. For the ZZ@ZZ systems the n = 55, 80, 105, 130, 155, 180, and 243 nanotubes are chosen. For the AC@AC systems the n = 31, 46, 60, 75, 89, 104, and 140 are chosen. For the ZZ@AC systems, the following set is considered: (54,0)@(36,36), (80,0)@(51,51), (104,0)@(65,65), (130,0)@(80,80), (154,0)@(94,94), (179,0)@(108,108), and (241,0)@(144,144). The local registry index color bar (right) ranges from blue to red, representing the optimal and worst stacking modes of graphene and *h*-BN, respectively. Grey, pink, and blue spheres on the right-hand-side represent carbon, boron, and nitrogen atoms, respectively. (Reprinted with permission from Leven et al. (2016b). Copyright (2016) by the American Physical Society)

both nanotube walls are of the same type (either zigzag (ZZ) or armchair (AC)), it was found that above a critical diameter that corresponds well with experimental observations (Garel et al. 2012), evenly spaced extended axial facets form (see Fig. 6). Notably, the number of facets equals the interlayer difference in number of circumferential unit-cells. Interestingly, similar axial facets are formed also for mono-chiral double-walled nanotubes, where both nanotube walls are chiral but share the same chiral angle (see left column in Fig. 7). Elongated helical facets, similar to those commonly observed in experiment, appear in nanotubes that exhibit small interlayer chiral angle mismatch (see middle columns in Fig. 7). These are gradually suppressed with increasing interwall chiral angle difference resulting in outer layer corrugation, which is induced by the moiré superlattice, in agreement with experiments (Schouteden et al. 2013). Since multiwalled boronnitride nanotubes exhibit better interwall chiral angle matching (Celik-Aktas et al. 2005a; Golberg et al. 1999, 2000; Celik-Aktas et al. 2003; Li et al. 2003; Koziol et al.



**Fig. 7** Schematic representation of (120,100)@(126,105) (leftmost column), (60,60)@(66,65) (second column), (70,70)@(77,74) (third column), (68,68)@(75,70) (fourth column), and (71,71)@(80,72) (rightmost column) double-walled boron-nitride nanotubes showing their local interlayer registry patterns before (top row) and after (middle row) geometry relaxation. The color bar on the right refers to the interlayer spacing of the different systems presented in the bottom row. The colors used in the local registry index patterns are the same as in Fig. 6 above. The chiral angle difference between the inner and outer shells is indicated at the top of each column. (Reprinted with permission from Leven et al. (2016b). Copyright (2016) American Chemical Society)

2005; Hashimoto et al. 2005; Xu et al. 2006; Ducati et al. 2006; Hirahara et al. 2006; Gao et al. 2006; Guo and Guo 2007; Guan et al. 2008), these findings rationalize the experimental observation of relative abundance of faceting in the former (Celik-Aktas et al. 2005a, b; Golberg et al. 1999, 2000).

In resemblance to the effect of moiré structures on the interlayer sliding friction of planar interfaces, nanotube circumferential faceting is expected to have a notable impact on the interwall sliding friction. When the relative axial or angular alignment of adjacent nanotube walls is varied, the corresponding intervall lattice registry changes. If the nanotube is faceted, then this modification results in rearrangement of the faceted superstructure (Guerra et al. 2017). In the case of achiral or monochiral double-walled nanotubes, where the facets are axially aligned, a series of unfaceting and refaceting events occurs during the interwall motion accompanied by facet rotation and reconfiguration (see Fig. 8a, b). For bi-chiral systems, where helical facets appear, interwall telescoping results in rotation of the entire faceted superstructure akin to a rotating Archimedean screw (see Fig. 8c). These global structural variations introduce new dissipative channels that enhance intervall friction (Guerra et al. 2017). This, along with the above-mentioned fact that faceting is more abundant in multiwalled boron-nitride nanotubes than in their carbon counterparts, may rationalize recent experimental measurements showing that the former exhibit enhanced interwall friction (Nigues et al. 2014).



**Fig. 8** Facet reconfiguration during interwall pull-out and rotation in (a) armchair (104,104)@(109,109); (b) zigzag (180,0)@(188,0); and (c) bichiral (70,70)@(77,74) double-walled boron-nitride nanotubes.  $\theta$ , *z*, and  $\Psi$  values appearing in panels (a) and (b) indicate the relative angular and axial positions of the outer and inner walls and the corresponding facet rotation angle, respectively. The two configurations appearing in panel (c) have relative interwall angular and axial orientations of  $0.2^{\circ}/2.4$  Å (left) and  $0.2^{\circ}/3.2$  Å (right). These correspond to configurations close to the maximum and minimum of the interwall sliding-rotation potential energy surface, respectively. Red, white, and blue atom false coloring indicate low, average, and high atomic interlayer energy, respectively. (Reprinted with permission from Guerra et al. (2017). Copyright (2017) American Chemical Society)

## 5 Summary

Two-dimensional hexagonal layered materials are of the most promising systems in the field of material science to deliver new technological breakthroughs. The large variety of members in this family and their diverse chemical and physical properties form a vast playground for the design of homogeneous and heterogeneous systems presenting novel structure-function relations. The small dimensions characterizing this field of research call for a synergic interplay between experiment, theory, and computation. With this respect, carefully tailored classical force-field may provide valuable insights on the atomistic nature of different structural, mechanical, dynamical, and tribological phenomena found in these systems. In the present chapter, a review of recent advances in the field of anisotropic force-fields for describing the interlayer interactions in hexagonal layered materials has been provided. The performance of such force-fields was demonstrated via several applications that address the structural and frictional properties of planar heterojunctions of graphene and h-BN as well as faceted double-walled nanotubes. The good agreement obtained with several experimental observations indicates the predictive power of the developed interlayer force-fields and their ability to rationalize experimental results. The extension of such dedicated force-fields to treat other layered materials is an ongoing effort that, when fulfilled, is expected to enable the discovery of novel low-dimensional structures. Furthermore, the utilization of such force-fields within the framework of multiscale modeling as a source of reliable atomistic information for coarse grained and continuum treatments (Leven et al. 2013; Koren et al. 2016; Leven et al. 2016a; Jung et al. 2015; Kumar et al. 2015; Marom et al. 2010; Hod 2010; Hod 2012b; Blumberg et al. 2012; Garel et al. 2012; Hod 2013; Oz et al. 2016; Leven et al. 2016b; Girifalco 1992; Last et al. 1999; Shenoy et al. 2008; Lu et al. 2009; Yang et al. 2011; Chenxi et al. 2014; Ruiz et al. 2015; Ward 2016; Lebedev et al. 2016) may lead to the development of new nano- and microelectromechanical systems with diverse functionalities based on the promising concepts of 2D layered materials.

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